

ProECU Nissan VR30TT



Tuning Manual

V1.3

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1. Introduction

Nissan and Infiniti's latest venture into Sports luxury saloons has resulted in the release of the Nissan VR30DDTT Powered Q50 & Q60 vehicles. These vehicle sport some of the latest features developed and include the twin turbo 3.0L V6. The VR-series 3.0-liter Twin-Turbo V6 engine is available in two configurations:

- a 300 horsepower version with 295 lb-ft of torque
- a high-performance option with 400 horsepower and 350 lb-ft of torque

The VR30 is an award winning engine with seamless power delivery, the latest in Direct Injection technology and a range of special equipment to adequately and easily monitor maintain and increase power and torque delivery. The items to note on the VR30 are

- Water to Air intercoolers (with Aircon Cooling capacity) 1 pump on 300hp, two pumps on 400hp
- Turbo Speed sensors (on 400hp version)
- Twin turbo with Electronic WG actuators on integrated manifold
- Aluminium block with arc sprayed mirror coating to cylinder bores
- Aluminium cylinder heads with integrated exhaust manifold
- Electronically controlled variable displacement oil pump
- Dual Variable Valve Timing VTC (electronic inlet cam, Hydraulic exhaust cam)
- Direct Injection

Summary of Software

The Software to cover the VR30DDTT engines has been introduced to allow reprogramming of the factory ECU to tune the necessary components of the calibration to allow for modifications and increases in power. This is not a standalone replacement ECU so will not have the associated issues or disadvantages of setting up a purpose-built ECU and control system from scratch.

The software allows easy control of

- Boost Targets and Wastegate control
- Target AFR
- Ignition Timing
- Fuel Delivery including fuel pump calibration (using the same style pump as OEM)
- Airflow Measurement and fuel compensation

It also allows the addition of extra features to improve the speed and quality of the tune, these are features like

- Safe-guards for temperatures and airflow that the factory calibration does not include.
- Valet Modes
- EcuTek ECU Connect Compatibility and adjustment
- Map Switching for fuel and Ignition timing

As the product progresses and development occurs, new features and improved definitions will be added.

2. Block Programming

Method of operation

Block Programming (BP) will be enabled after a RaceROM patch is installed on an ECM. This means the first time you program with a BP/RaceROM equipped ROM the ECU needs to use the slow OEM programming sequence and therefore programming time will not change.

On subsequent programming operations, BP will be used. The minimum programming time is approximately 20 seconds and BP will always reprogram the start and end block. More changes will require more blocks to be reprogrammed taking additional time.

DTC clearing and power-off sequences still need to be followed after programming.

Failed Flash Recovery

Block Programming has been tested to ensure that it will not “brick” the ECM, if there is a programming failure, however the correct sequence must be used to recover from a failed programming attempt.

- Close the ProECU programming window
- Disconnect the battery for at least 15 seconds to stop the programming code continuing to run in RAM.
- Manually select the correct ECM programming window for the car. This is a critical step as ProECU will not be able to auto detect a part programmed ECM
- Select correct ROM
- Program

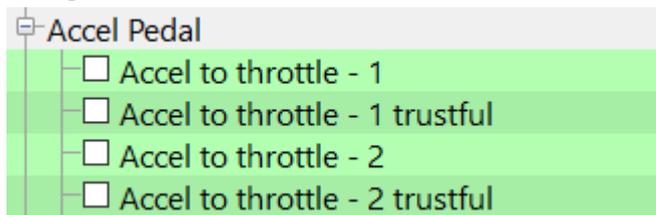
3. Map Descriptions

Accel Pedal

Introduction

Although the VR30 has very complex learning and control strategies (and in some vehicles force feedback pedal control) the accelerator to throttle response is only basically defined, it does however give adequate recalibration of the OEM pedal characteristics.

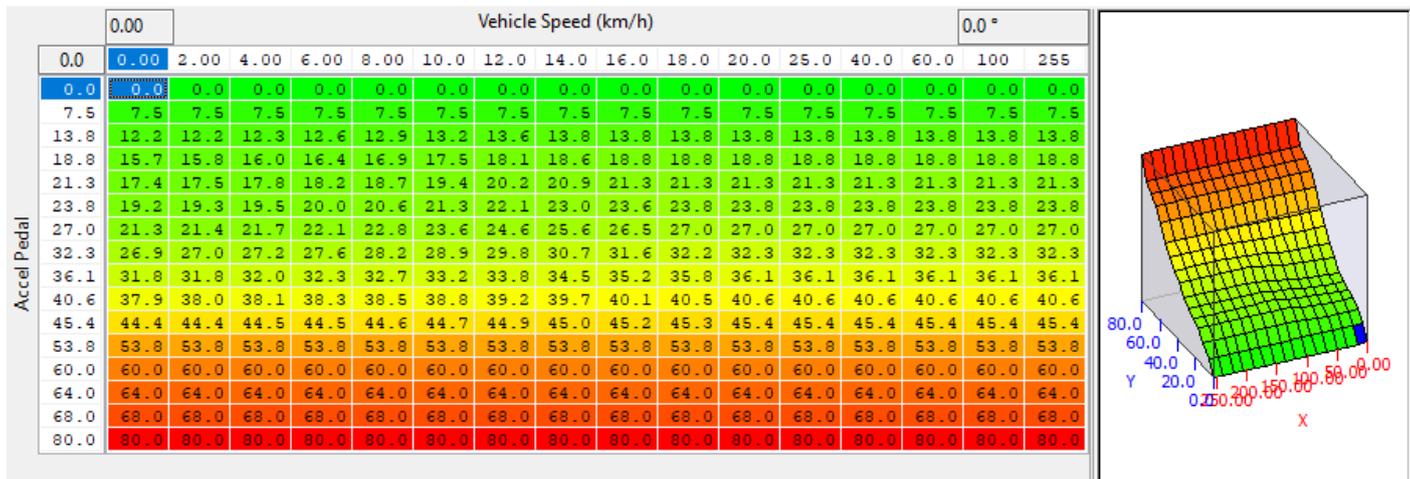
Map List



Live Data Parameters

- Accelerator Sensor #1 – Default accelerator logging parameter for accelerator pedal voltage.
- Accelerator Sensor #2 – Secondary accelerator pedal sensor logging parameter for pedal voltage.
- QH0 – Percentage of throttle airflow requested (not strictly related to accel pedal)

Accel to Throttle - 1 & 2 with trustful

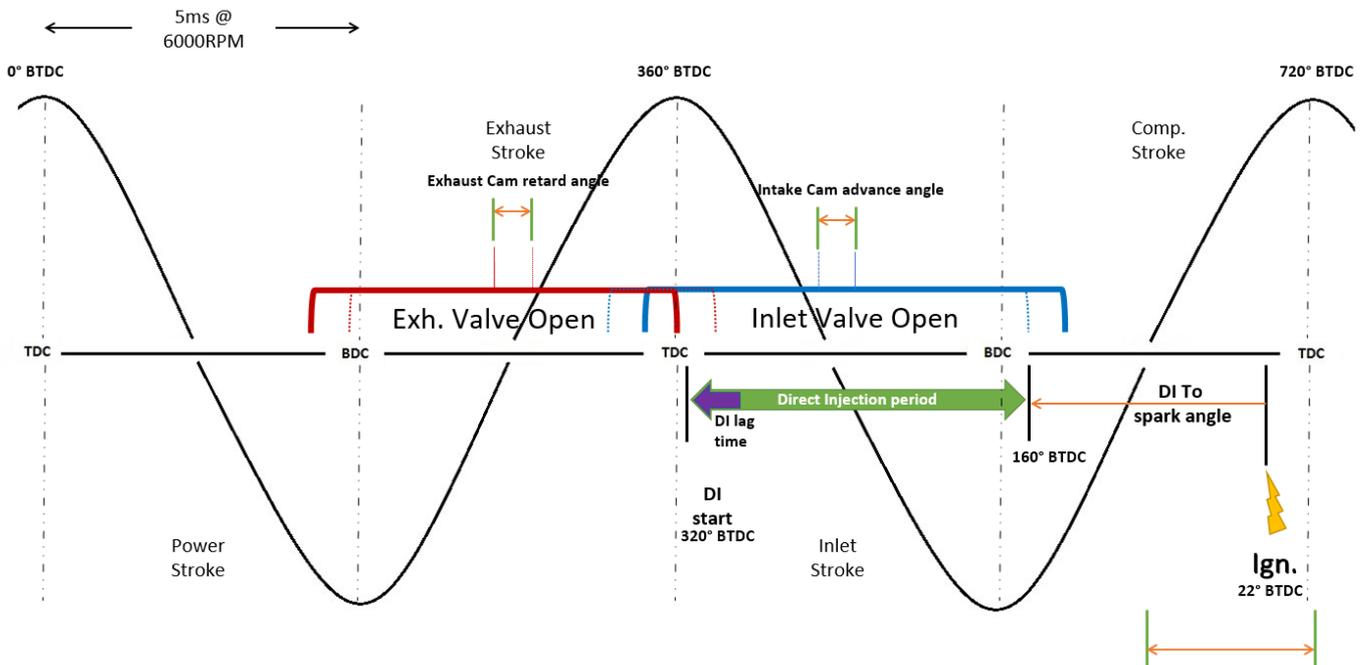


These maps can be changed to give a more linear accel pedal response per vehicle speed generally at lower speeds it's a 1:1 ratio but at higher speed it is a little less responsive at low accel pedal positions. There are trustful maps used and the trustful equivalent must match the original otherwise DTC's (P0605) will occur.

Cam Timing

Introduction

The VR30 has variable cam timing on both the inlet and exhaust cams allow for very precise valve opening and closing events and modulation for EGR etc. The Intake cam advance is driven electronically, and the exhaust cam timing is altered hydraulically by engine oil pressure. Cam timing can be adjusted in the calibration to get more power through the midrange and top end.



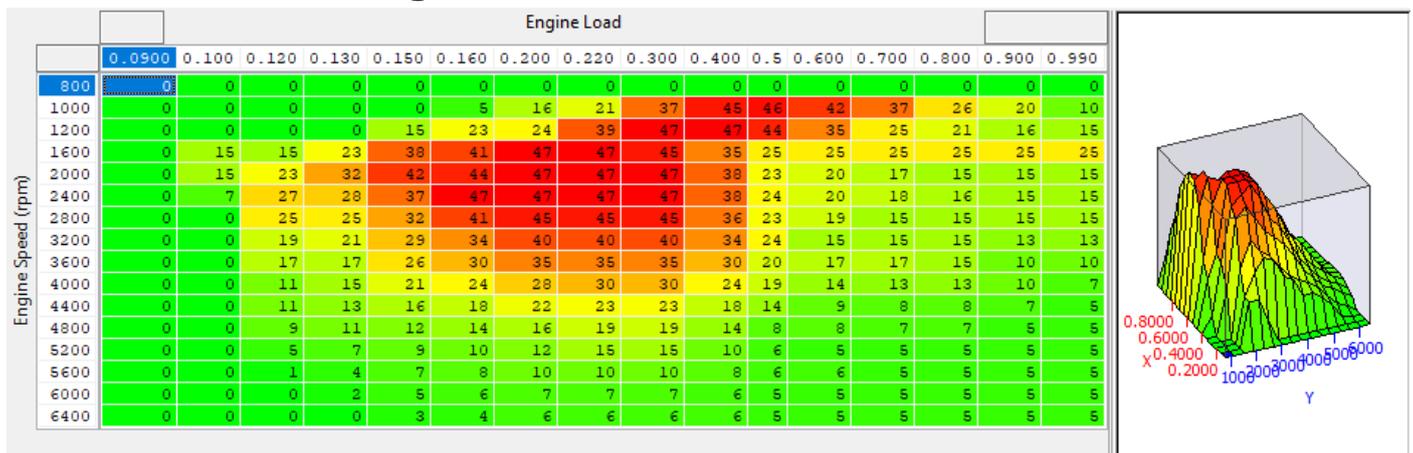
Map List

Cam Timing			
Exhaust			
<input type="checkbox"/>	VVT Exhaust #01	Beginner	OEM
<input type="checkbox"/>	VVT Exhaust #02	Beginner	OEM
Intake			
<input type="checkbox"/>	VVT Intake #01	Beginner	OEM
<input type="checkbox"/>	VVT Intake #02	Beginner	OEM
<input type="checkbox"/>	VVT Intake #03	Beginner	OEM
<input type="checkbox"/>	VVT Intake #04	Beginner	OEM
<input type="checkbox"/>	VVT Intake #05	Beginner	OEM
<input type="checkbox"/>	VVT Intake #06	Beginner	OEM
<input type="checkbox"/>	VVT Intake #07	Beginner	OEM
<input type="checkbox"/>	VVT Intake #08	Beginner	OEM
<input type="checkbox"/>	VVT Intake #09 - used	Beginner	OEM
<input type="checkbox"/>	VVT Intake #10	Beginner	OEM
<input type="checkbox"/>	VVT Intake #11	Beginner	OEM
<input type="checkbox"/>	VVT Intake #12	Beginner	OEM

Live Data Parameters

- VTC Exhaust Duty B1 (%) – Bank 1 Exhaust VVT Oil control valve duty in %.
- VTC Exhaust Duty B2 (%) – Bank 2 Exhaust VVT Oil control valve duty in %.
- VVT Exhaust Angle B1 (°CA) – Exhaust cam angle for bank 1 in crank degrees
- VVT Exhaust Angle B2 (°CA) – Exhaust cam angle for bank 2 in crank degrees
- VVT Intake Angle B1 (°CA) – Bank 1 Intake Cam angle in crank degrees
- VVT Intake Angle B2 (°CA) – Bank 2 Intake Cam angle in crank degrees

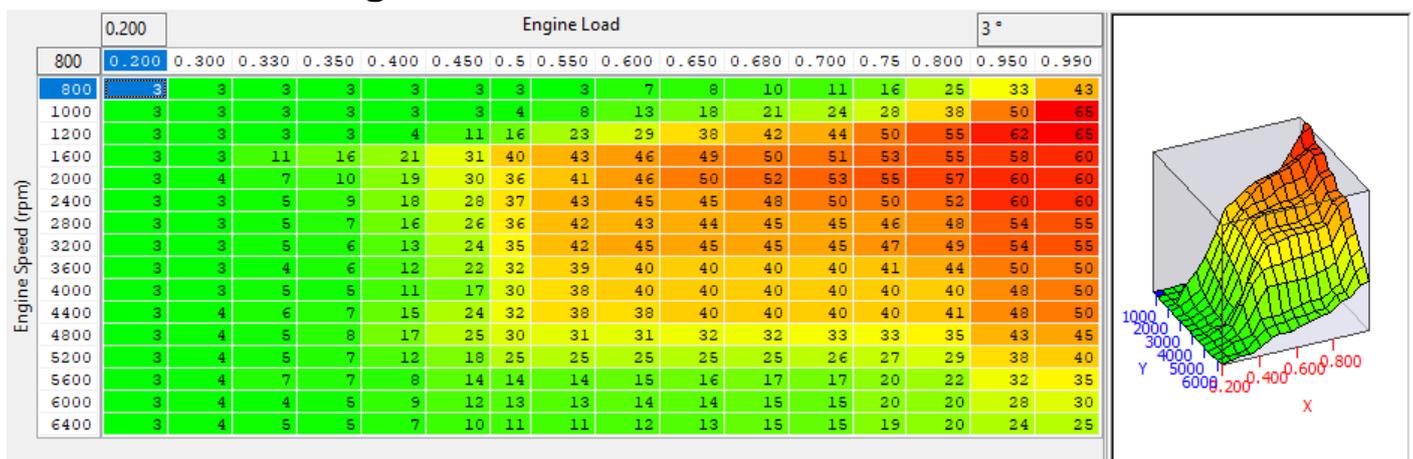
Exhaust Cam Timing



There are a series of maps that are used in different conditions, at the time of writing we are unsure of which conditions use which maps as standard there is little difference to the maps so if changes are made on one it may help to change the others.

These maps represent the target exhaust cam retard angle in crank degrees, we believe from the centre point of the cam.

Intake Cam Timing



There are a series of maps 0-12 that are used in different conditions, at the time of writing we believe that map 09 is used primarily but are unsure of which conditions use which maps. As standard there is little difference to the maps so if changes are made on one it may help to change the others.

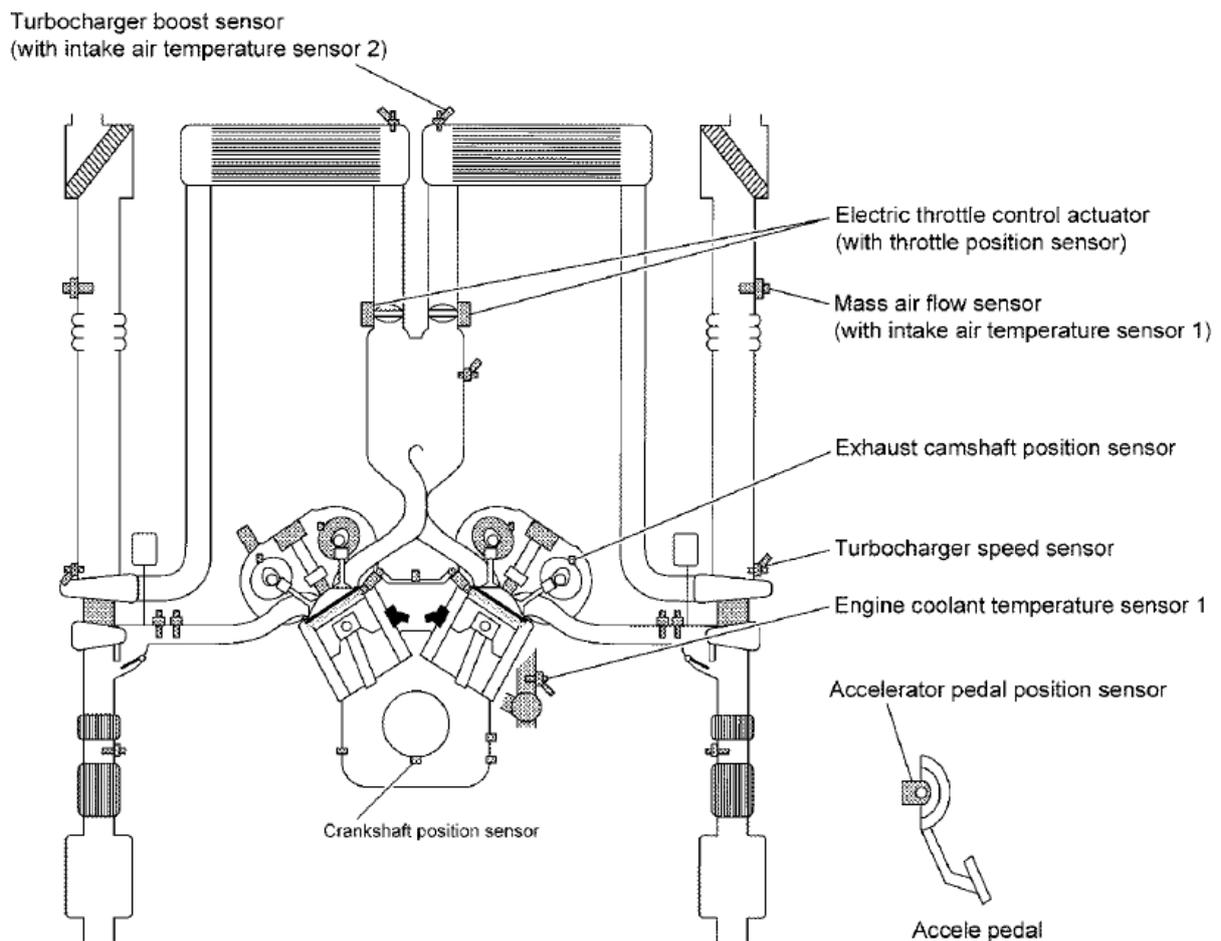
These maps represent the target intake cam advance angle in crank degrees from cam centre reference point.

Boost Control

Introduction

Starting with RaceROM Version 3, the OEM boost control has been rewritten and replaced with our own simplified boost control strategy using its own set of dedicated RaceROM maps. Upon adding a version 3 or later RRF, this option is enabled by default, and comes pre-populated with a sensible stage 1 boost control setup.

As the VR30 utilises electronic wastegates it is possible to set WG position at any RPM, the principles (proportional, integral and derivative) are the same as a pneumatic wastegate, however the control is performed in position rather than duty. There are also turbo speed sensors in the 400hp (high boost pressure) model which adds another dimension to the amount of control the ECU can exert.



There are no blow off valves (BOV's) as standard on the VR30DDTT motors and as a result they are prone to pre-throttle over boost during gearshifts and also when entering overrun. We have added some functionality to aid in reducing the over boost amount, fortunately the MAP is relatively well controlled using the throttle as well reducing risk to engine internals.

Map List

Boost Control	
<input type="checkbox"/>	Boost Controller Maximum
<input type="checkbox"/>	Boost Controller Minimum
<input type="checkbox"/>	Boost Limit
<input type="checkbox"/>	Boost Target A
<input type="checkbox"/>	Boost Target A (Trustful)
<input type="checkbox"/>	Boost Target Max Allowed #1
<input type="checkbox"/>	Boost Target Mode 1
<input type="checkbox"/>	Boost Target Mode 2
<input type="checkbox"/>	Boost Target Mode 3
<input type="checkbox"/>	Boost Target Mode 4
<input type="checkbox"/>	RaceROM Boost Controller Switches
<input type="checkbox"/>	Wastegate Base Target Position
<input type="checkbox"/>	Wastegate Base Target Position (EGR off)
<input type="checkbox"/>	Wastegate Correction - Integral #1
<input type="checkbox"/>	Wastegate Correction - Integral #2
<input type="checkbox"/>	Wastegate Correction - Proportional
<input type="checkbox"/>	Boost Target - Atmospheric Pressure Compensation #1
<input type="checkbox"/>	Boost Target - Atmospheric Pressure Compensation #2
<input type="checkbox"/>	Boost Target - Atmospheric Pressure Compensation #3
<input type="checkbox"/>	Boost Target Compensation - High Load #1
<input type="checkbox"/>	Boost Target Compensation - High Load #2
<input type="checkbox"/>	Boost Target Compensation - High Load #3
<input type="checkbox"/>	Boost Target Compensation - Low Load #1
<input type="checkbox"/>	Boost Target Compensation - Low Load #2
<input type="checkbox"/>	Boost Target Compensation - Low Load #3
<input type="checkbox"/>	Boost Correction - Air Temp Multiplier
<input type="checkbox"/>	Boost Correction - Integral Multiplier
<input type="checkbox"/>	Boost Target Scale by QH0
<input type="checkbox"/>	Exhaust pressure Map
<input type="checkbox"/>	Gearchange - Ignition Minimum Allowed
<input type="checkbox"/>	Gearchange - Wastegate Offset
<input type="checkbox"/>	Turbo Speed Minimum for Closed Loop
<input type="checkbox"/>	Turbo Speed Minimum for Closed Loop (Trustful)
<input type="checkbox"/>	Wastegate Correction - Air Temp
<input type="checkbox"/>	Wastegate Correction - Atmospheric Pressure
<input type="checkbox"/>	Wastegate Correction - Manifold Absolute Pressure
<input type="checkbox"/>	Wastegate Correction - Transient #1
<input type="checkbox"/>	Wastegate Correction - Turbo Speed Limiter 1
<input type="checkbox"/>	Wastegate Correction - Turbo Speed Limiter 2
<input type="checkbox"/>	Wastegate Correction - Turbo Speed Limiter 3
<input type="checkbox"/>	Wastegate Correction - Turbo Speed Threshold
<input type="checkbox"/>	Boost Limit Resume

Live Data Parameters

- *Boost Bank1/Boost Bank2* – Absolute pressure in bar, measured by the two boost sensors
- *RBC Maximum Desired Boost* – Relative boost max target, matches number format on gauge
- *Boost Target* – Absolute pressure target in bar, measured by the intake manifold pressure sensor
- *Boost Error* – Difference between MAP and Boost Target, positive numbers are over boost
- *Boost Target – RBC Maximum* – The current RR boost controller setpoint.
- *Boost Target Multiplier* – The QH0 based multiplier used for boost target correction
- *Manifold Gauge Pressure* – “Boost” pressure measured in bar above the current atmospheric pressure
- *Manifold Absolute Pressure* – Absolute pressure in bar, measured by the intake manifold pressure sensor
- *Manifold Pressure Sensor* – MAP sensor voltage value
- *Turbo Speed B1 & B2*– Current turbo speed in rpm only available on the 400hp models
- *Wastegate Actuator Position B1 & B2* – The mm distance the wastegate has extended (related to WG angle)
- *WG Actuator Position Sensor B1 & B2* – the WG position sensors current voltage output
- *WG Corr Base* – Output from Wastegate Posn. Corr. Calculation, not used in RR boost control strategy
- *WG Corr Integral* – WG duty added by Integral correction of EcuTek boost control strategy
- *WG Corr Proportional* – WG duty added by Proportional correction of EcuTek boost control strategy
- *WG Corr - Prop Int Sum* – Correction resulting from proportional and integral added together

- *WG Corr – Transient – Derivative component of boost error calculation*
- *WG Offset – During Gearshift – Offset applied in mm during upshift.*
- *WG Target – Air Temp Comp – Air temp correction value from target map (in Bar)*
- *WG Target – Atmospheric Pressure Correction amount applied from the Atmo Pressure Comp map*
- *WG target – Basemap Lookup - the value referenced in the WG target map (in mm)*
- *WG Target – Position – Final Position target after all corrections (in mm)*

EcuTek Boost Control vs RaceROM Boost Controller

There may be some confusion between the features for boost control in recent RaceROM versions, despite the similar naming due to historic reasons the two RaceROM features have different functions.

EcuTek Boost Control

EcuTek Boost Control is the control strategy to set the boost target and control the wastegate solenoid such that the boost reaches and remains on target.

RaceROM Boost Controller

(abbreviated to RBC) is a feature used to limit the boost target using ECU Connect and cruise control switchgear (when made available). The maximum boost target is displayed only in ECU connect or a ProECU log file. As can be determined from the boost target flow diagram the boost target can be below the value set by the RBC but it can never exceed it.

The RRBC is a final limit to any boost target, any boost target higher than the RRBC limit will be capped to the RRBC limit.

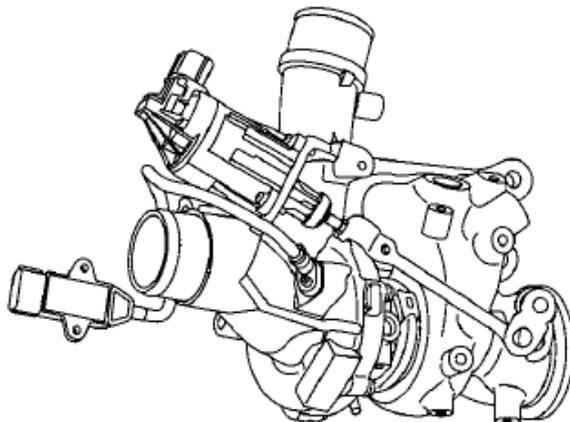
Absolute Boost

As per the latest updates to GTR the VR30DDTT follows the use of Manifold Absolute Pressure (MAP) for all aspects of tuning the boost control. All boost target, boost limit and boost threshold values are all absolute values in Bar. Tuners will now find that all boost related maps and live data will give consistent readings regardless of altitude, and calculations will hold true in all circumstances.

To make tuning as simple as possible we have added the Boost Target - Atmospheric Pressure Compensation maps by default, this gives a consistent “boost” at all altitudes, but the result is that your MAP will drop as a result, and power will be reduced at altitude if using the default **Boost Target Atmospheric Compensation** map.

Electronic Wastegate Control

The VR30DDTT uses the latest technology for controlling the opening angle of the wastegates, the wastegate actuator is now electronically driven as opposed to pneumatically. The electric wastegate control actuator operates based on a signal from ECM and adjusts the turbocharger boost control valve angle via link rod. The electronic control allows the turbocharger wastegate control valve to be opened even in non-supercharging regions. This reduces pumping losses and contributes to the fuel economy. When boost is requested the wastegate valve angles are controlled by the electronic control with a high degree of accuracy but are currently limited to OEM WG setups.



The Key Principle with Electronic wastegates is that they are controlled by a target position as opposed to a duty cycle. This extension is

- 8mm equals fully extended / fully open wastegate (no boost)
- 0mm equals fully protracted / fully closed wastegate (full boost)

There is a further lower level control for the actuator but these are not required currently as aftermarket WG controllers are not widely available.

Enable Special Features (Boost Control Related)

<input checked="" type="checkbox"/>	Enable RaceROM Boost Controller
<input type="checkbox"/>	RBC - Same value in all modes
<input type="checkbox"/>	Scale Boost Target by Atmospheric Pressure disable

EcuTek Boost Control – Enabled by default when adding RaceROM Feature File (patch)

The overall enable for the RaceROM boost control strategy is set by default when adding a patch. Once the patch is added the RR maps for boost control are used as opposed to the OEM strategy, this cannot be disabled or unchecked.

Enable RaceROM Boost Controller

Overall enable for the RBC, enabled by default. If turned off the cruise switchgear will do nothing boost control related.

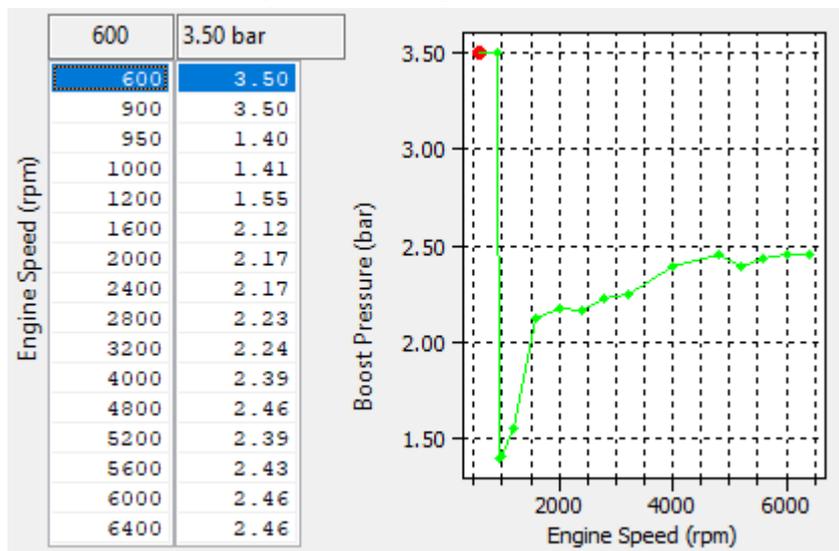
RBC – Same value in all modes

Forces the RBC setpoint to be maintained even when switching MapSwitch Mode. There is a limitation of this in that ALL modes will have a maximum setpoint corresponding to the lowest of the four values in **Boost Controller Maximum**.

Scale Boost Target by Atmospheric Pressure disable

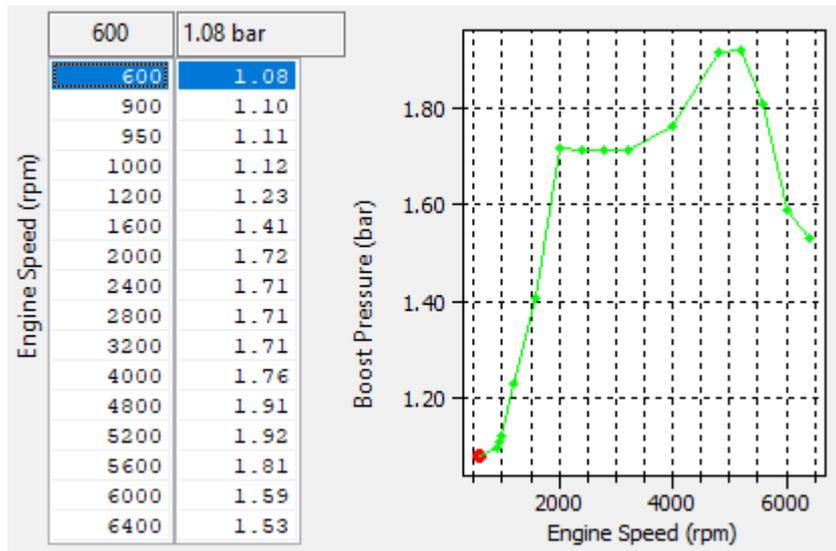
Forces the RRBC to ignore changes in atmospheric pressure when calculating boost error.

Boost Limit (Fuel Cut)



The manifold absolute pressure needs to exceed this limit, measured in Bar (Absolute) by the manifold pressure sensor, for a time that exceeds a currently undiscovered delay timer.

Boost Limit Resume

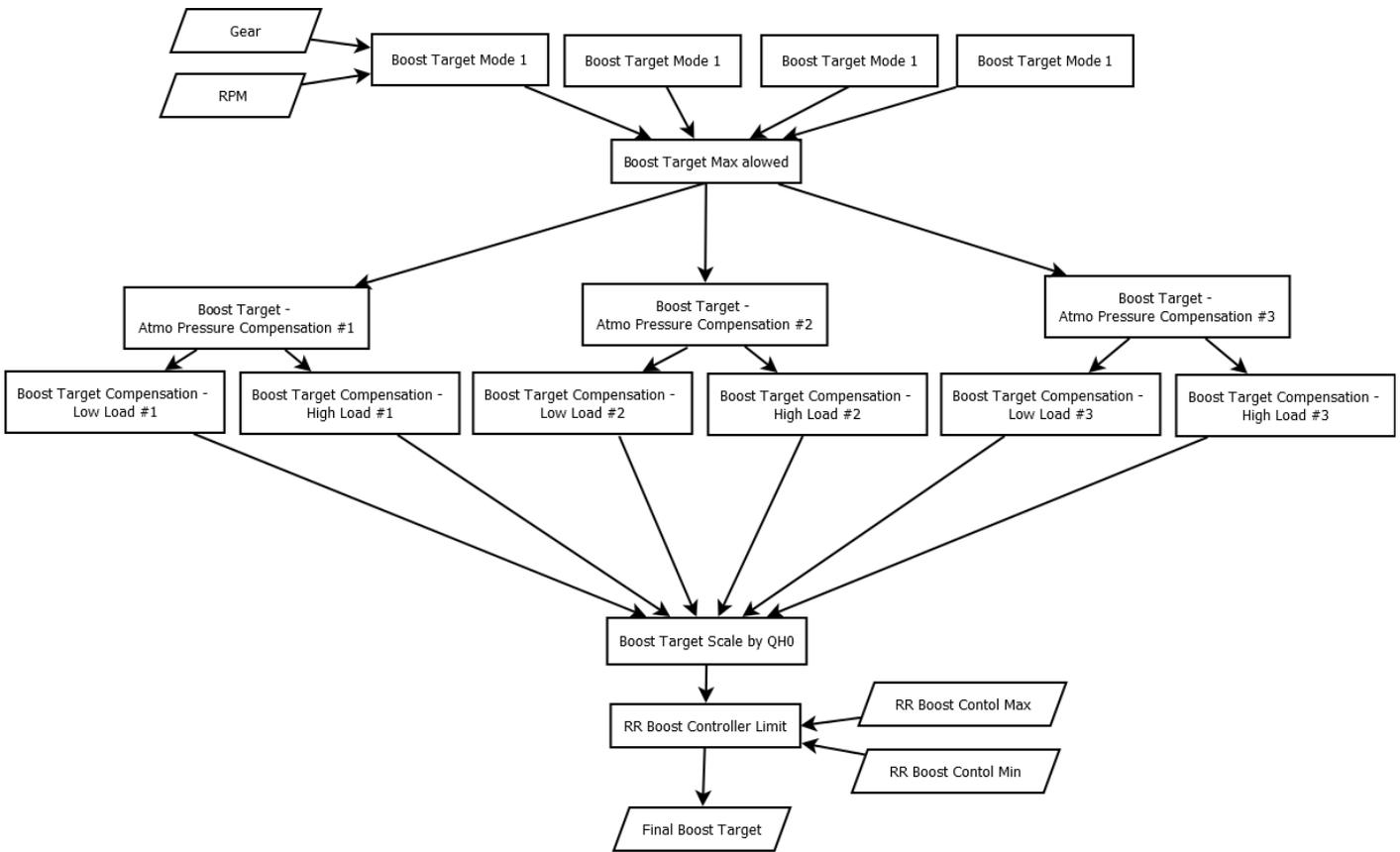


There are separate cut and resume maps to introduce hysteresis into the fuel cut.

With the default limit of 2.44 Bar (at 4400RPM) and a Resume of 1.86Bar, the fuel will be cut when the MAP exceeds 2.44Bar for a set time and resume when the MAP drops below 1.86Bar.

Boost Target

The boost target system in the VR30 product has some aspects that are slightly different to the normal boost target set point methods. The current understanding and setup can be seen in the below flow chart.



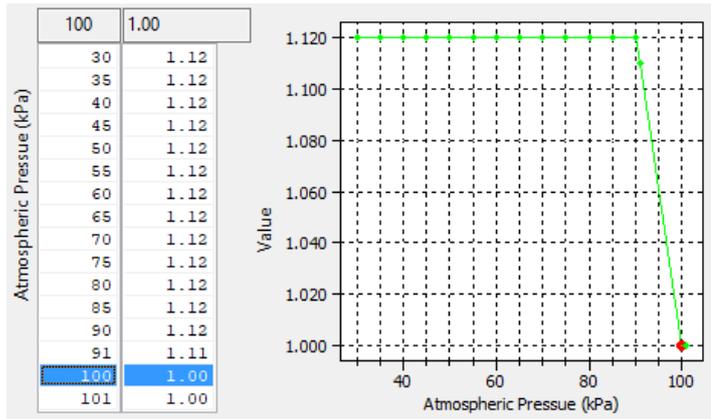
Boost Target Mode 1 - 4

		800.0	Engine Speed (rpm)													0.94 bar	
		800.0	1000	1200	1600	2000	2400	2800	3200	4000	4400	4800	5200	5600	6000	6400	6800
Gear (raw)	1	0.945	0.986	1.21	1.71	1.72	1.77	1.82	1.82	1.94	1.98	2.00	1.90	1.78	1.60	1.51	1.40
	2	0.945	0.986	1.21	1.71	1.72	1.77	1.82	1.82	1.94	1.98	2.00	1.90	1.78	1.60	1.51	1.40
	3	0.945	0.986	1.21	1.71	1.72	1.77	1.82	1.82	1.94	1.98	2.00	1.90	1.78	1.60	1.51	1.40
	4	0.945	0.986	1.21	1.71	1.72	1.77	1.82	1.82	1.94	1.98	2.00	1.90	1.78	1.60	1.51	1.40
	5	0.945	0.986	1.21	1.71	1.72	1.77	1.82	1.82	1.94	1.98	2.00	1.90	1.78	1.60	1.51	1.40
	6	0.945	0.986	1.21	1.71	1.72	1.77	1.82	1.82	1.94	1.98	2.00	1.90	1.78	1.60	1.51	1.40
	7	0.945	0.986	1.21	1.71	1.72	1.77	1.82	1.82	1.94	1.98	2.00	1.90	1.78	1.60	1.51	1.40

Boost target is now defined using four 3D maps with RPM and gear axis', there are 4 separate target maps, one for each Map Switch Mode, throttle modulation is in the form of a simple 2D QH0 map.

An RPM dependant target boost profile is set on a per gear basis. Typically gears 1 and 2 have noticeably lower targets due to traction limitations.

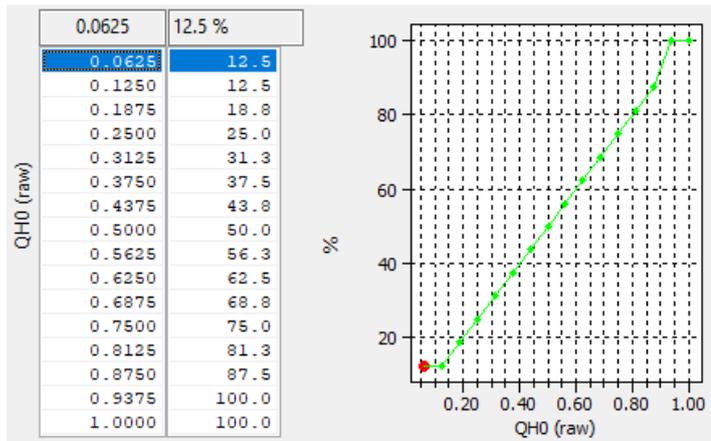
Boost Target Atmospheric Compensation



The boost target can be offset for changes in atmospheric pressure, the default map values reduce the absolute boost target 0.1Bar for the first 0.1 Bar drop in atmospheric pressure and stay at that afterwards. This is suitable for stock turbos which will often be further limited by turbo speed, pushing the same absolute pressure at altitude can be damaging to the turbos while still not achieving the desired pressure.

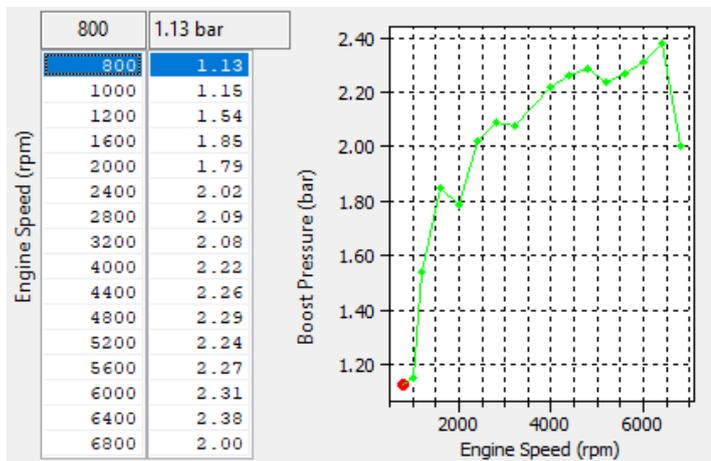
If working with turbos that have plenty of headroom at sea level then flattening this map to 0 will give the same absolute pressure target at altitude and result in similar power levels.

Boost Target Scale By QH0



The boost target as set by the **Boost Target** map is multiplied by the output of this map. For example, a target of 2.4bar * 0.45 = 1.08bar absolute.

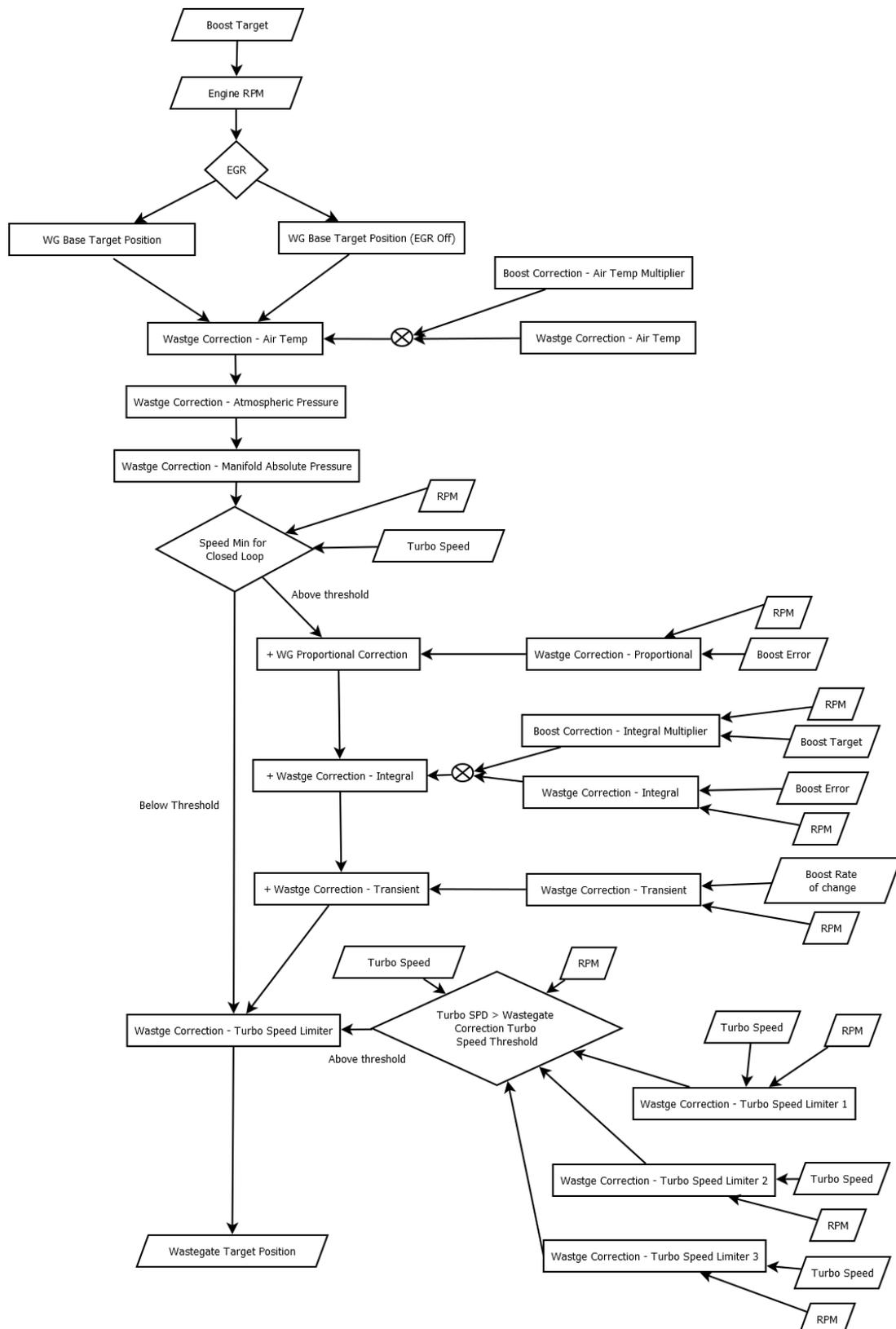
Boost Target Max Allowed



Maximum target based on engine speed, used as a maximum limit for boost target.

Wastegate Duty Calculation

The Wastegate position calculation follows the process below, the closed loop control consists of a base wastegate position. The base duty is always subject to air temperature, Barometric pressure and Manifold pressure corrections. If the turbo speed is high enough (above the threshold for closed loop turbo control) a proportional, integral and a transient correction term are calculated and added. There is an overall turbo speed limiting waste gate correction amount applied when above the maximum allowed turbo speed threshold.



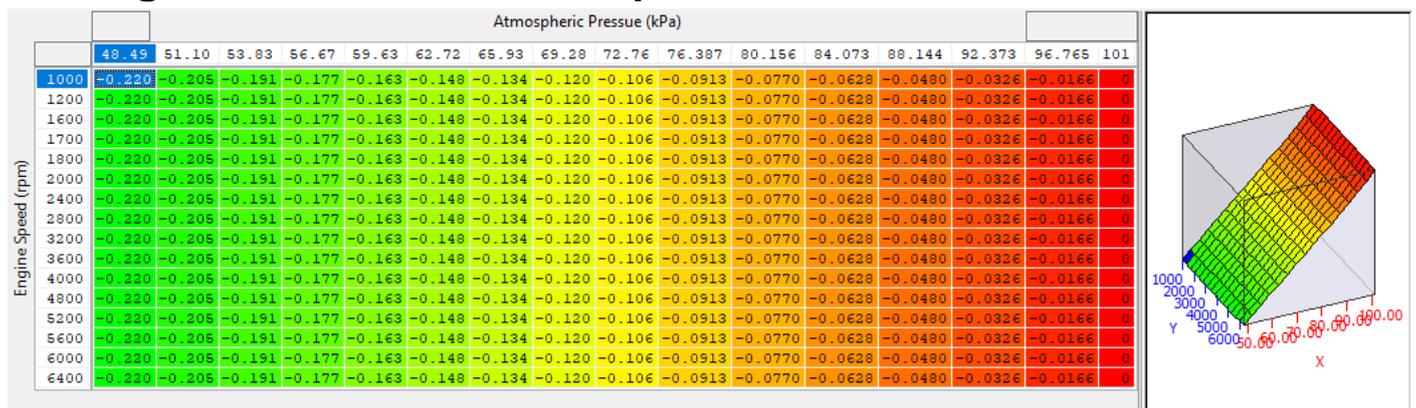
WG Base Target Position (EGR On)

WG Base Target Position (EGR Off)

		Target Boost Pressure (bar)															
		0.800	0.900	1	1.01	1.100	1.2000	1.300	1.4000	1.5000	1.60000	1.70000	1.80000	1.90000	2.00000	2.1000	2.20000
Engine Speed (rpm)	1000	8	8	8	6.53	0.770	0.0000	-0.630	-1.130	-1.370	-1.5400	-1.6200	-1.7000	-1.7800	-1.8600	-1.950	-2.0300
	1200	8	8	8	8.00	1.400	0.0200	-0.250	-0.750	-1.000	-1.1600	-1.2400	-1.3200	-1.4100	-1.4900	-1.570	-1.6500
	1600	8	8	8	8.00	6.200	1.9000	0.900	0.430	0.170	-0.0800	-0.3250	-0.5700	-0.6500	-0.7400	-0.820	-0.9000
	1700	8	8	8	8.00	8.000	2.3500	1.210	0.660	0.420	0.1500	0.0700	0.0200	-0.0300	-0.0800	-0.130	-0.1800
	1800	8	8	8	8.00	8.000	3.1000	1.670	1.120	0.780	0.5600	0.4000	0.3300	0.2600	0.1900	0.120	0.0500
	2000	8	8	8	8.00	8.000	4.3000	2.460	1.700	1.240	1.0000	0.8700	0.7600	0.6500	0.5400	0.430	0.3200
	2400	8	8	8	8.00	8.000	6.2700	3.750	2.780	2.180	1.7700	1.4400	1.0883	0.7367	0.6433	0.553	0.4600
	2800	8	8	8	8.00	8.000	8.0000	5.110	3.790	2.990	2.4800	2.0700	1.5450	1.0200	0.8600	0.690	0.5300
	3200	8	8	8	8.00	8.000	8.0000	6.930	4.950	3.910	3.1000	2.6000	2.0800	1.5600	1.3900	1.230	1.0600
	3600	8	8	8	8.00	8.000	8.0000	8.000	6.550	5.000	3.9000	3.2800	2.6800	2.2650	1.8500	1.680	1.5100
	4000	8	8	8	8.00	8.000	8.0000	8.000	7.430	5.690	4.4800	3.7900	3.1100	2.5000	2.3300	2.170	2.0000
	4800	8	8	8	8.00	8.000	8.0000	8.000	8.000	6.350	4.9200	4.0000	3.4300	3.0300	2.3200	2.160	2.0000
	5200	8	8	8	8.00	8.000	8.0000	8.000	8.000	5.770	4.5400	3.7600	3.2300	2.8900	2.2900	2.140	1.9900
	5600	8	8	8	8.00	8.000	8.0000	8.000	8.000	5.320	4.2100	3.4800	3.0200	2.6100	2.2600	1.870	1.7900
	6000	8	8	8	8.00	8.000	8.0000	8.000	8.000	5.270	4.1800	3.4400	2.9400	2.5300	2.1400	1.680	1.4700
	6400	8	8	8	8.00	8.000	8.0000	8.000	5.790	4.590	3.7600	3.1500	2.6700	2.2700	1.9400	1.460	1.3800

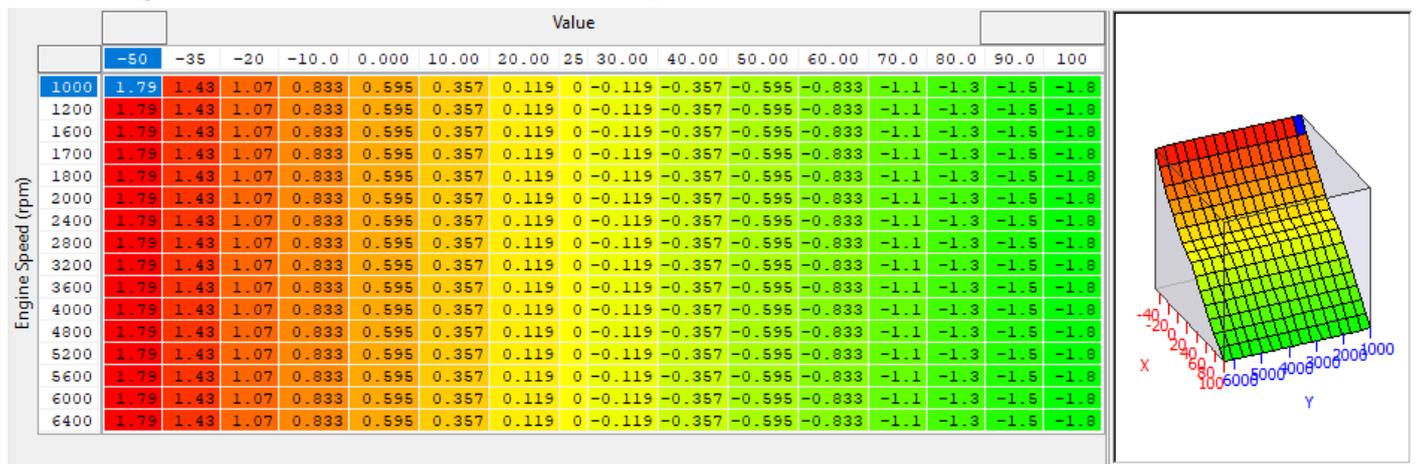
These two maps are used to set a base wastegate position for EGR On and EGR Off, which set a base position in mm extension for the WG for corrections. The X axis is target boost in Bar (absolute) and the Y axis is engine speed. 8mm = fully open, 0mm = fully closed. Negative values cannot be achieved but keep the profile of the map for OEM calculations.

Wastegate Correction – Atmospheric Correction



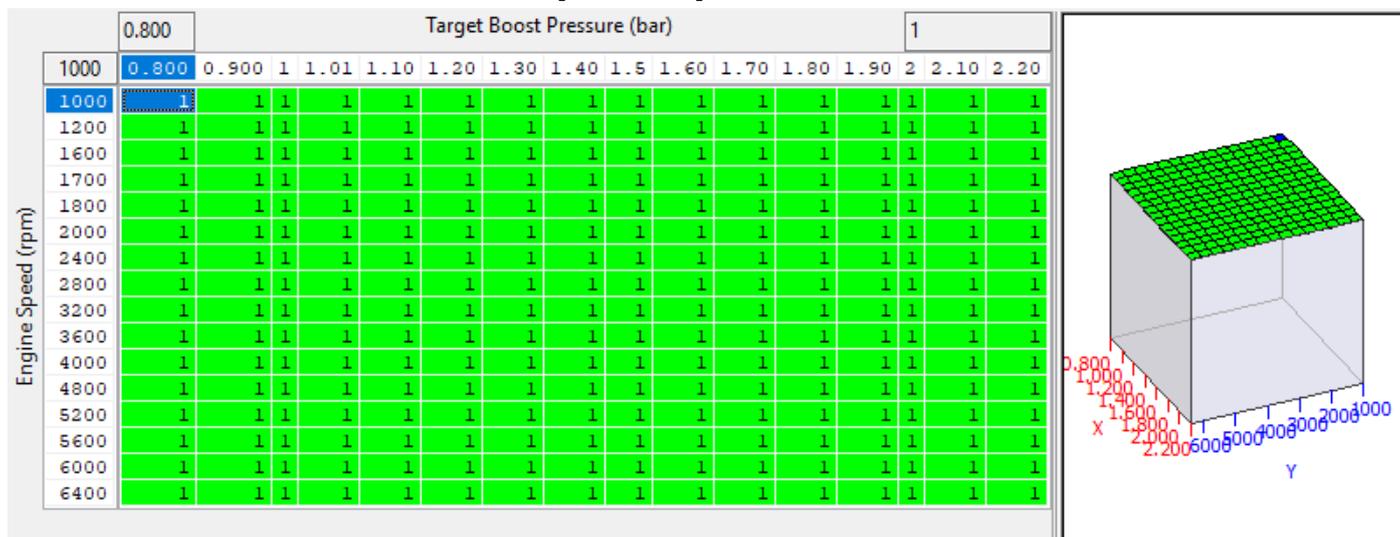
This map defines the amount of WG correction applied in millimeters to the base duty maps depending on the measured barometric pressure (in kPa).

Wastegate Correction - Air Temp



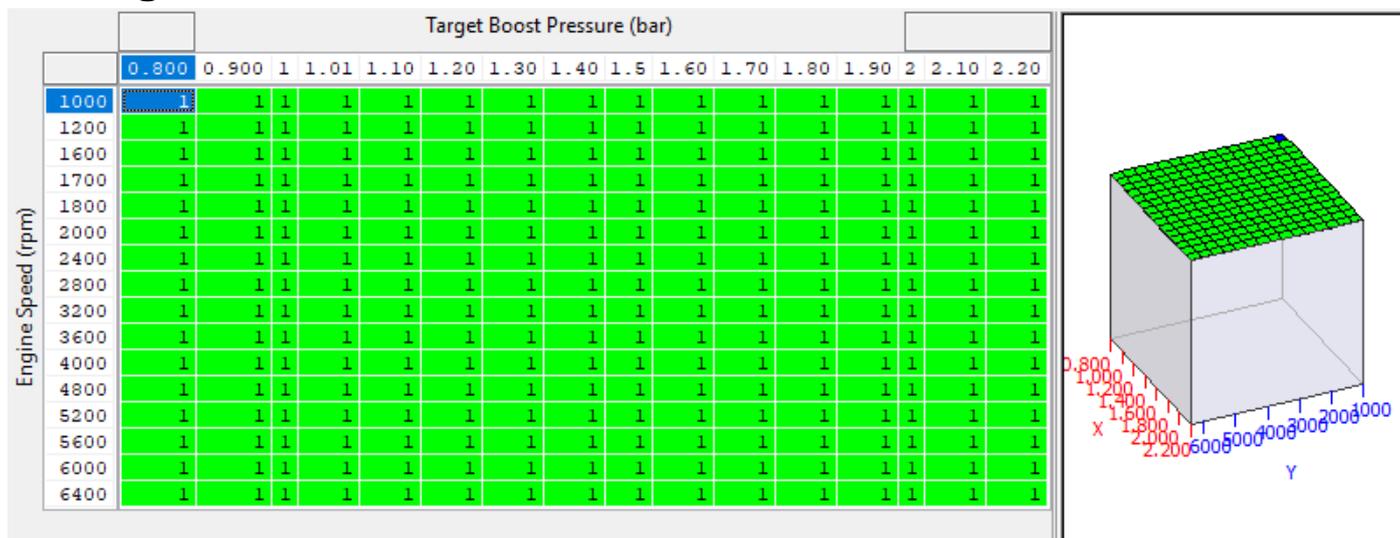
This map defines the amount of WG correction applied in millimeters to the base position maps depending on intake air temperature. The map output is then multiplied by the Boost Correction – Air Temp Multiplier.

Boost Correction - Air Temp Multiplier



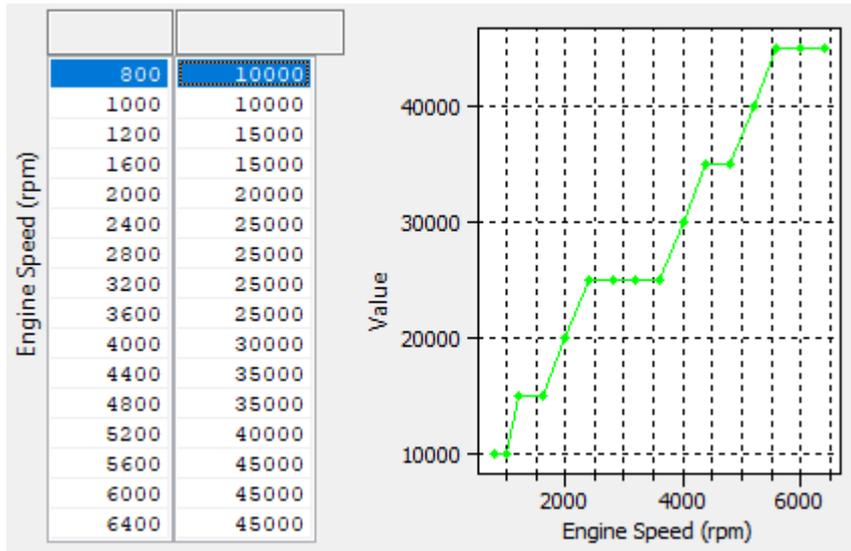
This map multiplies the amount of WG correction – Air Temp map output. The resulting output is then added to the base position map. It can be used to calibrate the Wastegate - Air Temp correction map for a given RPM and Manifold Absolute Pressure.

Wastegate Correction – Manifold Absolute Pressure



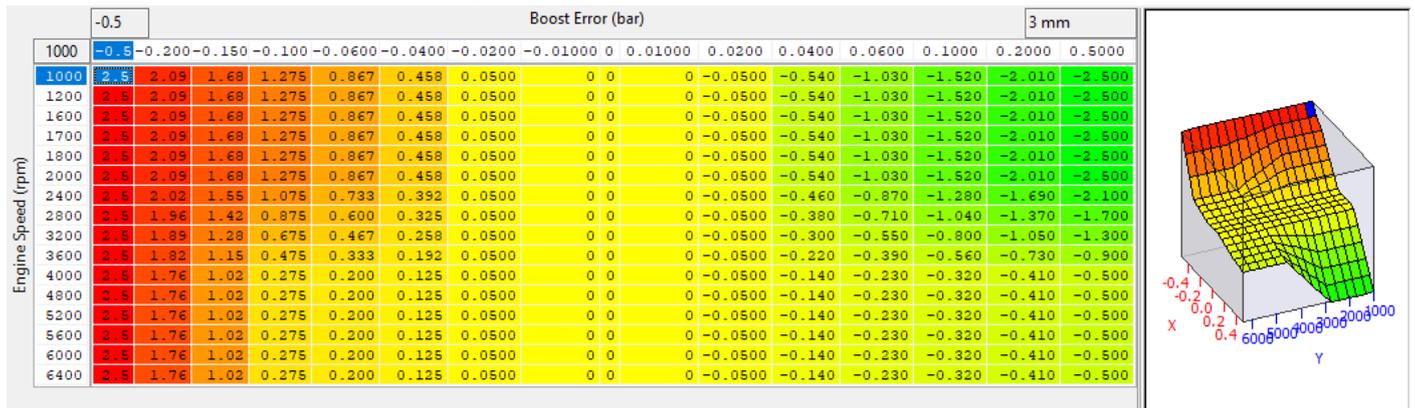
This map multiplies the output of all correction maps before the information is fed into the closed loop corrections.

Turbo Speed Minimum for Closed Loop & Trustful



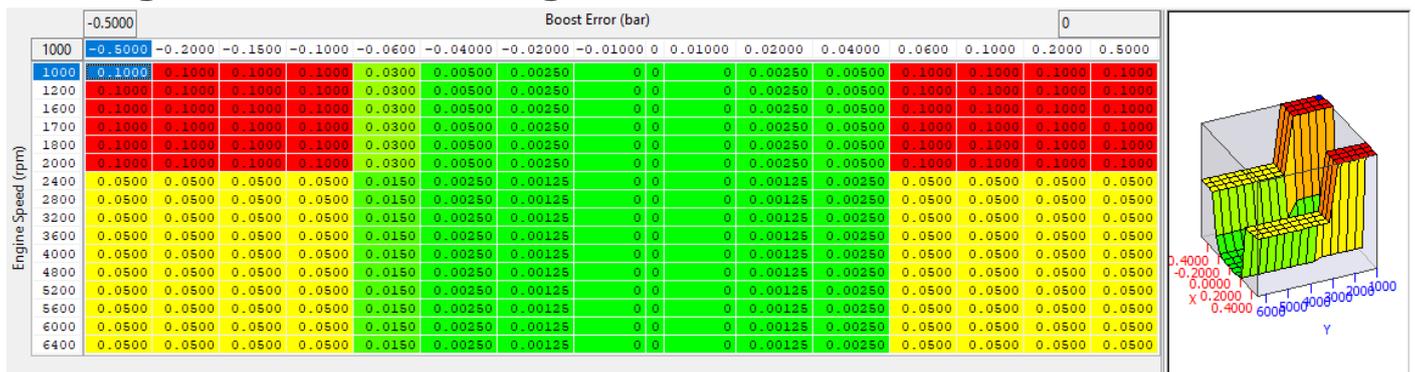
A threshold of turbo speed to enable closed loop control of the wastegate position. Proportional, Integral and Derivative feedback are activated when the turbo speed value is exceeded and remains active until the turbo speed drops by an unknown hysteresis value. This table can be used to stop integral windup when at full throttle and waiting for the boost to rise.

Waste Correction - Proportional



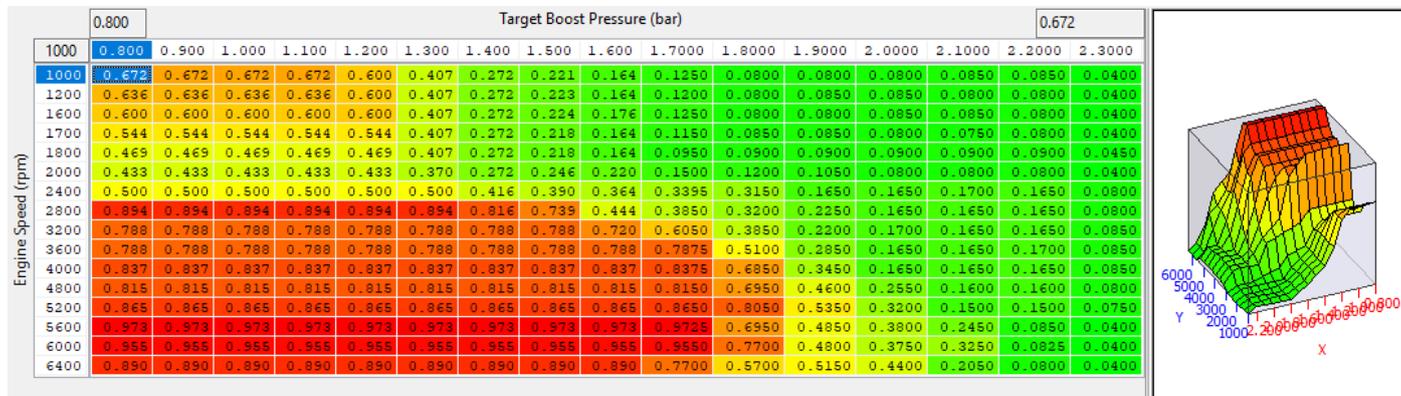
Proportional correction is absolute wastegate duty added or subtracted at an instant in time based on the current boost error. The default maps have high positive values when the boost is under target at low RPM while in spool up. Using high proportional values is preferable to high integral values to prevent windup but still results in low wastegate position on spool.

Wastegate Correction Integral #1 & #2



Wastegate Integral correction builds up over time. While active (see above conditions) this map dictates how much the integral value is increased with each cycle of the boost control loop. Each loop takes just 10ms (one 1/100 of a second) and the current integral correction is multiplied by the integral multiplier before being applied, it can be observed by checking the *WG Corr - Integral* live data parameter which is logged by default.

Boost Correction Integral Multiplier



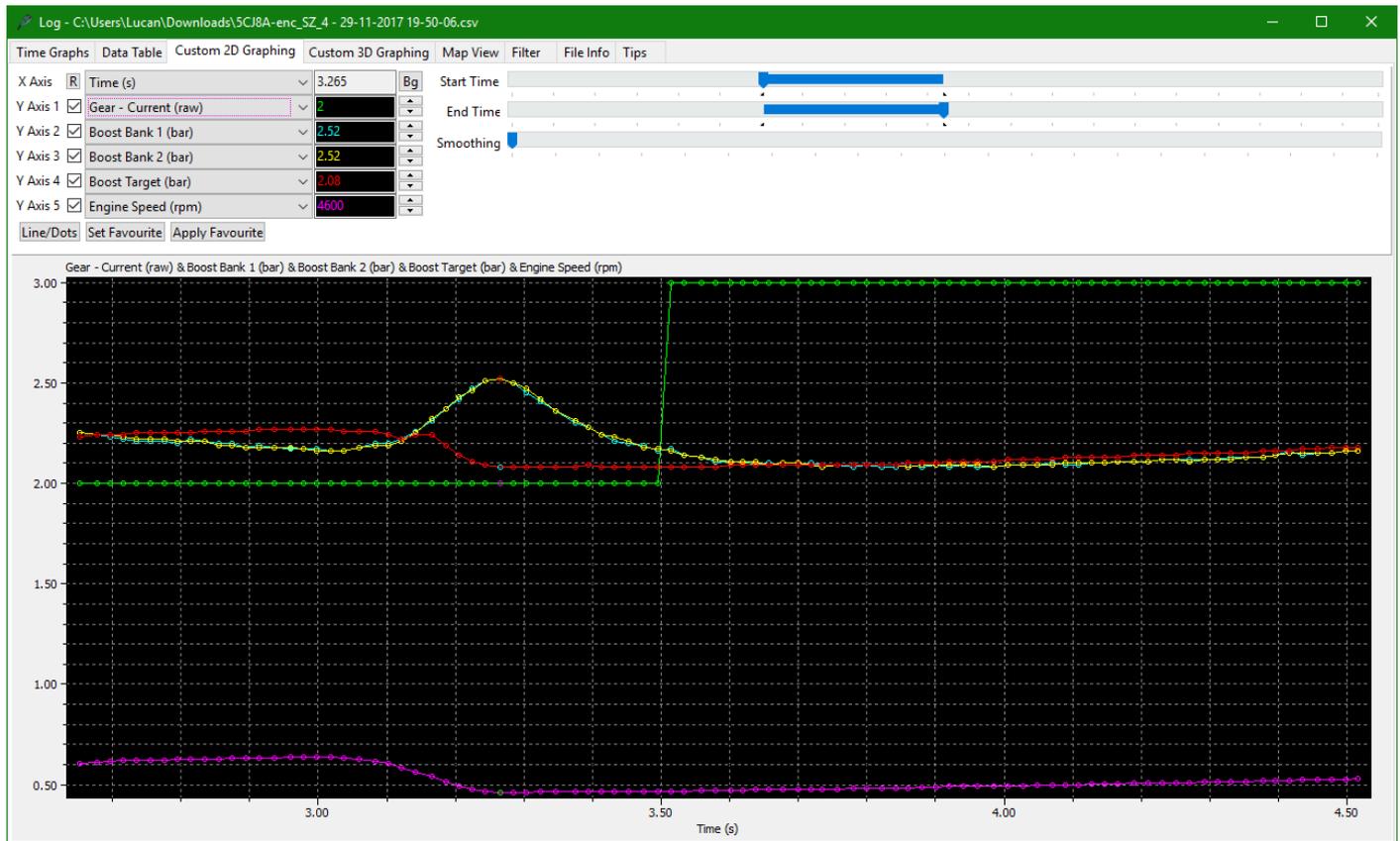
Multiplies the current integral correction, the result is shown as the logging parameter called *WG Corr - Integral*. The intent of this map is to reduce or increase the effectiveness of the total integral correction based on engine speed and Manifold Absolute Pressure allowing fine control in different running conditions

Waste Correction – Transient (Derivative)



Transient/Derivative correction is absolute wastegate duty added or subtracted at an instant in time based on the current rate of change in boost. The default maps only have positive values when the boost is increasing at a fast rate (peak spool RPM). Using high derivative values should only really be needed to prevent the inertia of large turbos overshooting the boost target value but still need a closed WG position to spool.

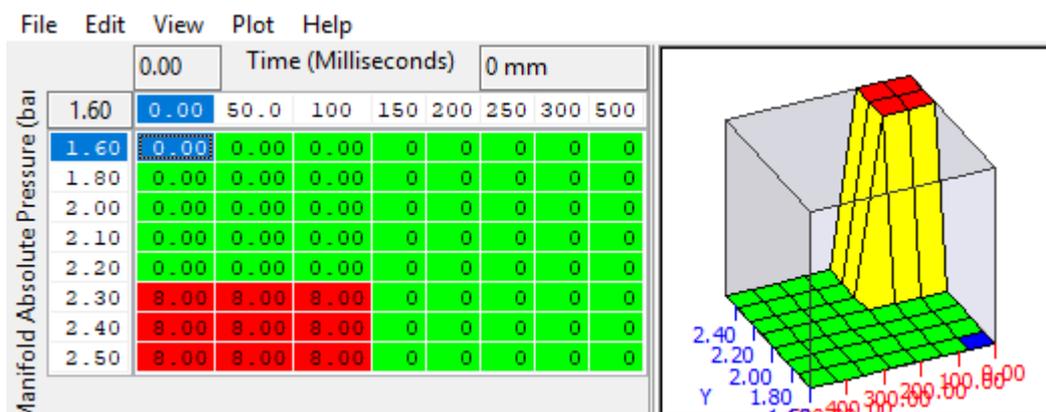
Gearchange Boost Spikes



The Turbo chargers on the VR30DDTT engines are designed for optimal drivability but even with turbo speed sensors and electronic wastegates there is still a lag time between the WG opening fully and the boost dropping. This is compounded when the airflow requirements are reduced on gearshift or overrun. There is no mechanical blow off valves (BOV's) on these engines so when the boost is increased and the airflow requirements of the engine reduce (on gearshift) boost spikes can occur.

To aid in combating this spike we have added custom code (*Gearchange – Wastegate Offset*) to drive the waste gate to a set position for a set time during the shift to reduce turbine airflow and hence boost, The *Gearchange - Ignition Minimum Allowed* map can also be used to limit the amount of ignition retard to reduce the amount of exhaust enthalpy limiting the ability of the turbo to make boost pressure.

Gearchange – Wastegate Offset



A temporary change in the Wastegate duty triggered with an upshift to prevent boost spikes on gearshift caused by a sudden change in the air consumption of the engine as the RPM drops. The X axis is time since the start of an upshift, and the Y axis is the relative boost in Bar at the time the shift was triggered.

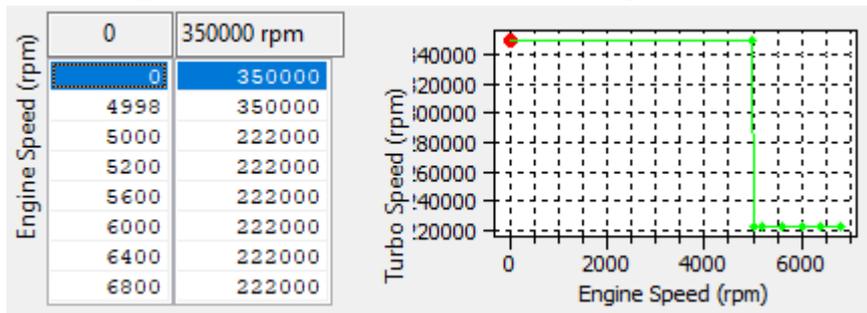
Gearchange – Ignition Minimum Allowed



A temporary lower limit on the final ignition timing value triggered by an upshift to prevent boost spikes on gearshift caused by a sudden change in the air consumption of the engine as the RPM drops. The X axis is time since the start of an upshift, and the Y axis is the relative boost in Bar at the time the shift was triggered.

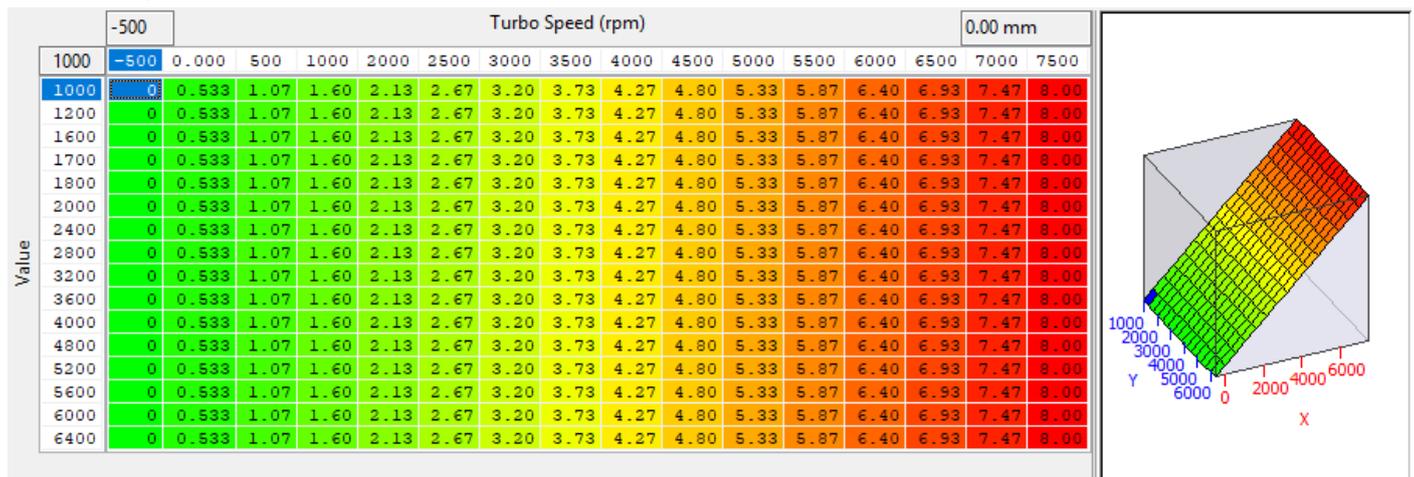
Keep in mind that this will effect the amount of torque reduction achieved so may mean that gear shift quality is affected.

Wastegate Correction Turbo Speed Threshold



This map is the turbo speed limit, when the measured (or estimated for silver sport cars) turbo speed goes above this threshold the **Wastegate Correction Turbo Speed Limit #1 - #3** maps are applied to maintain the turbo speed for turbo reliability. This map can be increased to allow the turbo to spin faster and increase the airflow/pressure.

Wastegate Correction Turbo Speed limiter #1 - #3



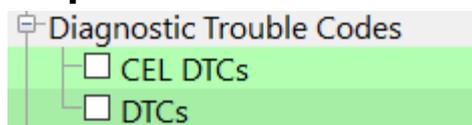
When the **Wastegate Correction Turbo Speed Threshold** is exceeded the above offset to absolute WG position is applied reducing the achieved boost. This maintains a specific turbo speed preventing damage to the turbo due to over-speeding. The X axis is turbo speed above the threshold, the Y-Axis is engine speed.

Diagnostic Trouble Codes

Introduction

All OBD vehicles use forms of self diagnosis and driver alerting, in the VR30DDTT equipped vehicles there are two separate DTC lists, one for the ECM limp modes and one for the Check Engine Light (CEL)

Map List



Live Data Parameters

- *Dig: Safe Mode* – shows on or off depending on DTC's that cause a limp mode.

DTC's will need to be scanned using ProECU or ECU Connect to know which DTC's are causing a limp mode. If DTC's occur do not assume that they should just be disabled, it is likely that an actual issue with the car has come up and needs to be fixed as opposed to ignored.

Operation

To Disable a DTC simply uncheck the DTC code, in the VR30DDTT there are separate maps for the CEL DTC and the non CEL DTC's so if you can disable the CEL DTC and still have a limp mode if required.

CEL DTCs & DTCs

File Edit Help

<input type="checkbox"/>	B1900 -
<input type="checkbox"/>	B1901 -
<input type="checkbox"/>	B1902 -
<input type="checkbox"/>	B1903 -
<input type="checkbox"/>	B1904 -
<input type="checkbox"/>	B1910 -
<input type="checkbox"/>	B1911 -
<input type="checkbox"/>	B1912 -
<input type="checkbox"/>	B1913 -
<input type="checkbox"/>	B1914 -
<input checked="" type="checkbox"/>	P0010 - "A" Camshaft Position Actuator Circuit/Open Bank 1
<input checked="" type="checkbox"/>	P0010 - "A" Camshaft Position Actuator Circuit/Open Bank 1
<input checked="" type="checkbox"/>	P0011 - "A" Camshaft Position - Timing Over-Advanced or System Performance Bank 1
<input checked="" type="checkbox"/>	P0011 - "A" Camshaft Position - Timing Over-Advanced or System Performance Bank 1
<input checked="" type="checkbox"/>	P0014 - "B" Camshaft Position - Timing Over-Advanced or System Performance Bank 1
<input checked="" type="checkbox"/>	P0020 - "A" Camshaft Position Actuator Circuit/Open Bank 2
<input checked="" type="checkbox"/>	P0020 - "A" Camshaft Position Actuator Circuit/Open Bank 2
<input checked="" type="checkbox"/>	P0021 - "A" Camshaft Position - Timing Over-Advanced or System Performance Bank 2
<input checked="" type="checkbox"/>	P0021 - "A" Camshaft Position - Timing Over-Advanced or System Performance Bank 2
<input checked="" type="checkbox"/>	P0024 - "B" Camshaft Position - Timing Over-Advanced or System Performance Bank 2
<input checked="" type="checkbox"/>	P0030 - HO2S Heater Control Circuit Bank 1 Sensor 1
<input checked="" type="checkbox"/>	P0031 - HO2S Heater Control Circuit Low Bank 1 Sensor 1
<input checked="" type="checkbox"/>	P0032 - HO2S Heater Control Circuit High Bank 1 Sensor 1
<input checked="" type="checkbox"/>	P0037 - HO2S Heater Control Circuit Low Bank 1 Sensor 2
<input checked="" type="checkbox"/>	P0037 - HO2S Heater Control Circuit Low Bank 1 Sensor 2
<input checked="" type="checkbox"/>	P0038 - HO2S Heater Control Circuit High Bank 1 Sensor 2
<input checked="" type="checkbox"/>	P0046 - Turbocharger/Supercharger Boost Control "A" Circuit Range/Performance
<input checked="" type="checkbox"/>	P0046 - Turbocharger/Supercharger Boost Control "A" Circuit Range/Performance
<input checked="" type="checkbox"/>	P004B - Turbocharger/Supercharger Boost Control "B" Circuit Range/Performance
<input checked="" type="checkbox"/>	P004B - Turbocharger/Supercharger Boost Control "B" Circuit Range/Performance
<input checked="" type="checkbox"/>	P0050 - HO2S Heater Control Circuit Bank 2 Sensor 1
<input checked="" type="checkbox"/>	P0051 - HO2S Heater Control Circuit Low Bank 2 Sensor 1
<input checked="" type="checkbox"/>	P0052 - HO2S Heater Control Circuit High Bank 2 Sensor 1
<input checked="" type="checkbox"/>	P0053 - HO2S Heater Resistance Bank 1 Sensor 1
<input checked="" type="checkbox"/>	P0057 - HO2S Heater Control Circuit Low Bank 2 Sensor 2
<input checked="" type="checkbox"/>	P0057 - HO2S Heater Control Circuit Low Bank 2 Sensor 2
<input checked="" type="checkbox"/>	P0058 - HO2S Heater Control Circuit High Bank 2 Sensor 2
<input checked="" type="checkbox"/>	P0059 - HO2S Heater Resistance Bank 2 Sensor 1
<input checked="" type="checkbox"/>	P0075 - Intake Valve Control Solenoid Circuit Bank 1
<input checked="" type="checkbox"/>	P0078 - Exhaust Valve Control Solenoid Circuit Bank 1

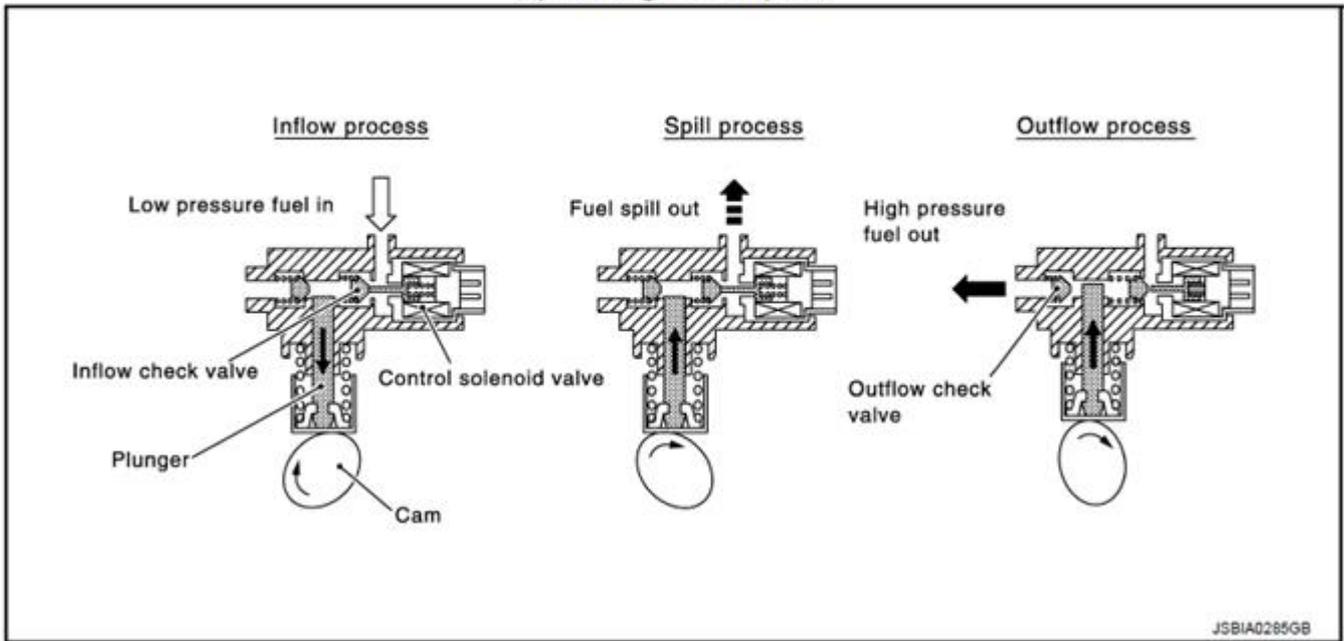
To turn off a DTC simply uncheck the DTC code you want to disable.

Fuel Pressure

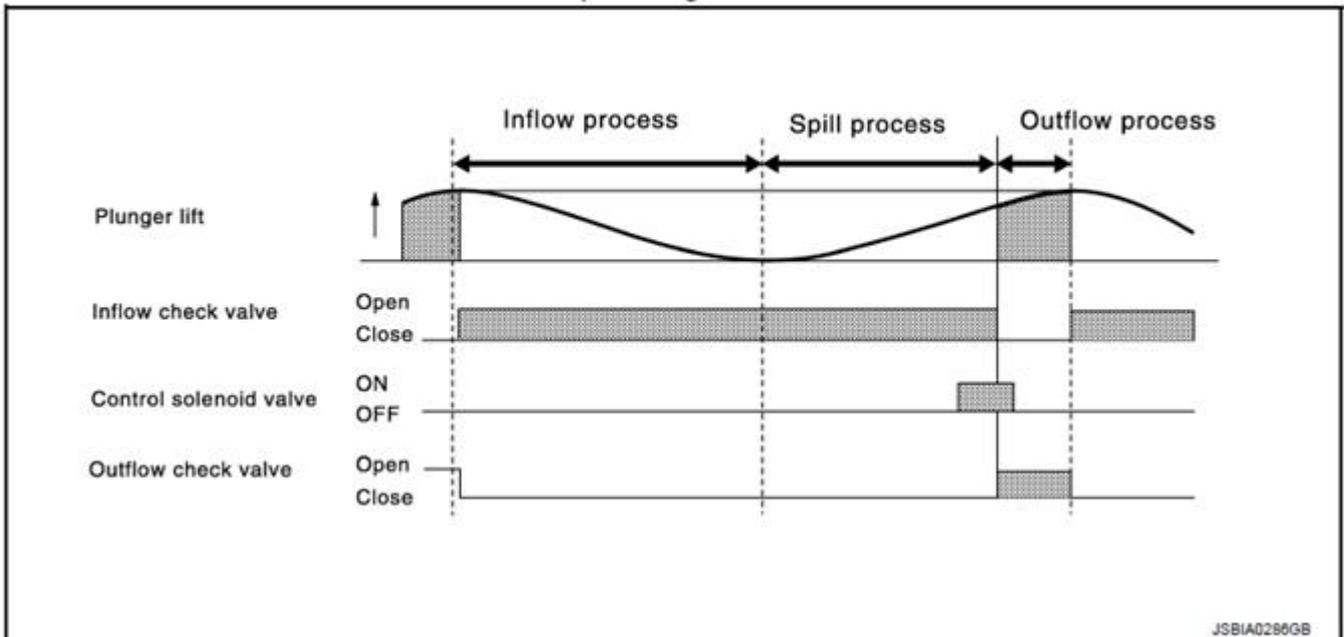
Introduction

The fuel pump in a VR30DDTT is slightly different to other manufacturers but seems to be common across the Nissan DI engines. Nissan specify a trigger point at which to start the outflow process to deliver the correct amount of fuel volume to maintain the correct pressure. The pump works as below but the VR30DDTT has a 3 lobe fuel pump cam, this means that we have 240 degrees of crank rotation per pump cycle and 120 degrees for an output stroke.

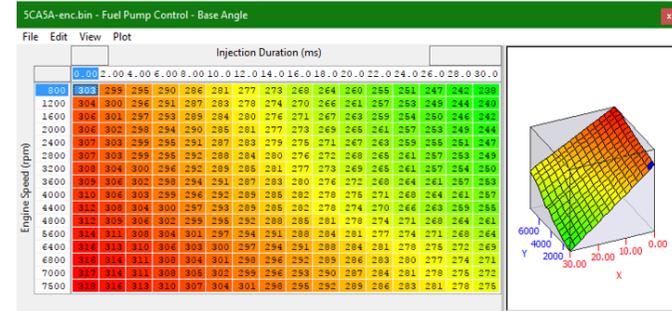
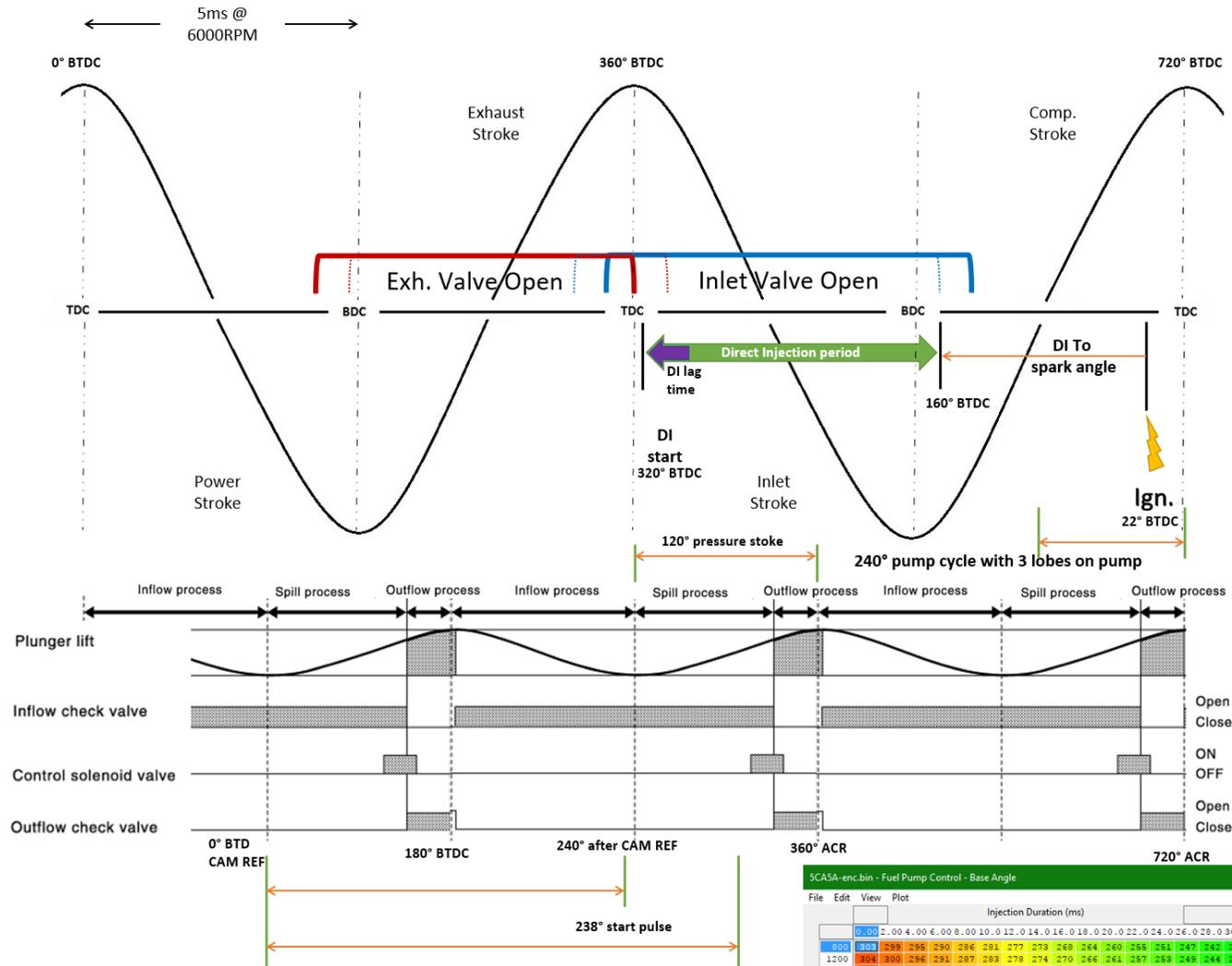
Operating Description



Operating Chart



The corrections for closed loop fuel pressure control are all modifiers to the outflow trigger angle. Below is a diagram illustrating how we believe that the pump control strategy and target maps work. The **Fuel pump control - Base angle** map is the ECU's initial point to trigger the outflow process. There are dead times, current targets and limits used as well, but these would only need to be changed if the pump solenoid is different, similar to what you would do if you were to change the injectors in other platforms.



The base angle maps give the start angle for the outflow process. The start angle (*Fuel Pump Angle Target – Base*) then has closed loop feedback corrections applied to it before the final value (*Fuel Pump Angle Target*) is used to trigger the solenoid. There are two closed loop feedback methods used and they directly work in degrees crank angle. There are

- Proportional feedback (*Fuel Pump Angle Target – Prop*)
- Integral feedback (*Fuel Pump Angle Target – Int*)

It applies the correction coefficients to the calculated fuel pressure error like below.

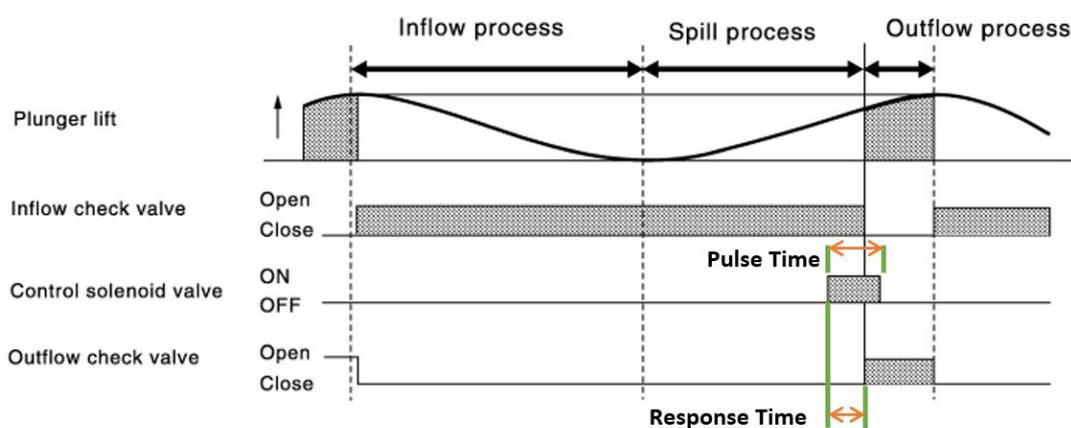
$$\text{Feedback Correction Angle} = \text{Map Output} \times (\text{Fuel Pressure} - \text{Fuel Pressure Target})$$

The correction angle values are directly applied to the base output value. If you find your actual fuel pressure does not match the target fuel pressure the first step is to adjust the base map, for example.

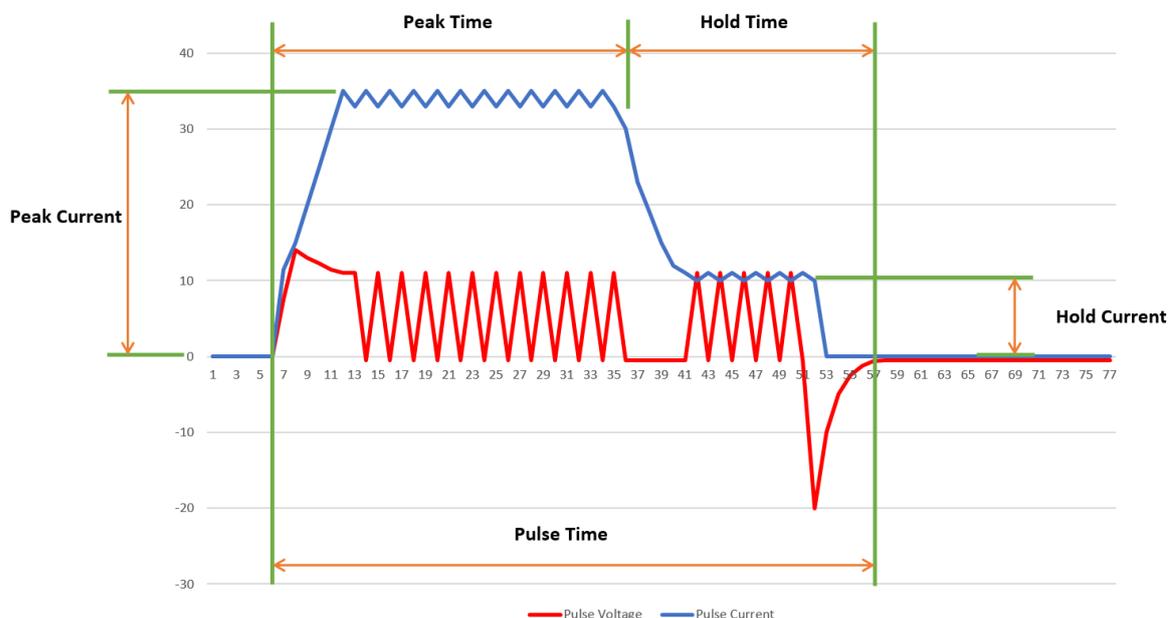
- Increase the angle to decrease stroke and delivered pressure
- Decrease the angle to increase stroke and delivered pressure

If you find that the *Fuel Pressure* does not meet the *Fuel Pressure Target* you can modify the proportional and integral factor maps at the required RPM to smooth out the delivered pressure.

The fuel pump solenoid is controlled in a peak and hold method. If you are calibrating a replacement fuel pump solenoid it's likely you will need to adjust **Fuel Pump Regulator Pulse Time** and **Fuel Pump Regulator Response Time**.



If only the mechanical pump unit has been changed, the **Fuel Pump Control - Base angle** and associated PID maps will require recalibration and the solenoid maps can be left alone. If changing the fuel pump solenoid you may need to alter the actual drive pulse characteristics to suit the physical changes to the solenoid, the drive current and voltage look a little like below, when changing the pulse characteristics use the below diagram as a reference.



The time period for each total pulse is set by the **fuel Pump Regulator - Pulse Time**. The hold component is set by the **Fuel Pump - Hold Time Initial Value** and the peak section is the difference between the total and hold section of the drive current profile. Peak and hold current can also be switched to different levels depending on engine speed if required.

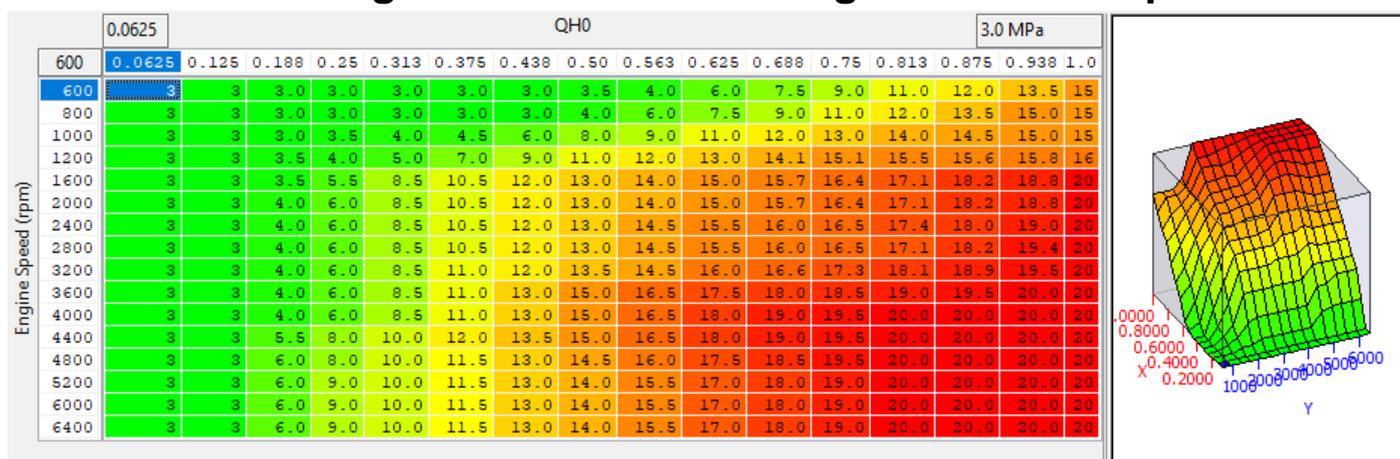
Map List

Fuel Pressure	
<input type="checkbox"/>	Fuel Pressure target
<input type="checkbox"/>	Fuel Pressure target at low temp
<input type="checkbox"/>	Fuel Pump - Battery Voltage for Switching Time
<input type="checkbox"/>	Fuel Pump - Delay Time switching Peak Current
<input type="checkbox"/>	Fuel Pump - Hold Current 1
<input type="checkbox"/>	Fuel Pump - Hold Current 2
<input type="checkbox"/>	Fuel Pump - Hold Time Initial Value
<input type="checkbox"/>	Fuel Pump - Peak Current Initial Value
<input type="checkbox"/>	Fuel Pump - RPM for switching hold current
<input type="checkbox"/>	Fuel Pump - RPM for switching hold current hys
<input type="checkbox"/>	Fuel Pump - RPM for Switching Peak Current
<input type="checkbox"/>	Fuel Pump - RPM for Switching Peak Current hys
<input type="checkbox"/>	Fuel Pump Control - Base Angle
<input type="checkbox"/>	Fuel Pump Control - Feedback Deadband
<input type="checkbox"/>	Fuel Pump Control - Integral Factor
<input type="checkbox"/>	Fuel Pump Control - Proportional Factor
<input type="checkbox"/>	Fuel Pump Regulator Pulse Time
<input type="checkbox"/>	Fuel Pump Regulator Response Time

Live Data Parameters

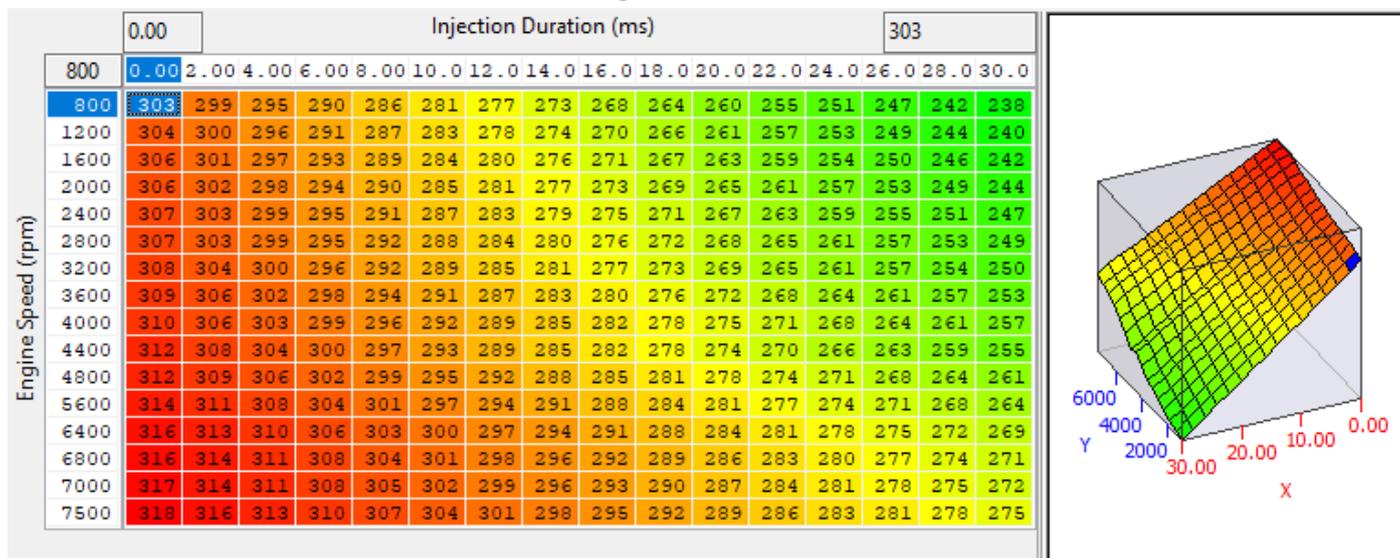
- Fuel Pressure Target (Mpa) - Fuel Rail Pressure target
- Fuel Pressure (Mpa) - Actual Fuel Pressure in High pressure fuel rail
- Fuel Pressure Sensor (mV) - Fuel Pressure sensor raw voltage
- Fuel Pump Angle Target (°)– Actual target angle for fuel pump solenoid trigger
- Fuel Pump Angle Target - Base (°) – Base map angle output value
- Fuel Pump Angle Target – Int (°) – Current integral correction angle output value
- Fuel Pump Angle Target – Prop (°) – Current Proportional angle correction value

Fuel Pressure Target / Fuel Pressure Target at Low Temp



There are two fuel pressure target maps, these are active dependant on high and low coolant temperatures. The output is in MPa and profiled for specific RPM and QH0. This value is used for the error calculation and fuel pressure correction function.

Fuel Pump Control – Base Angle

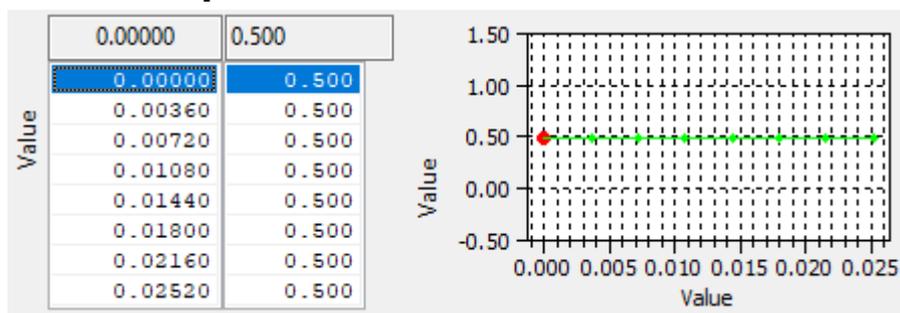


This is the crank angle at which the trigger pulse for the fuel pump solenoid is set.

- Increasing the angle reduces outflow and pressure
- Decreasing the angle increases outflow and pressure.

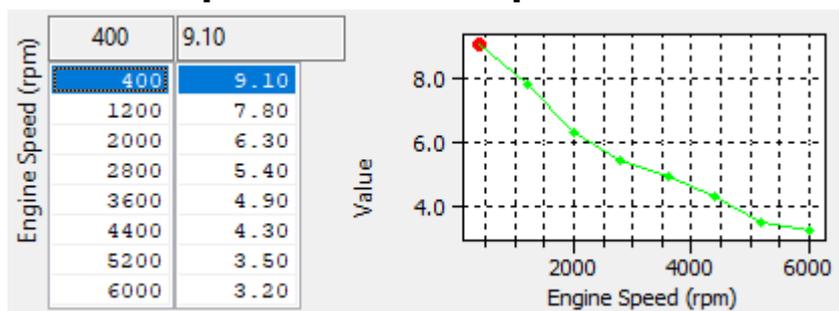
If the *Fuel Pressure* is not hitting the *Fuel Pressure Target* at the final *Fuel Pump Angle Target* displayed change this map to give more pump stroke to maintain pressure. Be aware that if the angle is set to high or low it will trigger the pump before on the inlet stroke and cause pressure issues.

Fuel Pump Control – Feedback Deadband



This is the pressure range in which the proportional and integral feedback of solenoid trigger angle will not become active, if the error is outside of 0.5 Mpa P&I correction will commence.

Fuel Pump Control – Proportional Factor

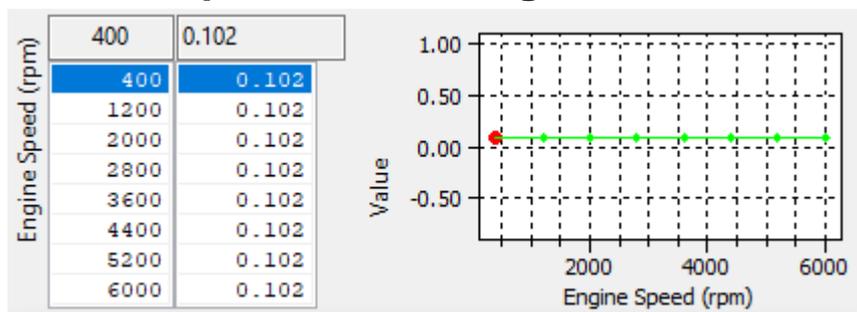


This is a proportional gain to calculate the instantaneous absolute addition to the *Fuel Pump Target* angle, based on RPM, the feedback angle is generated using the fuel pressure error value multiplied by the proportional correction amount.

$$\text{Fuel Pump Angle Target} - \text{Prop} = \text{Fuel Pump Control} - \text{Proportional Factor map output} \times (\text{Fuel Pressure} - \text{Fuel Pressure Target})$$

Increasing the factor give more instantaneous correction for the same amount of fuel pressure error

Fuel Pump Control – Integral Factor

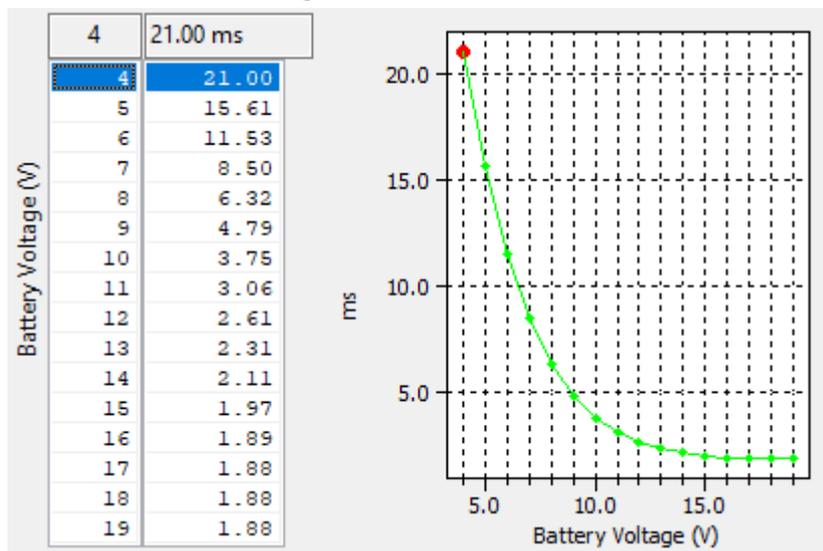


This is an integral gain factor map to calculate the cumulative addition to the *Fuel Pump Angle Target*, based on RPM, the feedback angle is generated using the fuel pressure error value multiplied by the proportional correction amount at the loop speed.

$$\text{Fuel Pump Angle Target} - \text{Int} = \text{Fuel Pump Control} - \text{Integral Factor map output} \times (\text{Fuel Pressure} - \text{Fuel Pressure Target})$$

Increasing the factor give more correction and faster responding cumulative values for the same amount of fuel pressure error.

Fuel Pump Regulator Response Time



This is the dead / lag time of the pressure control solenoid, when changing pump solenoids this must match the dead time of the new solenoid installed. Like injectors, if tuned incorrectly it will effect the closed loop pressure control systems.

Fuel Pump – Battery Voltage switching Time



At different battery voltages the ECU uses different times for switching between hold time initial values of the fuel pump solenoid. Depending on what the battery voltage is it will use the range specified on the **Fuel Pump – Hold Time Initial Value** map, see that map description for more details.

Fuel Pump – Hold Time Initial Value

2.82	ms
4.03	
6.40	
12.03	

When the battery voltage is above the top threshold of **Fuel Pump – Battery Voltage switching Time** the top row of this map is used, when between the top and middle threshold the second values are used, as per below

File	Edit	File	Edit
15.92		2.82	
11.92		4.03	
9.92		6.40	
		12.03	

Fuel Pump – Peak Current Initial Value

6	Current (A)
6	

The target current (Amps) for the Peak driving phase of the pressure control solenoid. This could be adjusted to better suit increased current demands of an upgraded pump solenoid. The two values are for mode 1 and 2 as per the hold current maps and its believed these are switched by exceeding the thresholds **Fuel Pump - RPM For switching Peak Current & Hys**.

Fuel Pump – Hold Current 1 & Fuel Pump – Hold Current 2

3	Current (A)
---	-------------

The target hold current set to drive the pressure control solenoid. Two maps are used for different modes but believed they are switched using **Fuel Pump – RPM For switching Hold Current**. This could be used to cope with the increased current demands of an upgraded pump solenoid.

Fuel Pump – RPM For switching Hold Current

12750	Engine Speed (rpm)
-------	--------------------

RPM at which the ECU changes from using **Fuel Pump – Hold Current 1** to **Fuel Pump – Hold Current 2**.

Fuel Pump - RPM For switching Hold Hys

0	Engine Speed (rpm)
---	--------------------

Hysteresis value used when evaluating the RPM threshold.

Fuel Pump – RPM For switching Peak Current

0	Engine Speed (rpm)
---	--------------------

RPM at which the ECU changes from using **Fuel Pump – Peak Current 1** to **Fuel Pump – Peak Current 2**.

Fuel Pump - RPM For switching Peak Hys

0	Engine Speed (rpm)
---	--------------------

Hysteresis value used when evaluating the RPM threshold.

Fuel Pump - Delay Time Switching Peak Current

255	Value
-----	-------

This is the time of the peak current drive for the control solenoid.

Charge Air Failsafe

Introduction

The OEM intercoolers on a VR30DDTT engine are water to air, and prone to airlocks in their coolant system after removal and installation, this creates high charge air temperatures, the OEM code offers no protection, so an engine can be quickly destroyed at higher boost levels. Adding an element of safety to tuning, a charge air to intake air temperature differential threshold has been created to limit the desired torque to reduce power until the dangerous running conditions subside.

To clear the limp mode torque limit, the ignition will need to be turned off for a few seconds and then the engine restarted or the time out option implemented.

Map List

<input type="checkbox"/> Charge Air Failsafe
<input type="checkbox"/> Charge Air Failsafe - Torque Limit
<input type="checkbox"/> Charge Air Failsafe - Min Engine Load
<input type="checkbox"/> Charge Air Failsafe - Min Engine Speed
<input type="checkbox"/> Charge Air Failsafe - Min Temp Diff
<input type="checkbox"/> Charge Air Failsafe - Timeout
<input type="checkbox"/> Charge Air Failsafe Enable

Live Data Parameters

- *Dig: Charge Air Failsafe Limiter* – An on/off parameter to show if the car is in charge air related failsafe modes.
- *Charge Air Temp* – The intake charge air temperature (post intercooler) in °C.
- *Charge Air Coolant Temperature* – The W2A intercooler water temperature in °C.
- *Intake Air Temp* – The intake charge air temperature (pre intercooler) in °C.

Operation

When enabled, the code then checks if the enable thresholds have been met as per below,

- *Charge Air Temp - Intake Air Temperature* is greater than **Charge Air Failsafe – Min Temp Diff**
- *Engine Load* is greater than **Charge Air Failsafe - Min Engine Load**
- *Engine Speed* is greater than **Charge Air Failsafe - Min Engine Speed**

when all three thresholds have been exceeded the desired torque is limited to **Charge Air failsafe – Torque Limit**.

This will drop the power output, lowering the boost and preventing engine damage.

The torque limit will stay applied until key off, or if enabled, the **Charge Air Failsafe – Timeout** time has been exceeded.

Charge Air Failsafe - Enable

<input type="checkbox"/> Enable Charge Air Failsafe
<input type="checkbox"/> Enable Timeout

Check these boxes to enable the charge air failsafe feature.

Charge Air Failsafe - Torque Limit

300 max (Nm)

This sets the maximum allowable torque when the failsafe mode is active it allows normal throttle response until the torque limit is achieved.

Charge Air Failsafe – Min Engine Load

1.20 min (load)

All Thresholds including the current engine load must be above their respective before the **Charge Air Failsafe – Torque limit** is applied.

Charge Air Failsafe – Min Engine Speed

3000 min (rpm)

All Thresholds including the engine speed RPM must be above their respective threshold to apply the **Charge Air Failsafe – Torque limit**.

Charge Air Failsafe – Min Temp Diff

40 min (°C)

All Thresholds including the Intake air to charge air temperature difference must be greater than their respective threshold before the **Charge Air Failsafe – Torque limit** is armed.

Charge Air Failsafe - Timeout

120 time (s)

If the timeout is enabled, the **Charge Air Failsafe – Torque limit** will be turned off automatically when this time has elapsed from when first triggered. If the timeout is disabled, the ignition will need to be cycled to release the **Charge Air Failsafe – Torque limit**.

Fuelling (Target & Control)

Introduction

The Infinity VR30DDTT has a complex fuelling function, the use of the direct injection enables more accurate adjustment of fuel injection quantity by injecting atomized high-pressure fuel directly into the cylinder. The amount of fuel injected (controlled by injector open time) is determined in the ECM referencing the engine running conditions which are determined by input signals (e.g. engine speed, intake air volume, fuel rail pressure and boost pressure), primarily using the crankshaft position sensor, camshaft position sensor and the mass air flow sensor.

In addition, the amount of fuel injected is adjusted to improve engine performance under various operating conditions as listed below.

Fuel increase

- During warm-up
- When starting the engine
- During acceleration
- Hot-engine operation
- When selector lever position is changed from N to D
- High-load, high-speed operation

Fuel decrease

- During deceleration
- During high engine speed operation

As part of the emissions control and engine safety function implemented in the ECM Stratified-charge Combustion or Homogeneous Combustion have been implemented.

Stratified-charge combustion is a combustion method which enables extremely lean combustion by injecting fuel in the latter half of a compression process, collecting combustible air-fuel around the spark plug, and forming fuel-free airspace around the mixture. The stratified charge can be split in up to 3 separate injection events, even during expansion strokes in some cases possibly to clean the 3 way catalyst NOx trap.

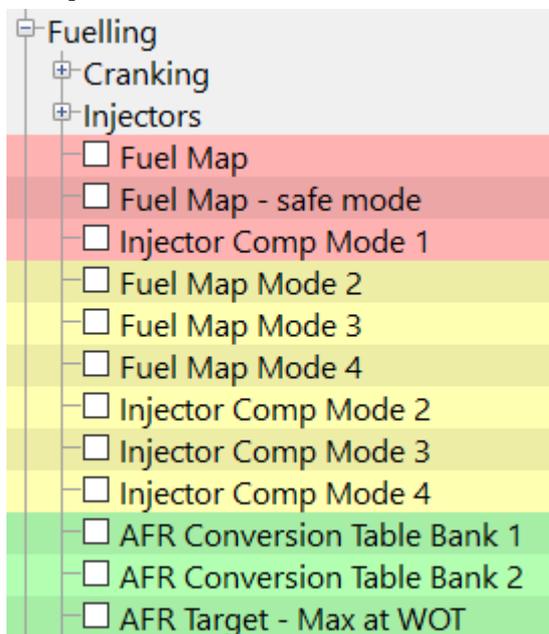
The use of the stratified-charge combustion method enables emissions-reduction when starting the engine with engine coolant temperature between 5°C (41°F) and 40°C (104°F). Right after a start with the engine cold stratified-charge combustion is used to heat up the catalyst as quick as possible.

Homogeneous combustion is a combustion method where fuel is injected during intake process so that combustion occurs in the entire combustion chamber, as is common with conventional methods. Except during start up with the engine cold, homogeneous combustion is used.

The fuel control functions on the VR30 engine we believe are per cylinder sequential (according to ignition order) self-learning and full time closed loop. Open loop fuel delivery is only used in very particular circumstances (like overrun and fail safe). The ECM uses the primary pre-turbo O2 sensors as well as the rear O2 sensors for fuelling adjustment.

There is a self learning function (short term and long term) as per all modern ECU's, long term forming a form of wear and environment change adaptation and the short term handling instantaneous pulse width adaption.

Map List

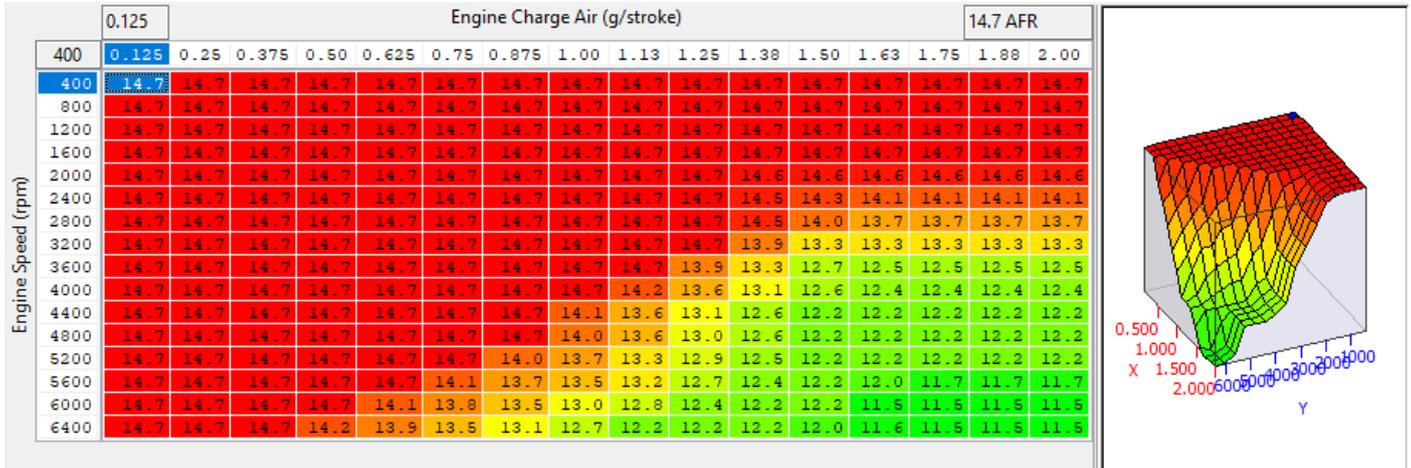


Live Data Parameters

- *AFR Average (AFR) – Bank 1 and 2 sensor values averaged*
- *AFR Average Calibrated (AFR) – Bank 1 and 2 sensor output using EcuTek Polynomial averaged*
- *AFR Bank 1 (AFR) – Bank 1 O2 sensor output as seen by the ECM*
- *AFR Bank 2 (AFR) – Bank 2 O2 sensor output as seen by the ECM*
- *AFR Bank 1 Calibrated (AFR) – Bank 1 O2 sensor output as seen by the EcuTek Polynomial*
- *AFR Bank 2 Calibrated (AFR) – Bank 2 O2 sensor output as seen by the EcuTek Polynomial*
- *AFR Sensor B1 (V) – Bank 1 O2 sensor output raw voltage*
- *AFR Sensor B2 (V) – Bank 2 O2 sensor output raw voltage*
- *AFR Sensor Heater #1 (%) – Percentage duty of Bank 1 O2 sensor heater*
- *AFR Sensor Heater #2 (%) – Percentage duty of Bank 2 O2 sensor heater*
- *AFR Target B1 (AFR) – Bank 1 target AFR*
- *AFR Target B2 (AFR) – Bank 2 target AFR*
- *Fuel Injection Angle (°)– OEM injection angle parameter*
- *Fuel Injector Duration B1(ms) – Injector open time on bank 1*
- *Fuel Injector Duration B2 (ms) – Injector open time on bank 2*
- *Fuel Injector End to Spark (ms) – Time between end of injection and ignition event.*
- *Fuel Trim Long term B1 (%) – Percentage extra injector open time applied by long term fuel correction*

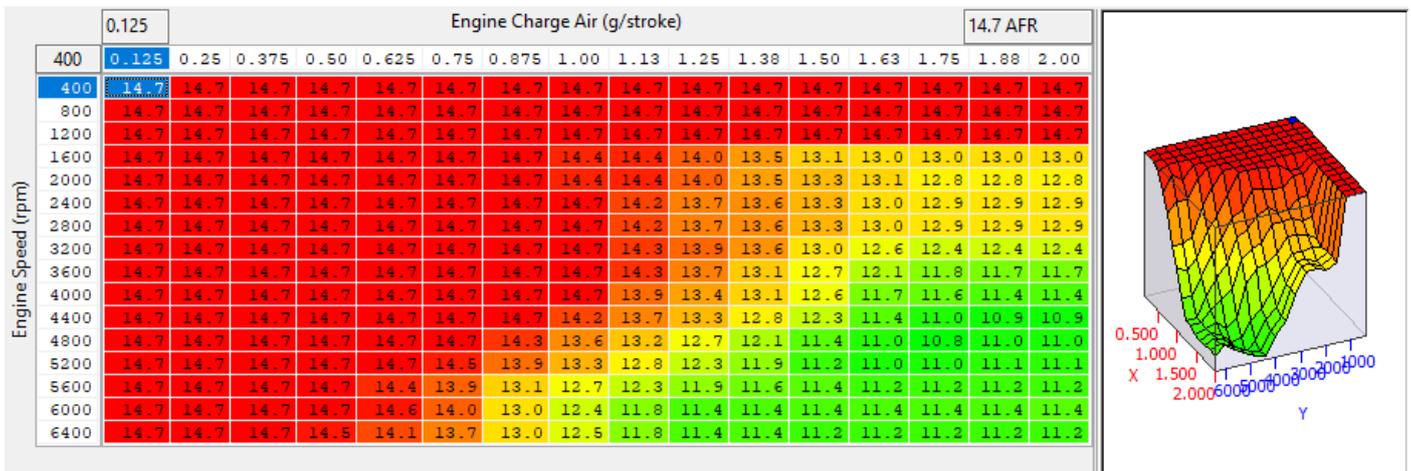
- Fuel Trim Long term B2 (%) – Percentage extra injector open time applied by long term fuel correction
- Fuel Trim Short term B1 (%) – Percentage extra injector open time applied by short term fuel correction
- Fuel Trim Short term B2 (%) – Percentage extra injector open time applied by short term fuel correction
- Injector Open Time (ms) – The injector open time of the last pulse used in the sequence
- Map Trace AFR (AFR) – Value used to map trace on fuel maps and ignition maps when colouring by AFR

Fuel Map Mode 1 - 4



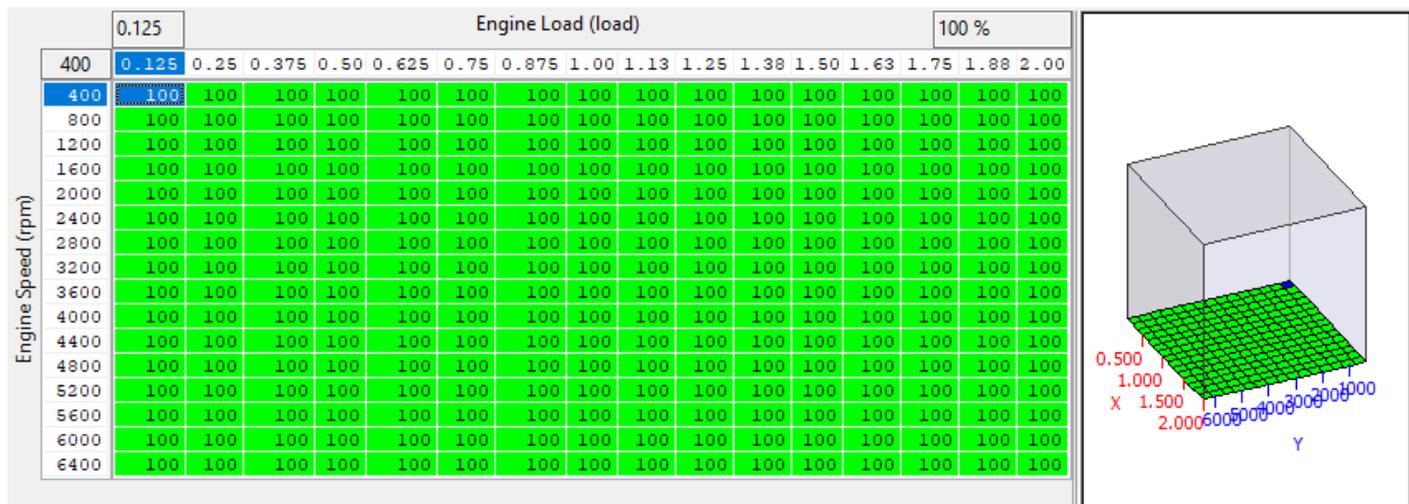
This is the target AFR the ECU chooses to run when not in lambda control modes, there are individual maps for each mode 1 to 4, these maps are equivalence ratio shown as AFR by the map editor.

Fuel Map - Safe Mode



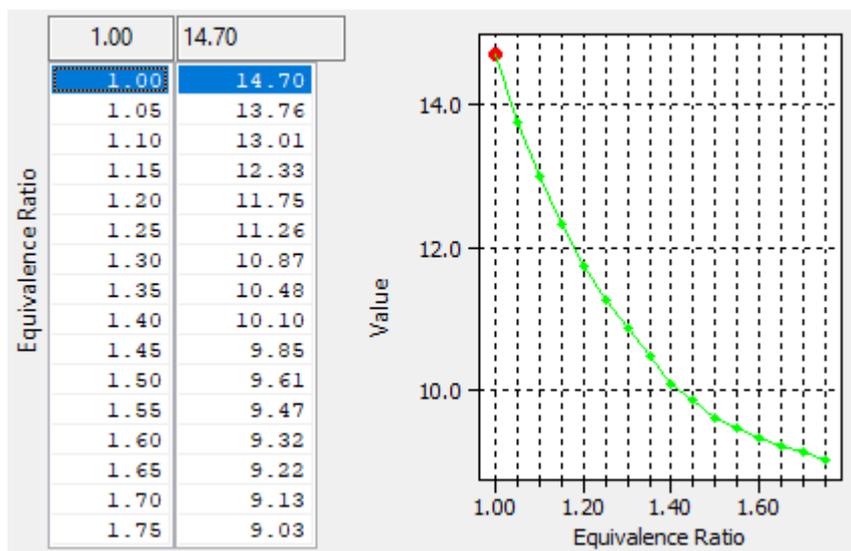
There is a safe mode map as well that we believe is used when the car senses knock events or suspects the octane rating of the fuel has changed (for example after refuelling)

Injector Comp Mode 1 - 4



The injector compensation maps work directly on the Injector magnification values so directly effect injector open time during engine operation. They are load and RPM scaled so can be used to adjust the total fuelling under certain running conditions or compensate “per mode” for different fuel densities and mass flow rates e.g. Ethanol fuels.

AFR Conversion Bank 1 & 2

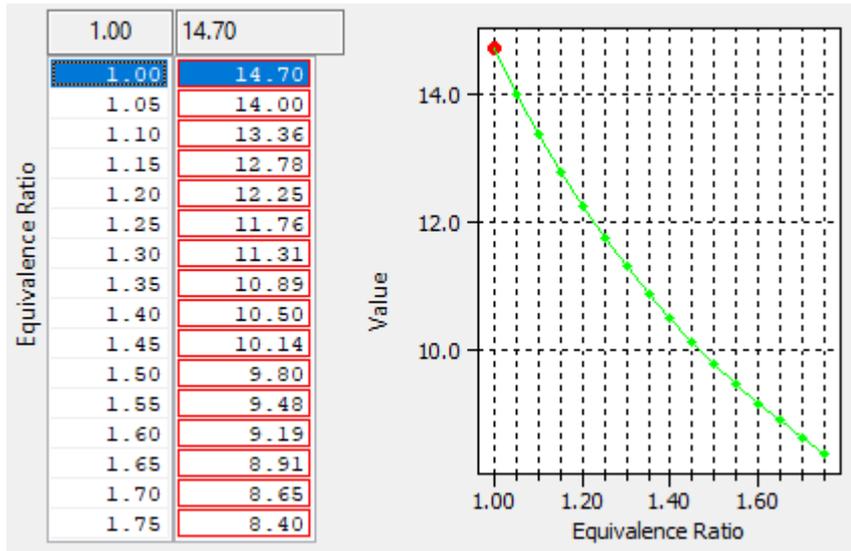


There are many different OEM fuelling target selection modes, these are for functions used when trying to achieve high efficiency closed loop stoichiometric fuelling, low temperature cat warm up, limp modes and High Load running conditions. The AFR conversion tables are an offset adjustment to the output of the fuel maps (in equivalence ratio) to convert into AFR. While the exact reason for having a changeable Eq ratio to AFR conversion is unknown we suspect it is to do with “in cylinder mixing” or safety factors.

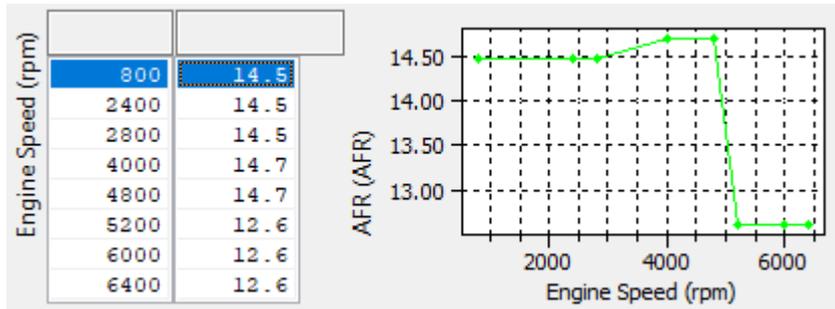
These two maps, one for each bank, are used internally by the ECU to convert values in the main fuel map to bank specific AFR targets. The units are Equivalence Ratio and can be converted to AFR by dividing 14.7 by the values in the table, for example 1.00 gives an AFR of 14.7:1 and 1.336 gives an AFR of 11:1.

By default they do not give an output identical to the input, and it is different between each bank, and they typically translate values from the fuel maps at high load to slightly richer targets. To nullify this effect, set that the data values to exactly equal the input values, but be aware that the result is that the reported AFR target and AFR logging parameter will not match when long and short term fuel trims are 100 (no trimming).

This ends up with a setting that looks like below,

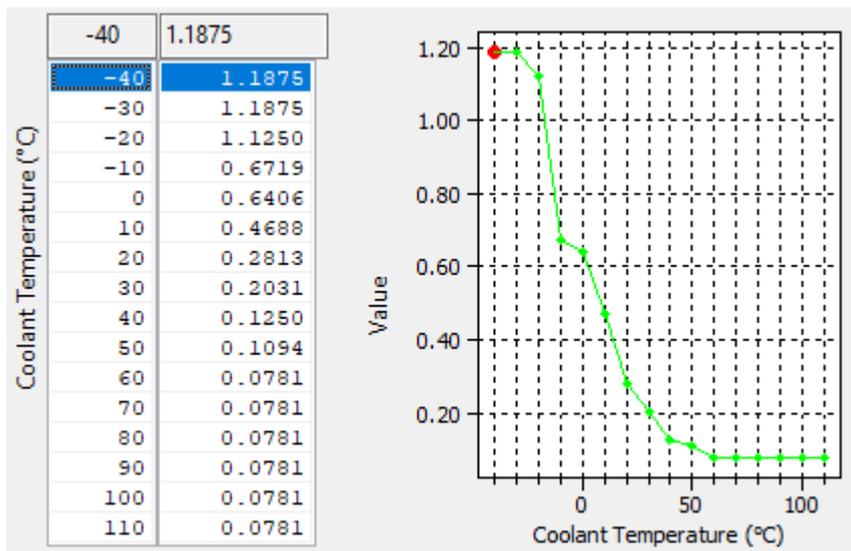


AFR Target – Max at WOT



This is the leanest AFR Target permitted for a given RPM when at WOT, it could also be called the leanest AFR for best torque. Of the values returned by this map and the main 3d fuel map(s), the richest value will be used by the ECU. Raising the values in this map prevents rich AFR Targets interfering with the intended target AFR typically used on high power cars with catalysts removed. Setting all the values in this map to 14.7 will completely disable the effect.

Cranking



There are many cranking maps and this function is currently not well understood, there are set pulse widths for cranking phases with reference to coolant temperature, and after start enrichments periods.

Injection Angle

Introduction

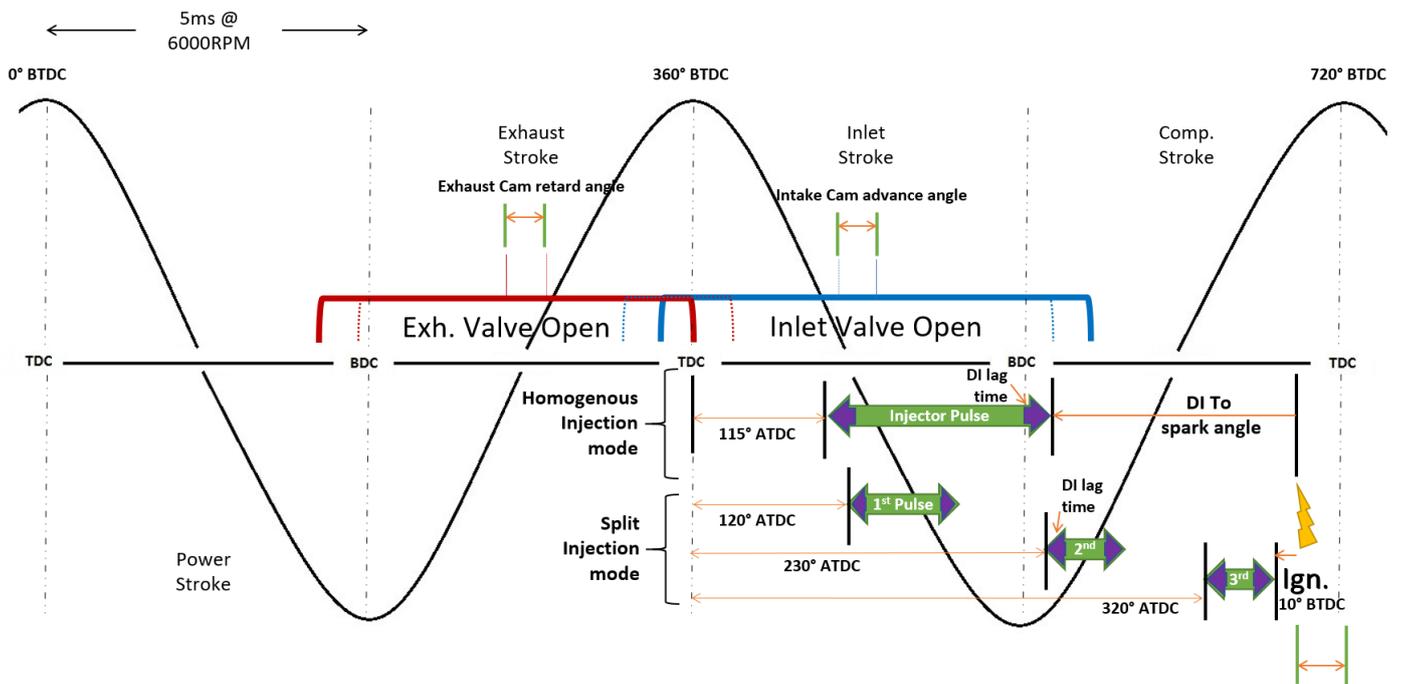
There are 4 pulse modes and 3 injection windows, these injection modes relate to which windows are used, the 4 modes are

- Homogeneous Middle Pulse Mode
- Homogeneous Pulse Mode
- Stratified Pulse Mode
- Pre-Injection Pulse Mode

The 3 windows that are used are an early, a middle, and a late window, and these have different start and end angles set in the software. The modes and windows are all decided "per injector" sequentially.

Fuel injection timing (*injection Angle 1, 2 & 3* in deg) Indicates the fuel injection timing computed by the ECM according to the input signals. There are 3 windows for injection events and it has been seen that at low RPM and peak torque these different windows are used mostly. This is to improve emissions and mitigate low speed preignition events that can occur. When using Homogenous injection strategies *Injection Angle 2* is used mostly,

NOTE: *Injection Angle* indicates degree of start of injection from TDC of intake stroke (After Top Dead Center). The diagram below shows the relationship between injection angle and combustion cycle.



Map List

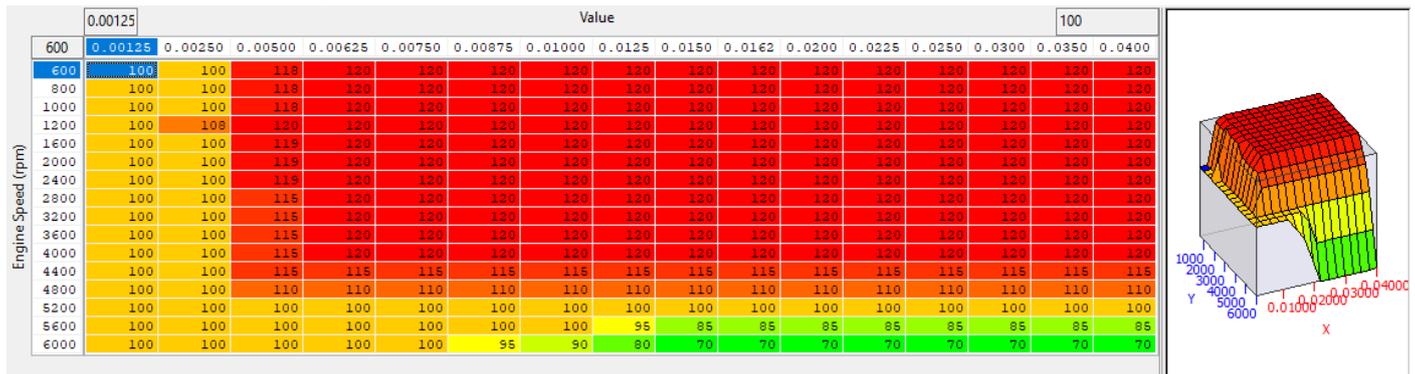
<input type="checkbox"/>	Injection Timing - pre-ignition lower limit - 799
<input type="checkbox"/>	Injection timing - Pre-ignition prevention (safe mode) - 832
<input type="checkbox"/>	Injection timing - Pre-ignition prevention - 831
<input type="checkbox"/>	Injection Timing 1 - 092
<input type="checkbox"/>	Injection Timing 1 High Power - 093
<input type="checkbox"/>	Injection Timing 1 High Power SCV closed - 094
<input type="checkbox"/>	Injection Timing 1 low temp - 098
<input type="checkbox"/>	Injection Timing 1 low temp SCV Closed - 099
<input type="checkbox"/>	Injection Timing 1 SCV Closed - 095
<input type="checkbox"/>	Injection Timing 1 v. low temp - 096
<input type="checkbox"/>	Injection Timing 1 v. low temp SCV Closed - 097
<input type="checkbox"/>	Injection Timing 1st 2 - 243
<input type="checkbox"/>	Injection Timing 1st 2 High power - 244
<input type="checkbox"/>	Injection Timing 1st 2 low temp - 245
<input type="checkbox"/>	Injection Timing 1st 3 - 252
<input type="checkbox"/>	Injection Timing 1st 3 High Power - 253
<input type="checkbox"/>	Injection Timing 1st 3 low temp - 254
<input type="checkbox"/>	Injection Timing 2nd 2 - 246
<input type="checkbox"/>	Injection Timing 2nd 2 High power - 247
<input type="checkbox"/>	Injection Timing 2nd 2 low temp - 248
<input type="checkbox"/>	Injection Timing 2nd 3 - 249
<input type="checkbox"/>	Injection Timing 2nd 3 High Power - 250
<input type="checkbox"/>	Injection Timing 2nd 3 Low Temp - 251
<input type="checkbox"/>	Injection Timing 3rd 3 - 255
<input type="checkbox"/>	Injection Timing 3rd 3 High Power- 256
<input type="checkbox"/>	Injection Timing 3rd 3 low temp - 257
<input type="checkbox"/>	Injection Timing on stratified startup - 266

These names will be changed and released in the near future.

Live Data Parameters

- *Injection Angle 1 (°) – Start of Injection angle of number 1 injection pulse*
- *Injection Angle 2 (°) – Start of Injection angle of number 2 injection pulse*
- *Injection Angle 3 (°) – Start of Injection angle of number 3 injection pulse*
- *Injection Pulsewidth 1 Cyl 1 (ms) – Injection Pulsewidth of 1st pulse on Cyl #1 injection*
- *Injection Pulsewidth 1 Cyl 2 (ms) – Injection Pulsewidth of 1st pulse on Cyl #2 injection*
- *Injection Pulsewidth 1 Cyl 3 (ms) – Injection Pulsewidth of 1st pulse on Cyl #3 injection*
- *Injection Pulsewidth 1 Cyl 4 (ms) – Injection Pulsewidth of 1st pulse on Cyl #4 injection*
- *Injection Pulsewidth 1 Cyl 5 (ms) – Injection Pulsewidth of 1st pulse on Cyl #5 injection*
- *Injection Pulsewidth 1 Cyl 6 (ms) – Injection Pulsewidth of 1st pulse on Cyl #6 injection*
- *Injection Pulsewidth 2 Cyl 1 (ms) – Injection Pulsewidth of 2st pulse on Cyl #1 injection*
- *Injection Pulsewidth 2 Cyl 2 (ms) – Injection Pulsewidth of 2st pulse on Cyl #2 injection*
- *Injection Pulsewidth 2 Cyl 3 (ms) – Injection Pulsewidth of 2st pulse on Cyl #3 injection*
- *Injection Pulsewidth 2 Cyl 4 (ms) – Injection Pulsewidth of 2st pulse on Cyl #4 injection*
- *Injection Pulsewidth 2 Cyl 5 (ms) – Injection Pulsewidth of 2st pulse on Cyl #5 injection*
- *Injection Pulsewidth 2 Cyl 6 (ms) – Injection Pulsewidth of 2st pulse on Cyl #6 injection*
- *Injection Pulsewidth 3 Cyl 1 (ms) – Injection Pulsewidth of 3rd pulse on Cyl #1 injection*
- *Injection Pulsewidth 3 Cyl 2 (ms) – Injection Pulsewidth of 3rd pulse on Cyl #2 injection*
- *Injection Pulsewidth 3 Cyl 3 (ms)– Injection Pulsewidth of 3rd pulse on Cyl #3 injection*
- *Injection Pulsewidth 3 Cyl 4 (ms) – Injection Pulsewidth of 3rd pulse on Cyl #4 injection*
- *Injection Pulsewidth 3 Cyl 5 (ms) – Injection Pulsewidth of 3rd pulse on Cyl #5 injection*
- *Injection Pulsewidth 3 Cyl 6 (ms) – Injection Pulsewidth of 3rd pulse on Cyl #6 injection*

Injection Timing



As described in the introduction, the injection timing maps set the angle after TDC of exhaust/intake stroke. The output values are in crank degrees and they are set by engine speed and a calculated load condition using multiple variables to generate the output value.

There are many different modes in which different injection windows are used and different injector “start of pulse” angles are chosen, these are for High power low temperature or SCV position.

Injection Characteristics

Introduction

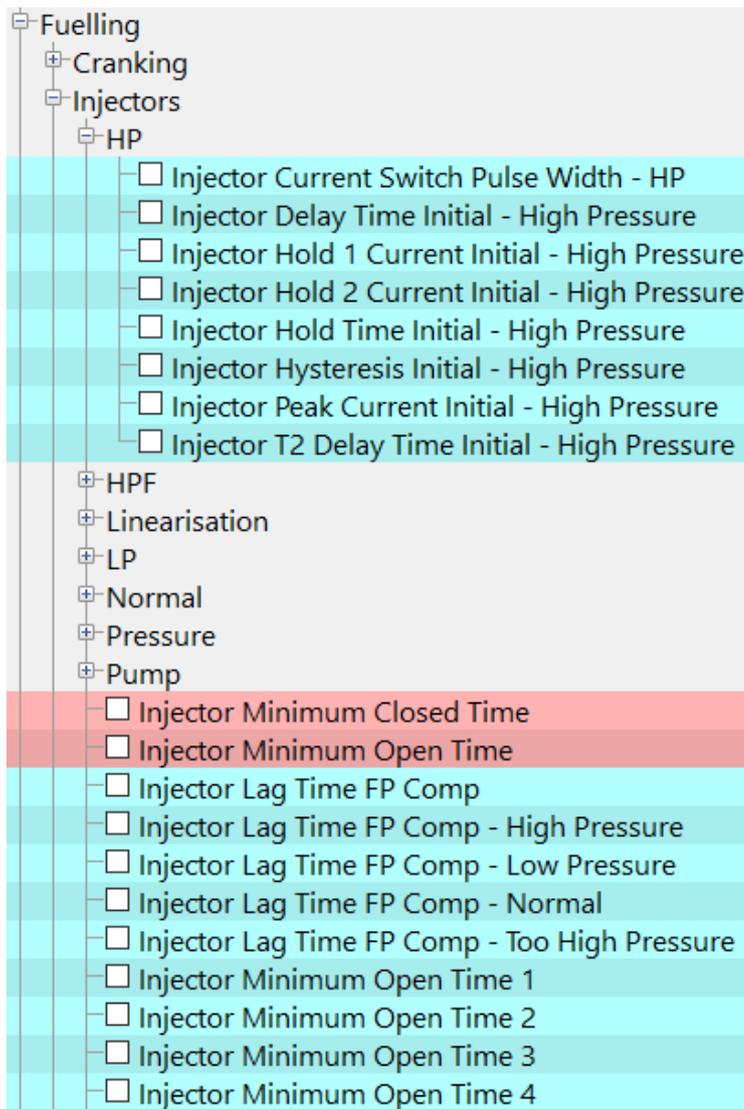
Direct injection (DI) characteristics are quite complex but can be broken down into several controlling functions. The injectors are driven at a high voltage for a short time using the high-pressure fuel supply to achieve the required quantity in a short period. The ECM is equipped with an injector driver unit that drives the fuel injector at approximately 65 V (maximum) to increase the speed of injector opening thus increasing the operating window available.

Injector characteristics are split into pressure groups like the following.

- High Pressure failure (pressure to high)
- High pressure
- Normal pressure
- Low Pressure

Each pressure mode has its own set of injector characteristic maps (including peak and hold currents, switching times and delays). The opening time is calculated using these values which are further split into the phase of the injector driving cycle. There are 2 main phases, a peak current phase to drive the injector open and a hold current phase to keep it open. The final pulse width is subject to low pulse width linearization maps and minimum open times.

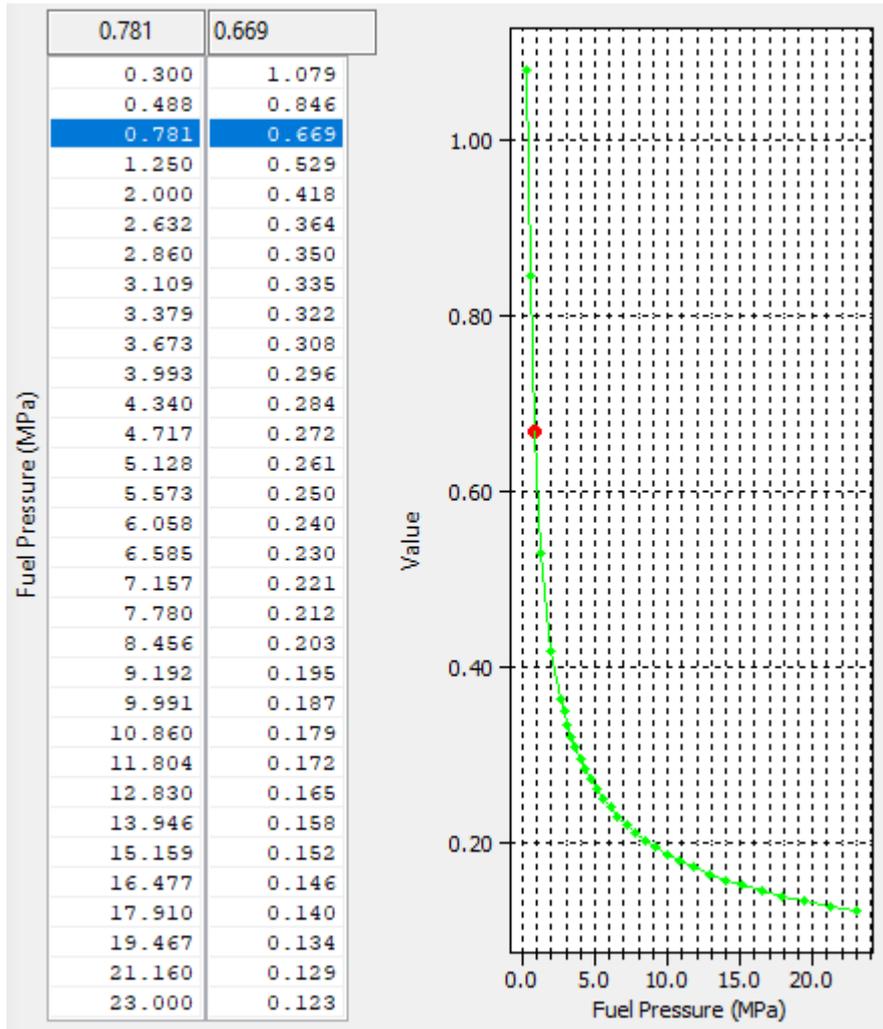
Map List



Live Data Parameters

- *Injection Pulsewidth 1 Cyl 1 (ms)* – Injection Pulsewidth of 1st pulse on Cyl #1 injection
- *Injection Pulsewidth 1 Cyl 2 (ms)* – Injection Pulsewidth of 1st pulse on Cyl #2 injection
- *Injection Pulsewidth 1 Cyl 3 (ms)* – Injection Pulsewidth of 1st pulse on Cyl #3 injection
- *Injection Pulsewidth 1 Cyl 4 (ms)* – Injection Pulsewidth of 1st pulse on Cyl #4 injection
- *Injection Pulsewidth 1 Cyl 5 (ms)* – Injection Pulsewidth of 1st pulse on Cyl #5 injection
- *Injection Pulsewidth 1 Cyl 6 (ms)* – Injection Pulsewidth of 1st pulse on Cyl #6 injection
- *Injection Pulsewidth 2 Cyl 1 (ms)* – Injection Pulsewidth of 2nd pulse on Cyl #1 injection
- *Injection Pulsewidth 2 Cyl 2 (ms)* – Injection Pulsewidth of 2nd pulse on Cyl #2 injection
- *Injection Pulsewidth 2 Cyl 3 (ms)* – Injection Pulsewidth of 2nd pulse on Cyl #3 injection
- *Injection Pulsewidth 2 Cyl 4 (ms)* – Injection Pulsewidth of 2nd pulse on Cyl #4 injection
- *Injection Pulsewidth 2 Cyl 5 (ms)* – Injection Pulsewidth of 2nd pulse on Cyl #5 injection
- *Injection Pulsewidth 2 Cyl 6 (ms)* – Injection Pulsewidth of 2nd pulse on Cyl #6 injection
- *Injection Pulsewidth 3 Cyl 1 (ms)* – Injection Pulsewidth of 3rd pulse on Cyl #1 injection
- *Injection Pulsewidth 3 Cyl 2 (ms)* – Injection Pulsewidth of 3rd pulse on Cyl #2 injection
- *Injection Pulsewidth 3 Cyl 3 (ms)* – Injection Pulsewidth of 3rd pulse on Cyl #3 injection
- *Injection Pulsewidth 3 Cyl 4 (ms)* – Injection Pulsewidth of 3rd pulse on Cyl #4 injection
- *Injection Pulsewidth 3 Cyl 5 (ms)* – Injection Pulsewidth of 3rd pulse on Cyl #5 injection
- *Injection Pulsewidth 3 Cyl 6 (ms)* – Injection Pulsewidth of 3rd pulse on Cyl #6 injection
- *Injector Open Time (ms)* – The injector open time of the last pulse used in the sequence

Injector Magnification



The injector flow rate differs at different fuel pressures the response time of the injector due to pressure can be modified by adjusting using the injector magnification map. This is also what the injector compensation values work on.

- Increasing the value will increase the calculated fuel amount required
- decreasing the values will decrease the amount of fuel calculated for the current conditions

Injector Lag Time

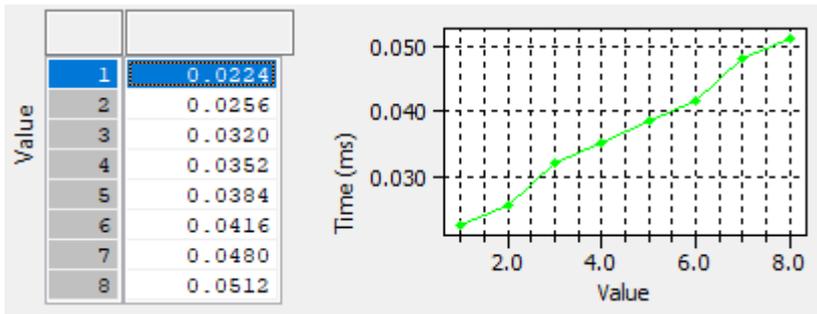
The OEM injector lag time (latency) is not defined like a typical injector, it is set to 0 and then the compensation tables used to determine the correct lag time

Injector Minimum Open Time

The OEM injector lag time (latency) is not defined like a typical injector, it is set to 0 and then the compensation tables are used to determine the correct lag time

Injector Lag Time FP compensation

- Injector Lag Time FP Comp
- Injector Lag Time FP Comp - High Pressure
- Injector Lag Time FP Comp - Low Pressure
- Injector Lag Time FP Comp - Normal
- Injector Lag Time FP Comp - Too High Pressure



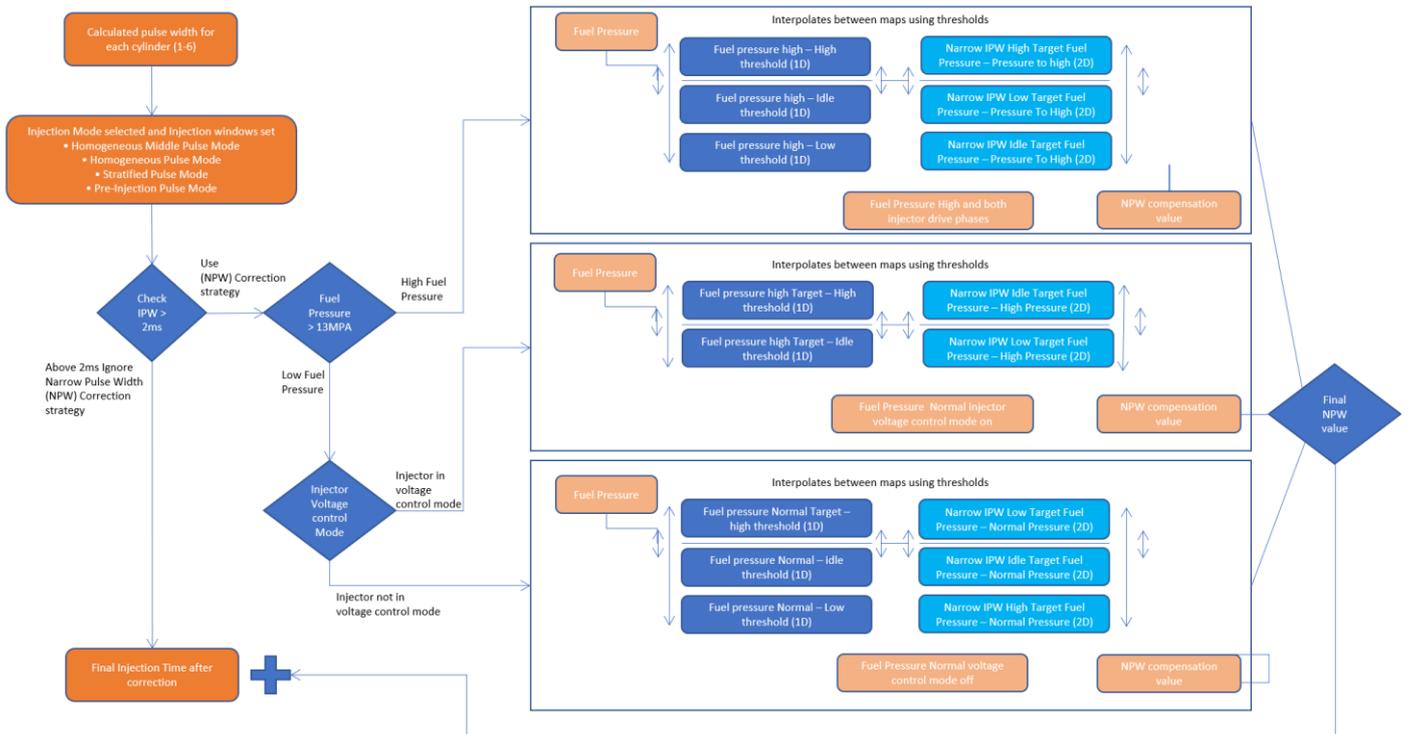
The axis of this map is fuel pressure and the output is milliseconds, these are added to the 0ms base time to form a lag time value.

Injector Narrow Pulse-width Linearization Compensation

- Linearisation
- Fuel Pressure High - High Threshold
 - Fuel Pressure High - Idle Threshold
 - Fuel Pressure High - Low Threshold
 - Fuel Pressure High Target - High Threshold
 - Fuel Pressure High Target - Idle Threshold
 - Fuel Pressure Normal - Idle Threshold
 - Fuel Pressure Normal - Low Threshold
 - Fuel Pressure Normal Target - High Threshold
 - Narrow IPW High Target Fuel Pressure - Normal Pressure
 - Narrow IPW High Target Fuel Pressure - Pressure too high
 - Narrow IPW Idle Target Fuel Pressure - High Pressure
 - Narrow IPW Idle Target Fuel Pressure - Normal Pressure
 - Narrow IPW Idle Target Fuel Pressure - Pressure too high
 - Narrow IPW Low Target Fuel Pressure - High Pressure
 - Narrow IPW Low Target Fuel Pressure - Normal Pressure
 - Narrow IPW Low Target Fuel Pressure - Pressure too high

Direct Injectors do have non-linearity characteristics at low pulse widths like Port injectors do. The Low Pulse width linearization maps are split into fuel rail pressure modes and injector drive current phases.

The chart below explains the map functions, they will only need to be adjusted if aftermarket injectors are fitted.

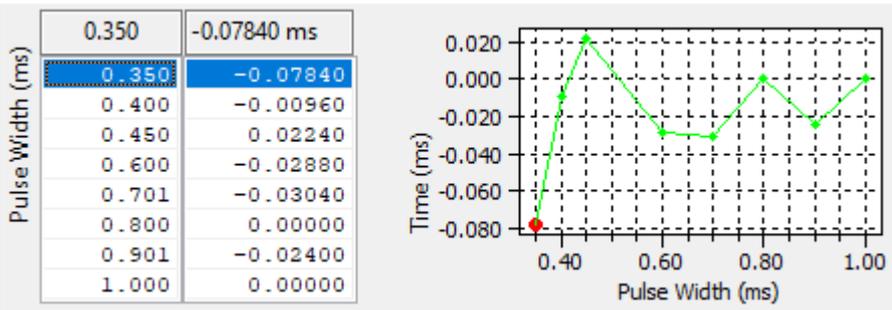


Fuel pressure high Target – Idle threshold (1D)



These 1D values are used to interpolate. They are compared to the current *Fuel Pressure* value and the difference between the respective threshold values. The difference sets the interpolation factor between the 2D **Narrow IPW Target Fuel Pressure – Pressure** maps as per the diagram above. These values will not need to be changed unless the injectors have been upgraded, the injector supplier should give changes to these values if required.

Narrow IPW Idle Target Fuel Pressure – High Pressure



These tables and the similar tables use the interpolation amounts of the 1D pressure thresholds to set the desired addition to pulse width. There are 2 or three maps per mode shown in the diagram above. They have initial injector open time as the input and output a value to add to this current injector time. These values will not need to be changed unless the injectors have been upgraded, the injector supplier should give changes to these values if required.

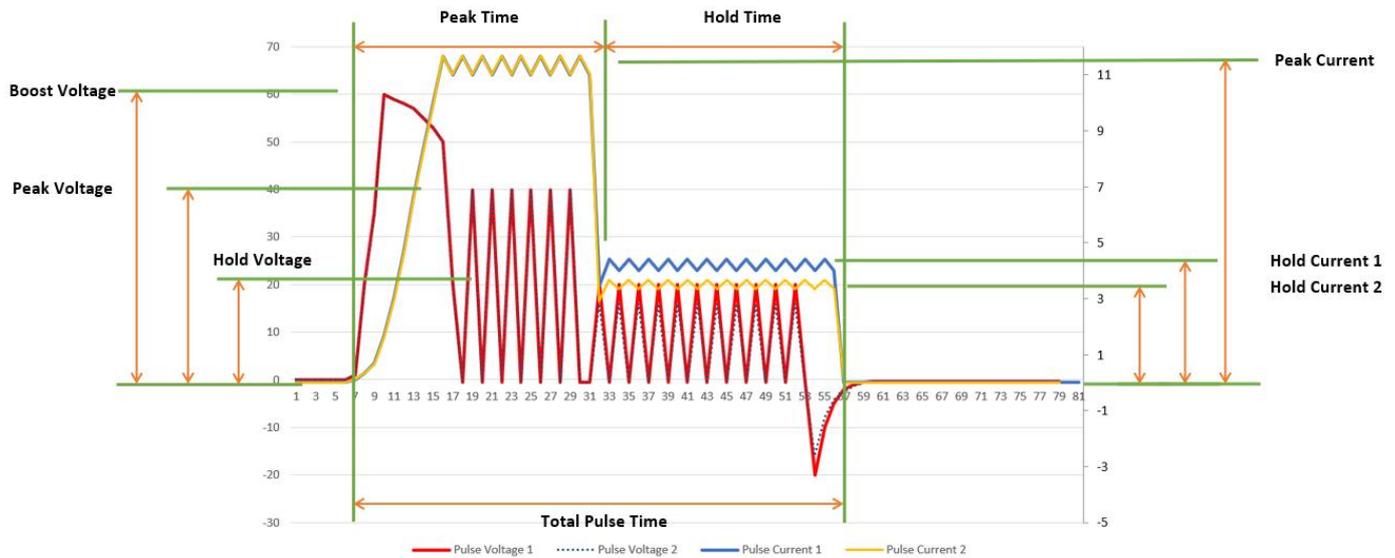
Injector Current Characterisation

Introduction

The injectors are driven in a peak and hold fashion per fuel pressure mode, there are individual times currents and delays involved for each of these modes, the modes are

- High Pressure Failure
- High Pressure
- Normal Pressure
- Low Pressure

The current drive pattern is the same as most other injector drivers and is roughly represented below.



The pressure mode map list consists of the maps below, there is a tree for each pressure mode.

HP

- Injector Current Switch Pulse Width - HP
- Injector Delay Time Initial - High Pressure
- Injector Hold 1 Current Initial - High Pressure
- Injector Hold 2 Current Initial - High Pressure
- Injector Hold Time Initial - High Pressure
- Injector Hysteresis Initial - High Pressure
- Injector Peak Current Initial - High Pressure
- Injector T2 Delay Time Initial - High Pressure

Pressure thresholds

Fuel Pressure (MPa)

Threshold for Fuel pressure being too high, the pump current is then controlled accordingly.

Injector Current Switch Pulse Width

Pulse Width (ms)

Initial Peak time switch point when the injector drive switch from peak to hold mode.

Injector Delay Time initial

Time (ms)

Initial delay timer for the total pulse to start

Injector Hold 1 Current Initial

Hold Current (A)

The target hold current for injection mode 1

Injector Hold 2 Current Initial

Hold Current (A)

The target hold current for injection mode 2

Injector Hold Time Initial

Time (ms)

The initial time of the hold current phase. If the total pulse duration is not long enough hold pulse won't be used

Injector Hysteresis Initial

Hysteresis Current (A)

Hysteresis value for PWM control when the current drops below this the voltage is increased again.

Injector Peak Current Initial

Peak Current (A)

The target peak current during the peak drive phase

Injector T2 Delay Time Initial

Delay Time (ms)

Hold delay time for injection mode 2

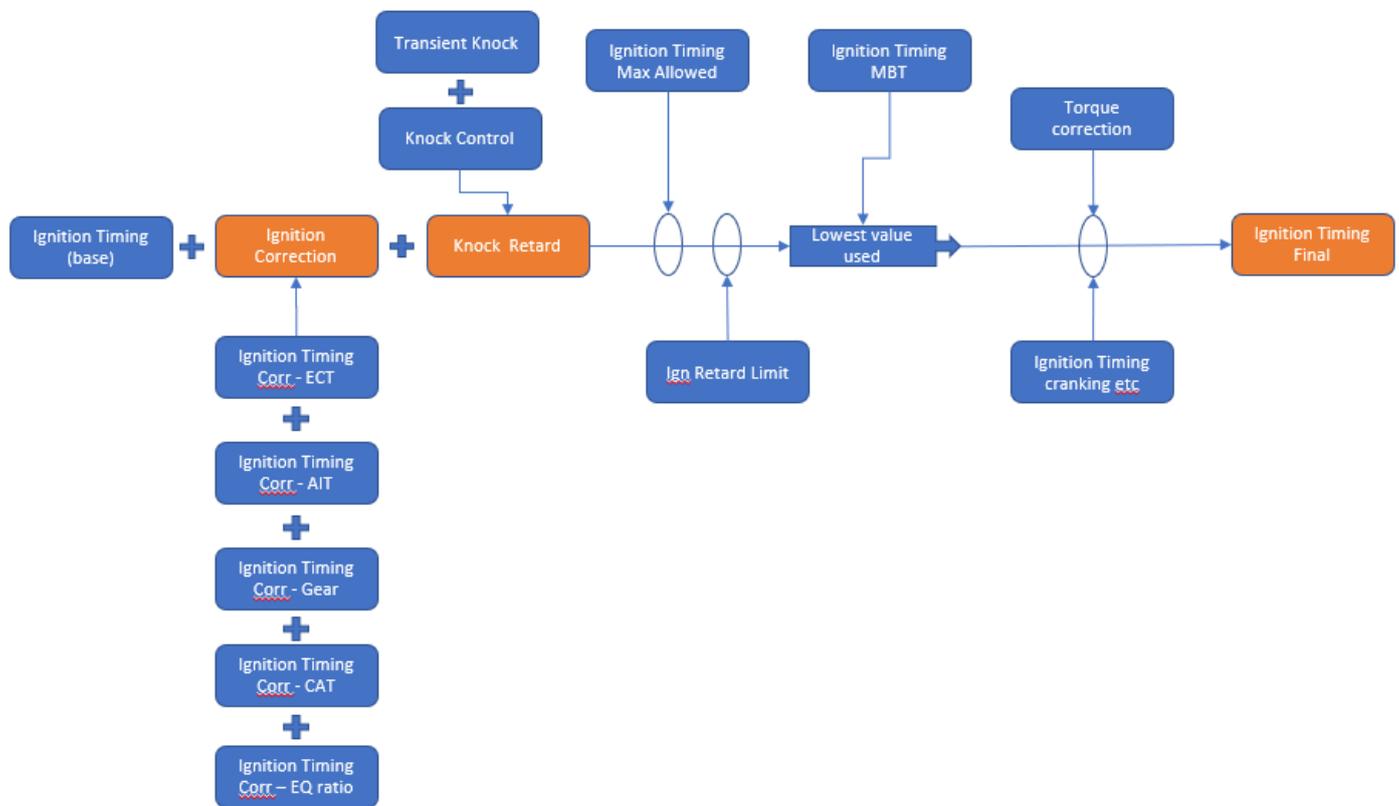
Ignition Timing

Introduction

The OEM ignition timing strategy is very good when applied to a stock car but difficult and restrictive to tune for high power applications. RaceROM adds easy to use larger maps with high precision load input axis for improved control and range. Supporting maps are also added for further safety.

The VR30DDTT platform uses a Maximum Best Torque (MBT) timing map, a base map (knock limited) and an ignition timing maximum allowed map to determine the base timing, it will choose the lowest value of the Base MBT or max map and then apply the engine conditions corrections and the knock detection correction amounts.

There is a safe mode (low octane) map that is switched to if the car enters a limp mode (DTC's) or high knock levels have been sustained for a set period, it may also switch on a refuelling event, but this is yet to be confirmed. This diagram below illustrates the control function, it doesn't include all of the maps and parameters of the function but the major inputs are included,



Live Data Parameters

- Ignition Timing Base (°) – Current base ignition timing in degrees BTDC, negative means ATDC
- Ignition Timing Base lookup (°) – Current ignition timing map output in degrees BTDC, negative means ATDC
- Ignition Charge air correction (°) – Current ignition timing correction for CAT degrees
- Ignition Final (°) – Current actual ignition timing in degrees BTDC, negative means ATDC
- Ignition MBT (°) – Calculated MBT ignition timing in degrees BTDC for use in Torque Calcs and max Limits
- Ignition Timing (°) – Current actual ignition timing in degrees BTDC, negative means ATDC
- Ignition Timing Correction (°) – Ignition timing correction amount
- Knock Retard (°) – Offset due to knock, negative is retard, positive is dynamic advance on GEN 2

Map List

- Ignition Timing
 - Correction
 - Ignition Timing Correction - Charge Air Multiplier
 - Ignition Timing - Charge Air Correction
 - Ignition Timing - Per Gear Correction
 - Ignition Timing Corr - Coolant Temp Coefficient
 - Ignition Timing Corr - Coolant Temp Threshold
 - Ignition Timing Corr - Intake Air Temp Coefficient
 - Ignition Timing Corr - Intake Air Temp Reference
 - Ignition Timing Correction - Equivalence Ratio
 - Ignition Timing Correction - Per Gear Threshold
 - Cranking
 - Idle
 - Knock Control
 - Knock Control on/off
 - Knock Retard Limiter
 - Knock Sensitivity 1
 - Knock Sensitivity 2
 - Ignition Timing
 - Ignition Timing - Safe Mode
 - Ignition Timing - Max Allowed
 - Ignition Timing - Max Allowed Mode 2
 - Ignition Timing - Max Allowed Mode 3
 - Ignition Timing - Max Allowed Mode 4
 - Ignition Timing Mode 2
 - Ignition Timing Mode 3
 - Ignition Timing Mode 4
 - Ignition MBT 1 SCV Closed
 - Ignition MBT 1 SCV Open
 - Ignition MBT 2 SCV Closed
 - Ignition MBT 2 SCV Open
 - Ignition Retard - Torque Reduction
 - Ignition Timing retard limit
 - Ignition Timing retard limit
 - Ignition Timing retard limit
 - Ignition Timing retard limit

Ignition Timing Mode1 (Mode 2, Mode 3 & Mode 4)

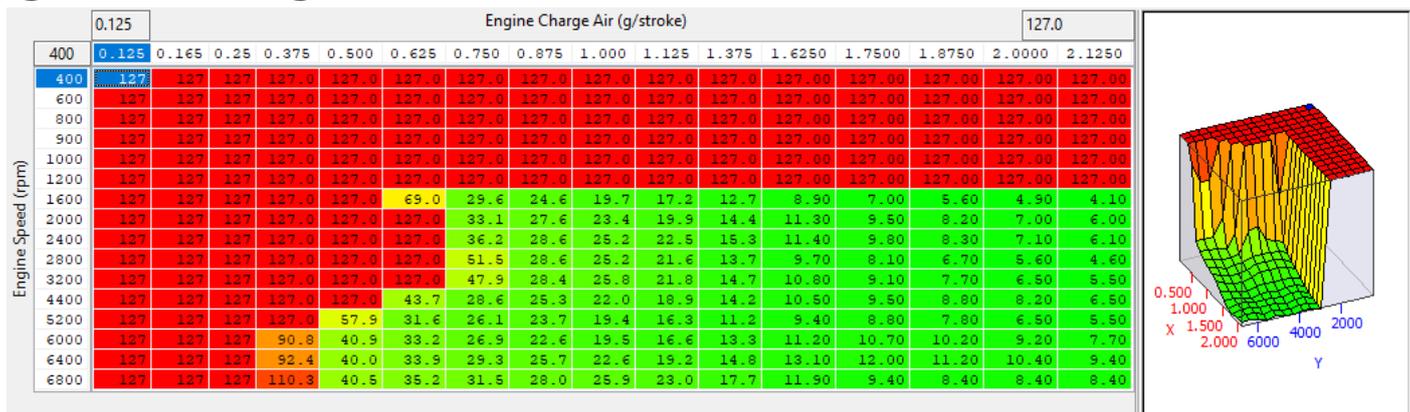


Four maps, one for each mapswitch mode providing an easy to understand and tune base ignition value in degrees BTDC. They provide increased precision and headroom for the load axis and increased RPM breakpoints. It's possible to create multiple maps and use map switching to cycle between each map for testing.

The numbers in these maps may not equal the final timing value as it will be subject to RaceROM corrections, knock control, dynamic advance and other OEM timing corrections.

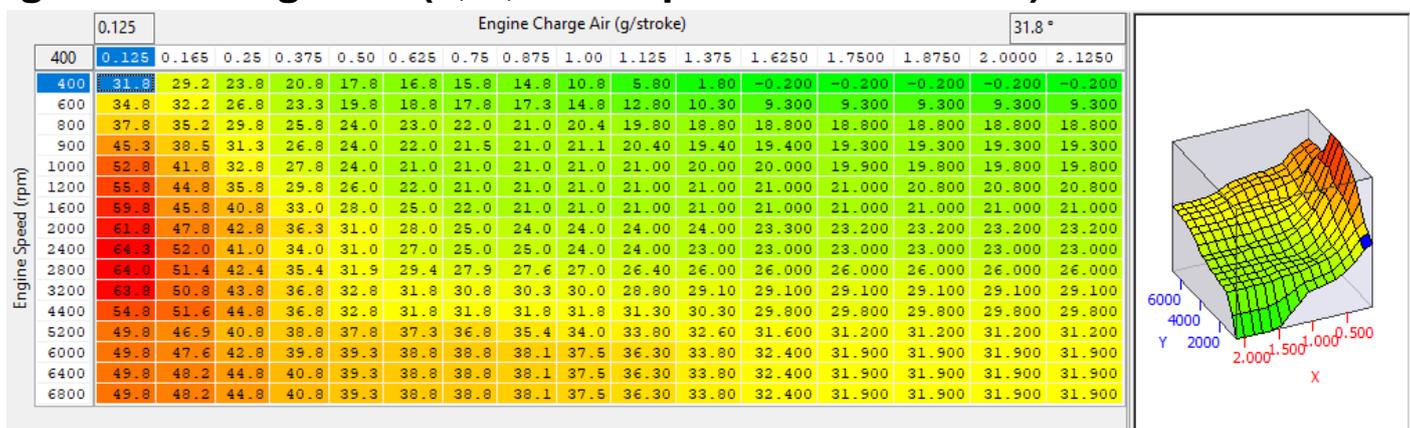
These maps are not employed in overrun and idle conditions where the OEM ignition control is used.

Ignition Timing – Max Allowed



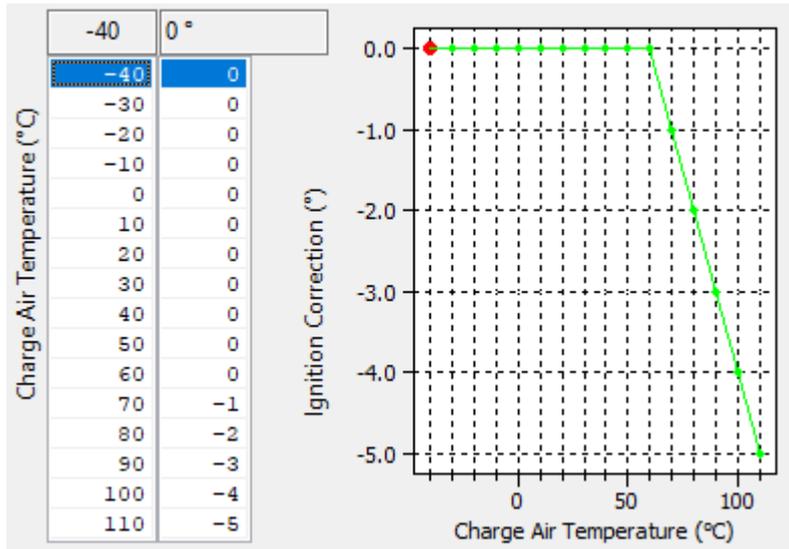
This is the Max allowed ignition timing, it is applied after the base map and corrections but before the torque reduction functions. It will cap the amount of corrections that can be applied ensuring sensible ignition values if sensors misread.

Ignition timing MBT (1, 2, SCV Open & SCV closed)



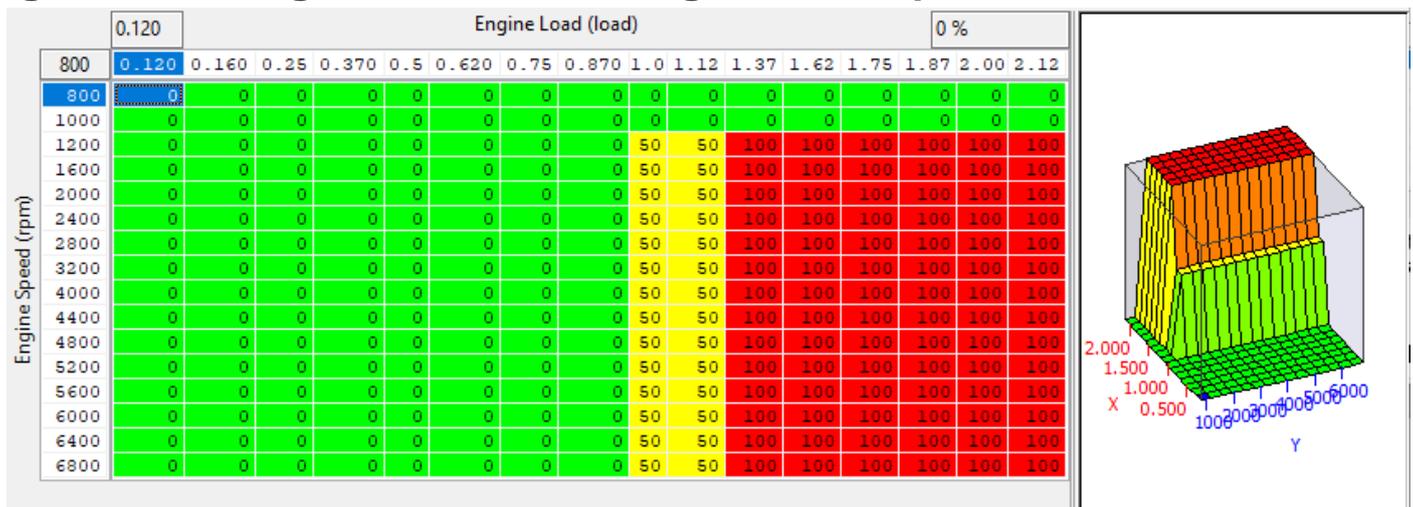
This is the calibrated Maximum Best Torque (MBT) timing for the engine in its OEM form, the timing will be limited to this value if the requested timing is above this. You should not need to go above this timing value.

Ignition Timing - Charge Air Correction



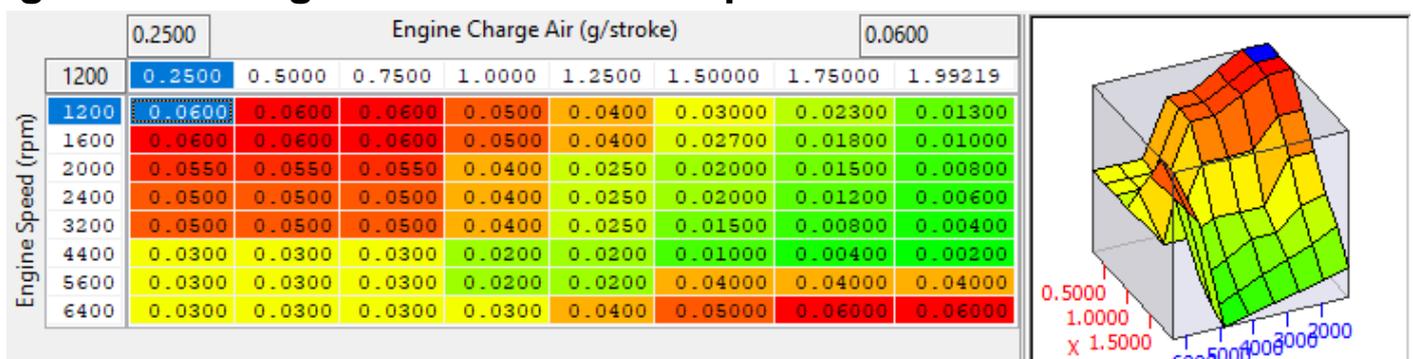
Ignition advance can be trimmed for increased charge air temperature using this map.

Ignition Timing Correction - Charge Air Multiplier



Ignition Timing Correction - Charge Air Correction value can be modified relative to RPM and engine load using this map. It would be normal to reduce advance in higher gears at high RPM or at an RPM sensitive to detonation.

Ignition Timing Corr – Coolant Temp Coefficient



An ignition timing offset based on the difference between *Coolant Temperature* and **Ignition Timing Corr – Coolant Temp Threshold** this can be used to retard or advance the ignition for different coolant temperatures. The final correction amount due to coolant temperature is calculated using the following formula.

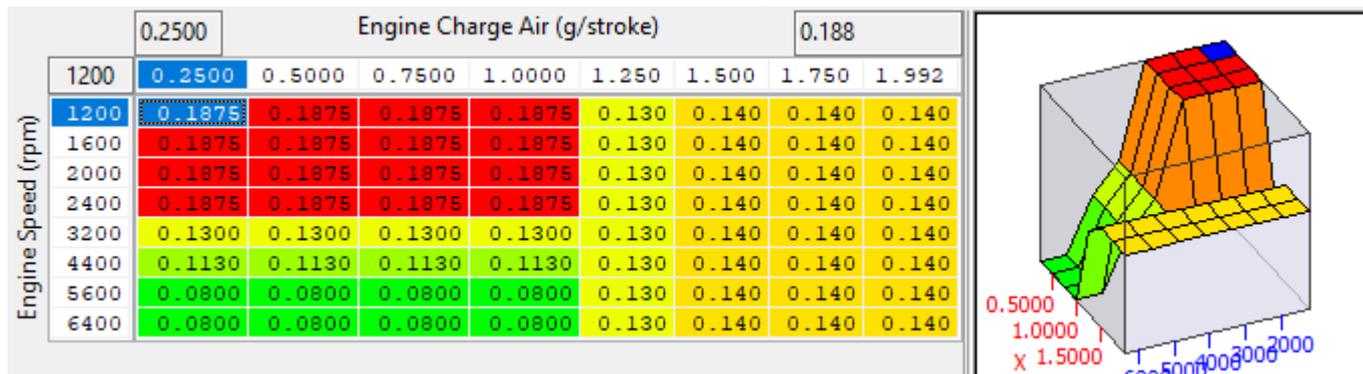
$$\text{Coolant Temp Correction amount} = (\text{ECT threshold} - \text{current ECT}) \times \text{Coolant Temp Coefficient}$$

Ignition Timing Corr – Coolant Temp Threshold

86	Value
----	-------

This is the value used in the formula to calculate the “difference” value that is multiplied by the RPM and the load scale map **Ignition Timing Corr – Coolant Temp Coefficient**,

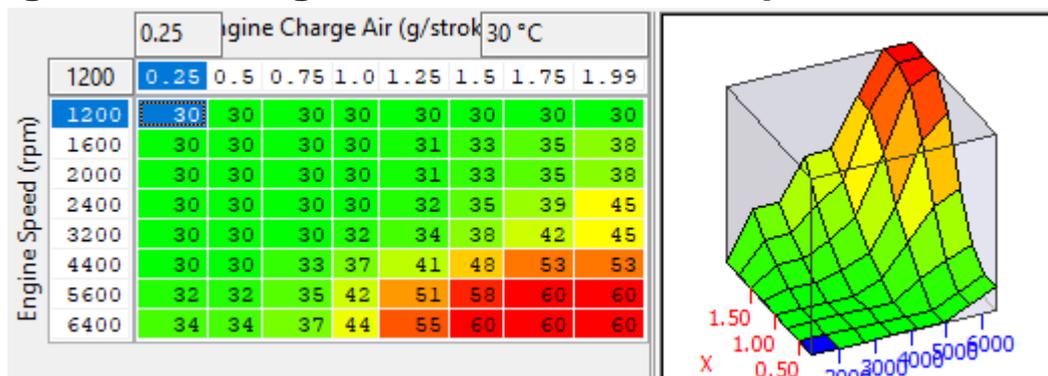
Ignition Timing Corr – Intake Air Temp Coefficient



A modifier for ignition timing offset based on the difference between *Intake Air Temperature* and **Ignition Timing Corr – Intake Air Temp Reference** and can be used to retard or advance the ignition for different intake air temperatures. The final correction amount due to IAT is calculated using the following formula.

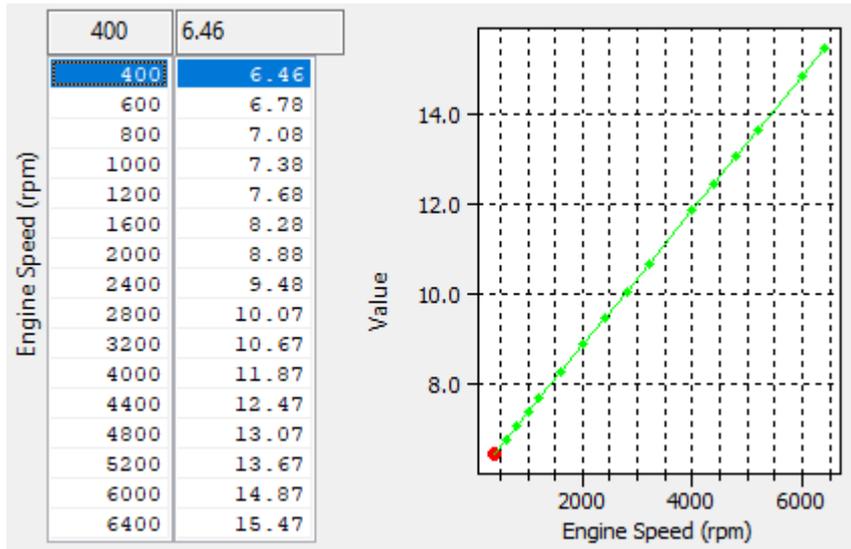
$$\text{IAT Correction amount} = (\text{IAT Reference} - \text{current IAT}) \times \text{IAT Temp Coefficient}$$

Ignition Timing Corr – Intake Air Temp Reference



This map sets the reference value used by the multiplier map **Ignition Timing Corr – Intake Air Temp Coefficient** it is essentially an expected charge air temperature map for different engine speeds and load. This OEM strategy combined with RaceROM’s charge air temperature correction method should be able to account for all air temperatures.

Ignition Timing Corr – Equivalence Ratio



This map multiplies the difference between Lambda 1 and the current lambda value and adds this to the correction calculations.

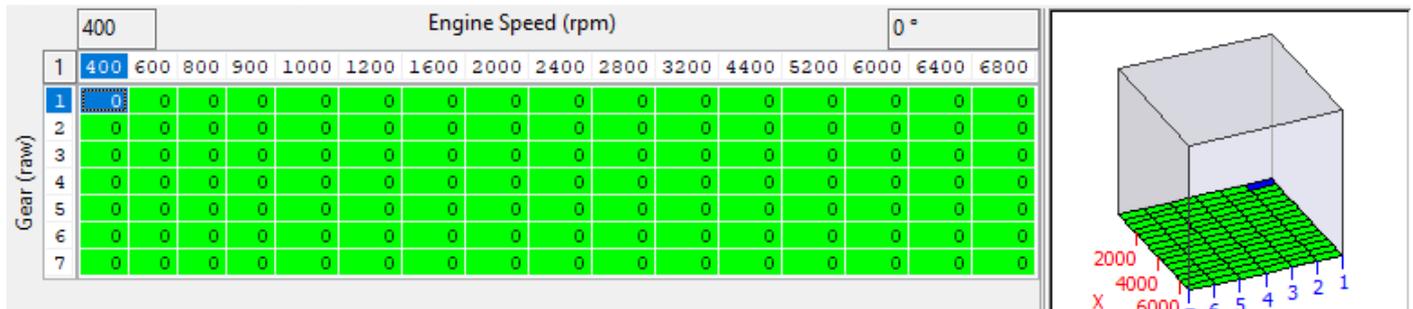
$$Eq \text{ Ratio Correction amount} = (\lambda_{stoich} - \text{current } \lambda) \times \text{Equivalence Ratio Corr map output}$$

Ignition Timing Corr – Per Gear Threshold



The load value (g/stroke) at which the per gear corrections become active.

Ignition Timing - Per Gear Correction



An amount of ignition retard (or addition) that is applied dependant on current gear and RPM. It is only applied after the load threshold has been exceeded. This can be used to compensate for the increased loading and heat generated in higher gears/high speed.

Knock Control

The knock retard systems in the VR30DDTT follow the Nissan method which involves control maps limiters and thresholds. There is a description on how the knock control strategy works on the EcuTek knowledgebase, for further reading

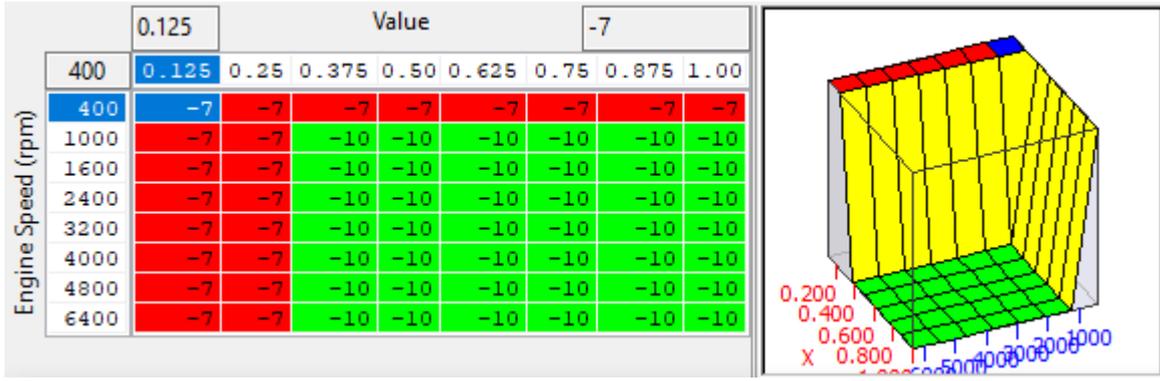
<https://ecutek.zendesk.com/hc/en-gb/articles/115000200589-GT-R-Knock-Sensing>

Knock Control on/off



Easy to use enable (=1) or disable (=0) map based on load and RPM for application of knock retard calculated by the knock control strategy.

Knock Retard Limiter



Limit applied to the amount of retard that can be set by the knock control strategy. Based on engine load and RPM the output is in degrees and could be used to limit the amount of knock retard.

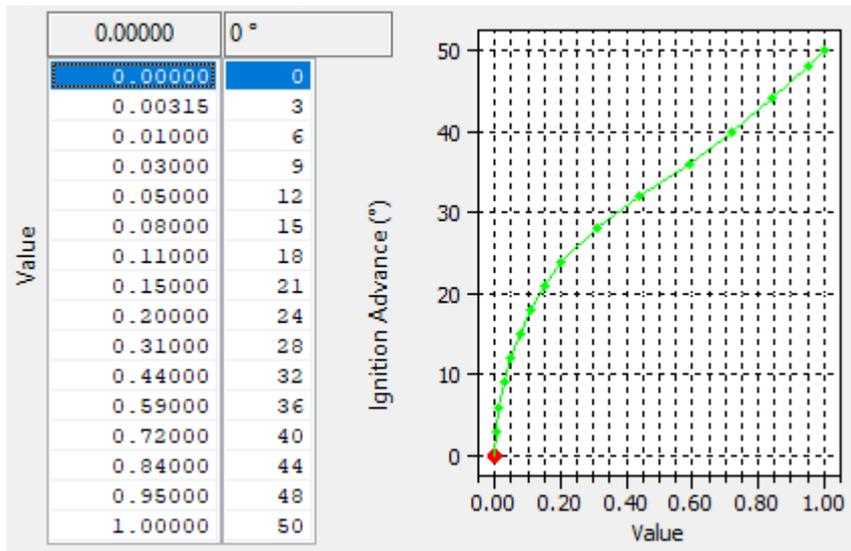
Knock Retard Sensitivity 1



This per cylinder threshold map is the point where knock correction will become active for each cylinder. If the values against RPM are breached then the knock correction parameter will start to show knock retard. Built engines often generate excessive engine noise that can be detected as knock, raising these values will help prevent this being detected, though care must be taken that the sensitivity will still show true knock! The centre two cylinders are noisier due to cylinders either side (1-3 or 4-6) so the noise thresholds are higher.

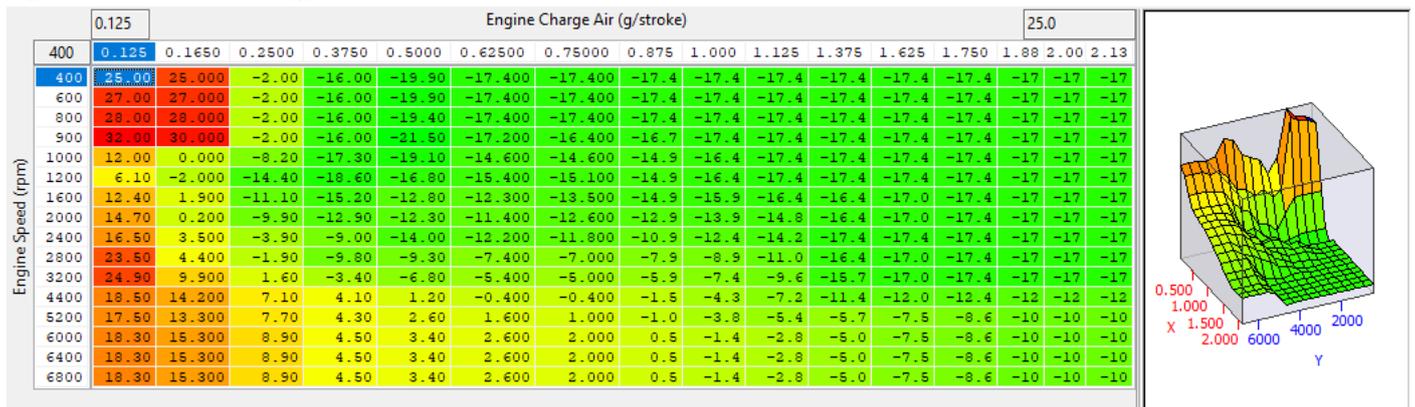
NOTE: the logging rate for per cylinder knock output cannot capture all knock events so use with caution!

Ignition Timing – Torque Reduction



This is the amount of retard (in degrees) applied for a given torque reduction percentage. Requests from other control functions such as Limit Modes or commands from other modules like the TCM, ABS or stability control module.

Ignition Timing Retard Limit



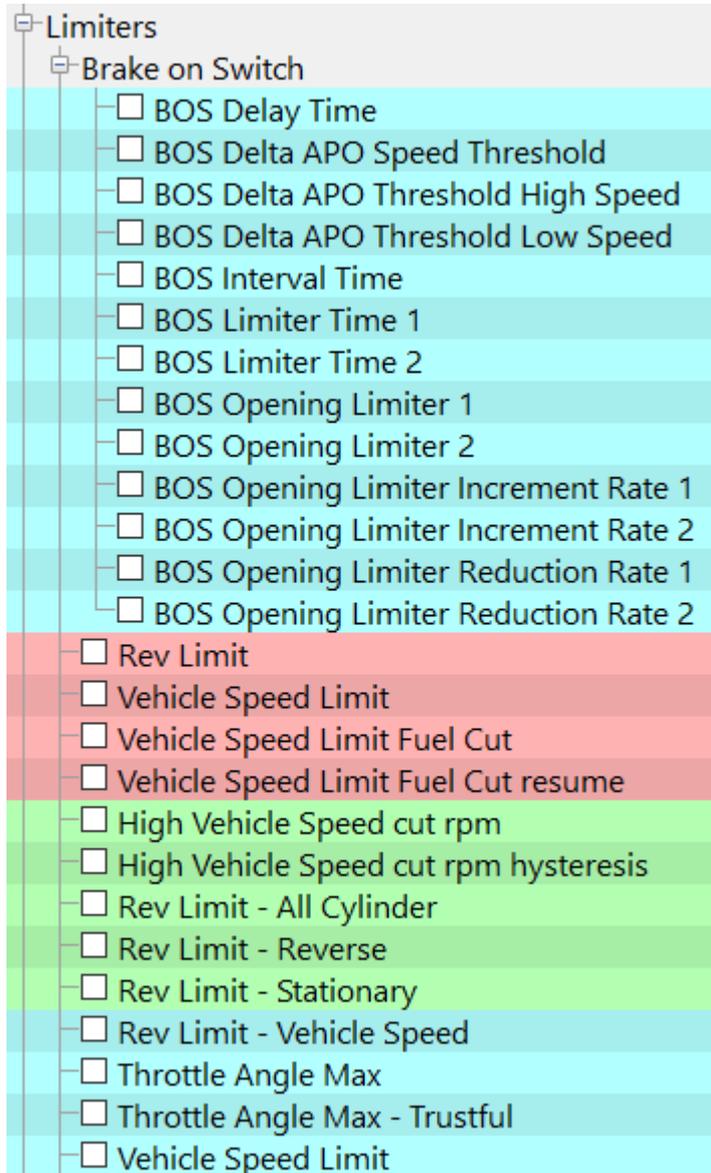
This is the minimum achievable timing after all the corrections are applied, if you need to apply greater amounts of retard for torque control or shift torque reduction adjust these maps.

Limiters

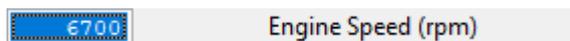
Introduction

The VR30DDTT has many safety limiters, raising limiters without understanding may cause issues. When attempting to generate more power though certain limiters may need to be increased or decreased.

Map List



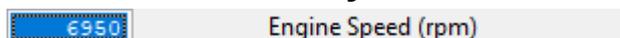
Rev Limit



This is the normal rev limit of the car, it starts with throttle closing and then a partial fuel cut, raise this if required.

Be aware that the TCM still has a shift limit so it will always shift at a set RPM.

Rev Limit – All Cylinder



This is the full fuel cut “all cylinder” RPM limit, This value should always be greater than the **Rev Limit** value.

Rev Limit – Reverse



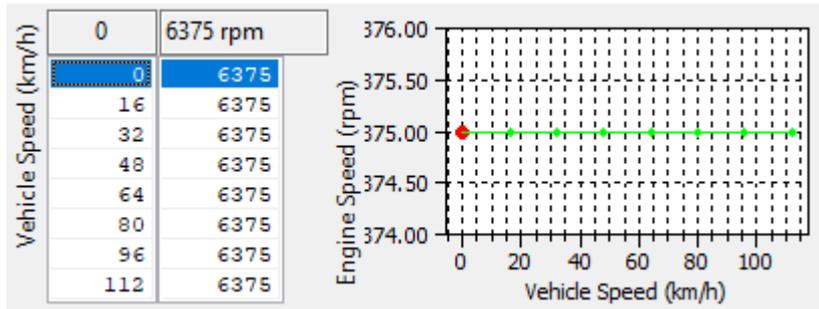
Rev limit when in reverse gear.

Rev Limit – Stationary



Rev limit when stationary

Rev Limit – Vehicle Speed



Secondary rev limit at individual vehicle speeds, the TCM will still limit RPM by shifting.

Vehicle Speed Limit



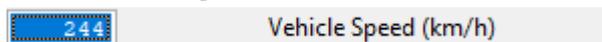
Primary speed limiter in Km/h

Vehicle Speed Limit



Secondary speed limit, raise if you find it limiting the vehicle speed.

Vehicle Speed Limit Fuel Cut & Resume

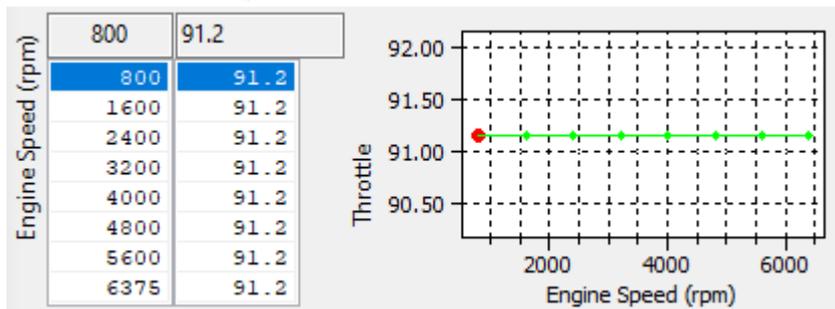


Fuel Cut will occur above this vehicle speed



Fuel Cut will end when the vehicle speed returns below this value.

Throttle Angle Max & Trustful

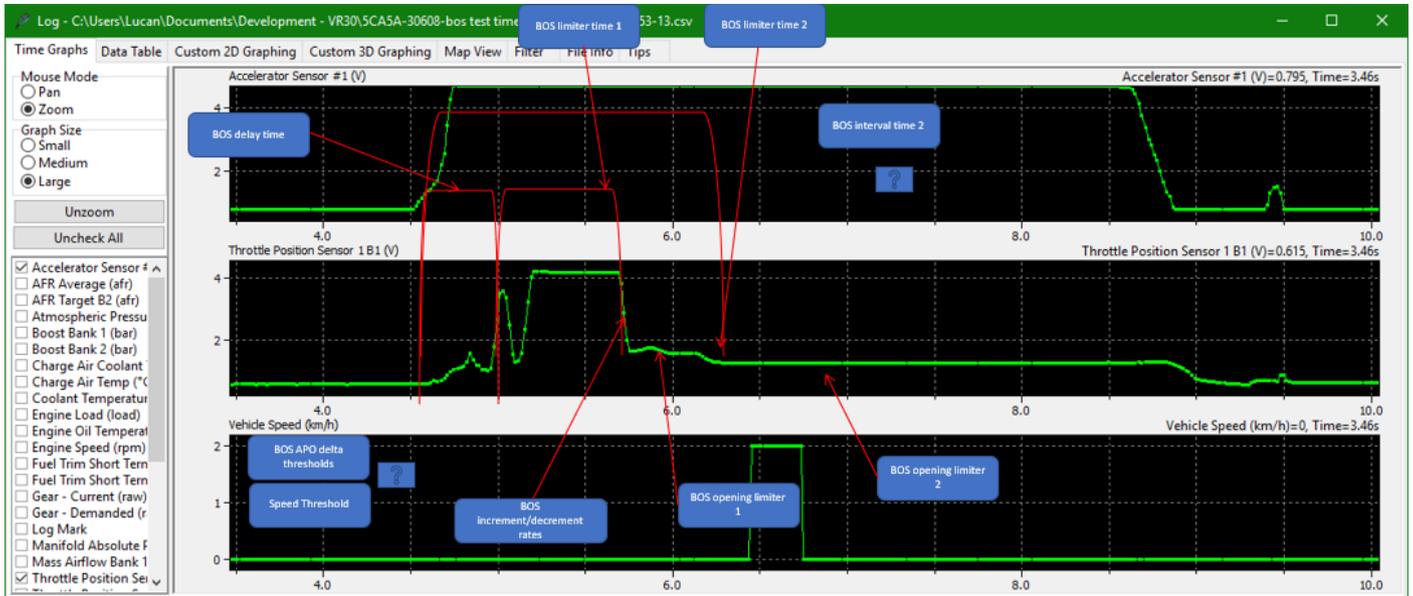


Maximum allowed throttle angle at independent engine speeds, the trustful map must match this exactly.

Brake On Switch (BOS) limiters

As with most modern ECU's there is a fail safe to cut the accelerator pedal input when the brake pedal is applied at the same time as the accelerator, this is a safety feature to slow the car if the driver or driving signals are not being received correctly to prevent the car from accelerating without driver input. This feature can be adjusted or disabled to allow the brake to be applied while applying the accelerator pedal for use while brake boosting etc.

The diagram below shows which maps are responsible for which part of the BOS limit process



BOS Delay Time

Time (s)

The delay time before the BOS limiter adjusts accel pedal output amount.

BOS Delta APO Speed Threshold

Vehicle Speed (km/h)

The vehicle speed to differentiate between **BOS Delta APO Speed Threshold High Speed & Low Speed**

BOS Delta APO Speed Threshold High Speed

Accel Pedal Delta (%)

The function of these are not completely understood but they appear to be the activation thresholds based on accel pedal position. Changing these had little effect on our test vehicle.

BOS Delta APO Speed Threshold Low Speed

Accel Pedal Delta (%)

The function of these is not completely understood but they appear to be the activation thresholds based on accel pedal position. Changing these had little effect on our test vehicle.

BOS Interval Time

Time (s)

The function of this value is currently unknown but may be related to the maximum time allowed before any BOS limits are applied or possibly the time before reactivation.

BOS Limiter Time 1

Time (s)

The time to wait before the **BOS Opening Limit 1** accel pedal adjustment is applied.

BOS Limiter Time 2

 Time (s)

The time to wait before the **BOS Opening Limit 2** accel pedal adjustment is applied.

BOS Opening Limiter 1

 Accel Pedal (%)

Limit applied to the Accel pedal input for torque calculations while before the **BOS Limiter Time 1** is, this will need to be raised to allow more accel pedal to be applied with the brake switch on.

BOS Opening Limiter 2

 Accel Pedal (%)

Limit applied to the Accel pedal input for torque calculations while before the **BOS Limiter Time 2** is, this will need to be raised to allow more accel pedal to be applied with the brake switch on.

BOS Opening Limiter Increment Rate 1

 Accel Pedal (%)

Rate at which the accel pedal is raised from the **BOS Opening Limiter 1** set point when the brake pedal is released. This is likely to be used for the BOS limits applied above **BOS Delta APO Speed threshold**.

BOS Opening Limiter Increment Rate 2

 Accel Pedal (%)

Rate at which the accel pedal is raised from the **BOS Opening Limiter 2** set point when the brake pedal is released. This is likely to be used for the BOS limits applied below **BOS Delta APO Speed threshold**.

BOS Opening Limiter Reduction Rate 1

 Accel Pedal (%)

Rate at which the accel pedal is lowered to the **BOS Opening Limiter 1** set point when the brake pedal is applied. This is likely to be used for the BOS limits applied above **BOS Delta APO Speed threshold**.

BOS Opening Limiter Reduction Rate 2

 Accel Pedal (%)

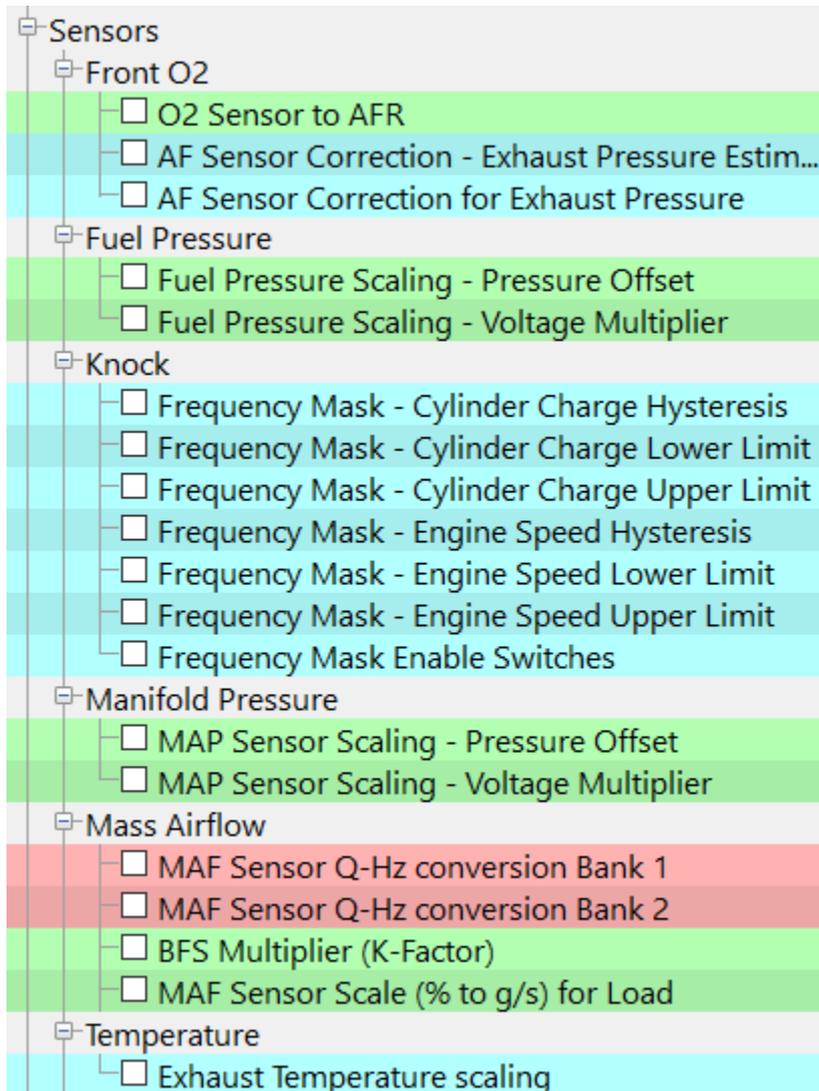
Rate at which the accel pedal is lowered to the **BOS Opening Limiter 1** set point when the brake pedal is applied. This is likely for the BOS limits applied below **BOS Delta APO Speed threshold**.

Sensor Scaling

Introduction

Sensor scaling is the category that contains all the sensor-based scaling factors relevant to tuning the VR30DDTT engine. If there are sensors that you wish to replace with aftermarket types use the sensor scaling maps and enter the values of the new sensors.

Map List

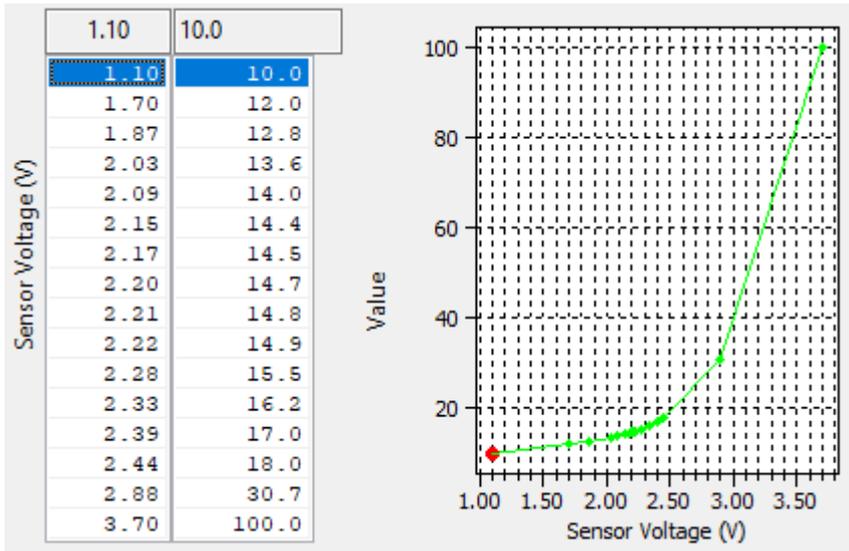


Live Data Parameters

- *AF Sensor B1 (V)* – Voltage output of the AFR sensor bank 1
- *AF Sensor B21 (V)* – Voltage output of the AFR sensor bank 2
- *AFR Bank 1 (AFR)* – Bank 1 Sensor output in AFR counts as seen by the ECU after corrections
- *AFR Bank 2 (AFR)* – Bank 2 Sensor output in AFR counts as seen by the ECU after corrections
- *AFR Calibrated* – AFR value according to polynomial calculation based on wideband measured AFR
- *Fuel Pressure (MPa)* – Absolute measured fuel pressure output of High pressure fuel rail in Mpa
- *Fuel Pressure Sensor (mV)* – Voltage output of High pressure fuel rail sensor in millivolts
- *Knock Index - Cylinder 1 to 6* – Knock count value as seen by the ECU for each individual cylinder
- *Knock Threshold - Cylinder 1 to 6* – The set knock threshold output of the knock threshold map.
- *Boost Sensor 1 & 2 (bar)* – Boost sensor output value in Bar
- *Manifold Pressure Sensor (V)* – Voltage output of the Manifold pressure sensor
- *Manifold Absolute Pressure (bar)* – Absolute pressure measure in the manifold.

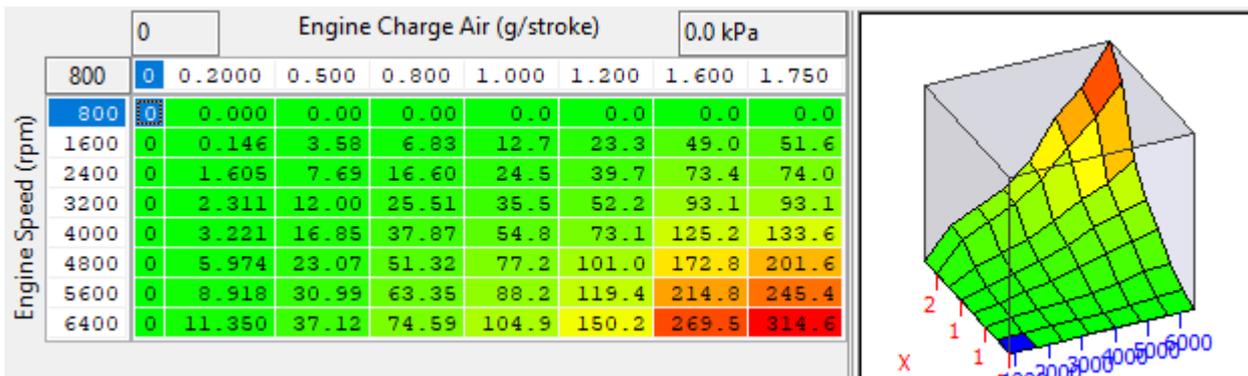
- Mass Airflow (g/s) – Converted Mass airflow after MAF sensor output processing
- Mass airflow Bank 1 (% load) – Bank 1 specific load converted output of MAF sensor (not corrected)
- Mass airflow Bank 2 (% load) – Bank 2 specific load converted output of MAF sensor (not corrected)
- Mass Airflow Sensor Freq B1 – Bank 1 MAF sensor output frequency
- Mass Airflow Sensor Freq B2 – Bank 2 MAF sensor output frequency
- Exhaust Temp 1 B1 (V) – Voltage output of EGT sensor for bank 1
- Exhaust Temp 1 B2 (V) – Voltage output of EGT sensor for bank 2
- Exhaust Temp B1 (°C) – Converted Exhaust gas temperature for Bank 1
- Exhaust Temp B2 (°C) – Converted exhaust gas temperature for bank 2

O2 Sensor to AFR



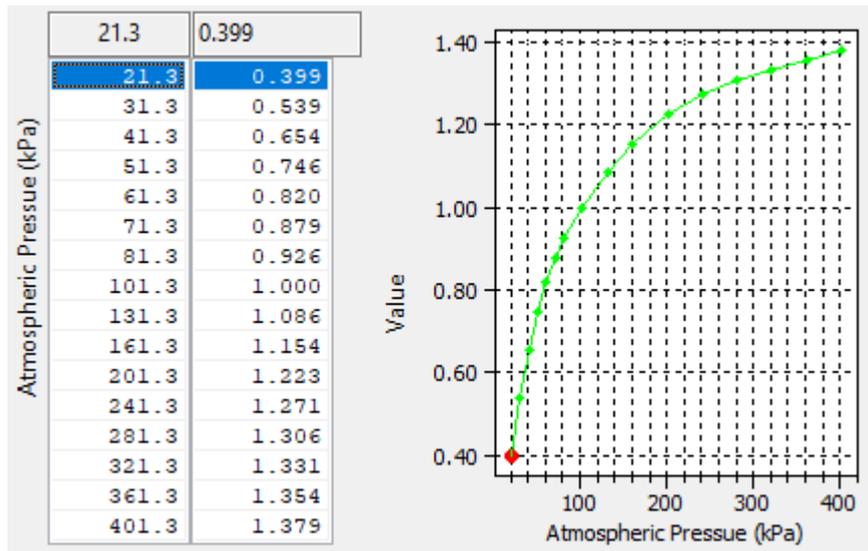
This is the map that converts O2 sensor voltage into AFR, there are corrections on this value after the sensor scaling is applied.

AF Sensor Correction – Exhaust Pressure Estimate



This map is the exhaust back pressure estimate used in the sensor correction function. If you have repositioned the O2 sensor to post turbo or the sensor readings become inaccurate at high loads and speeds this table may need to be adjusted. If you can measure exhaust pressure and put the measured values into this map it will hopefully give accurate pressure corrections.

AF Sensor Correction for Exhaust Back Pressure



This is the amount of AFR correction applied for the estimated back pressure (the left axis is believed to be estimated exhaust pressure not Atmo) This is used to compensate for inaccuracies created by measuring the exhaust gas above ambient pressure. It should not need to be adjusted unless the sensor has been changed or you need to make corrections because the sensor has been moved.

Fuel Pressure Scaling – Pressure Offset



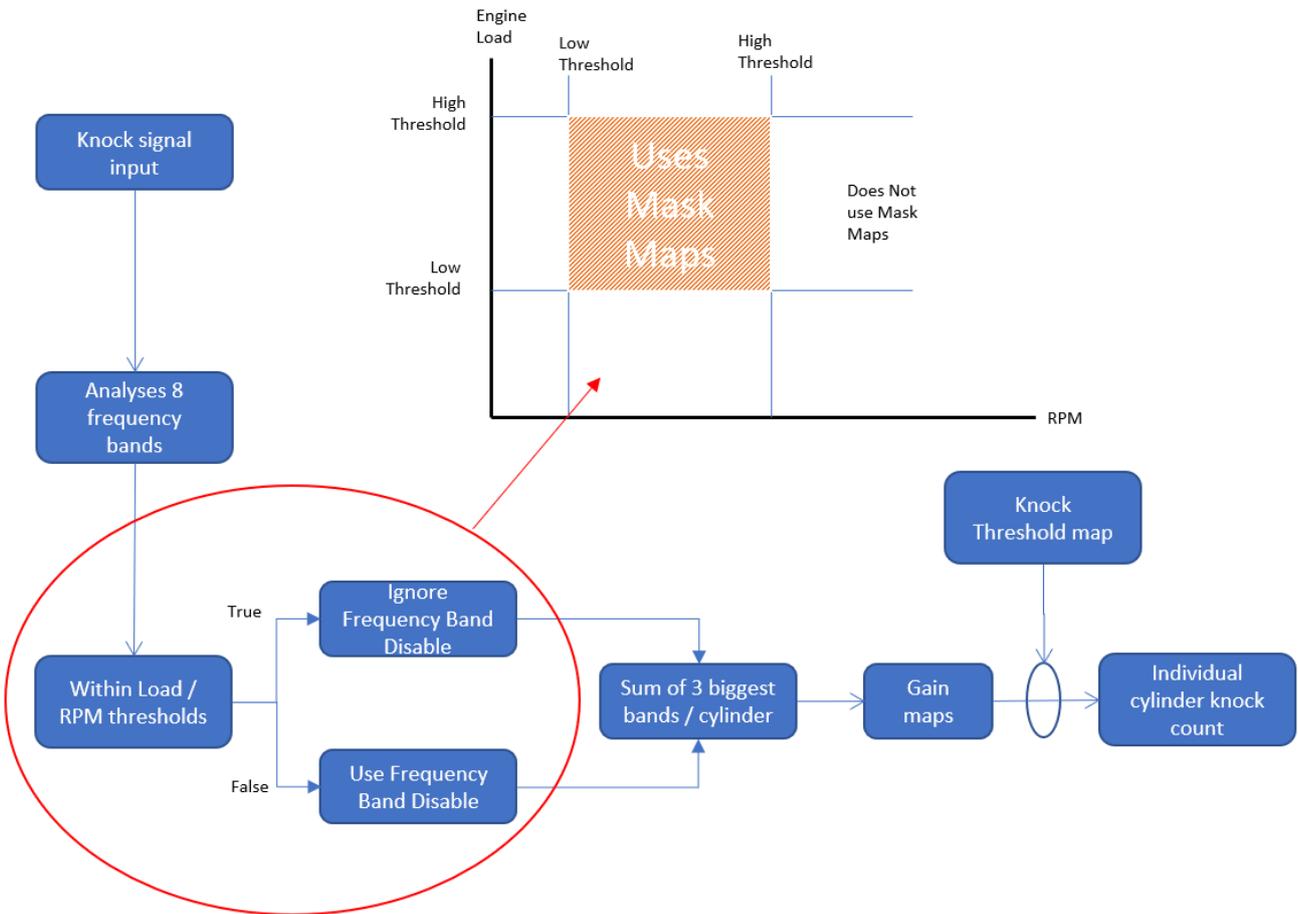
The offset for pressure sensor scaling in MPa, scale this in the same method as MAP sensor scaling.

Fuel Pressure Scaling – Voltage Multiplier



The multiplier value in MPa / volt used to convert sensor voltage to pressure, scale this similarly to a MAP sensor.

Knock Frequency Masking



The Nissan/Infinity strategy for knock sensor signal analysis takes windowed knock signals and sums up the amplitudes based on separate frequency bands. If you have a forged engine that makes more noise due to differences in clearances etc you may want to use these masks to try to reduce the background noise to eliminate “false knock” .

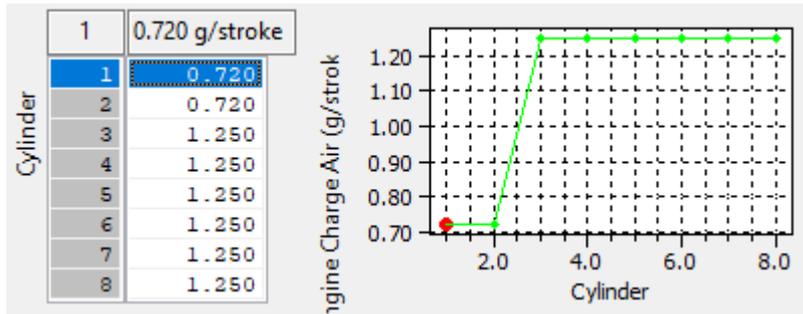
Frequency Mask – Enable (disable) Switches



We believe that the frequencies that are disabled go from top to bottom, lowest at the top highest at the bottom however this currently has not been confirmed.

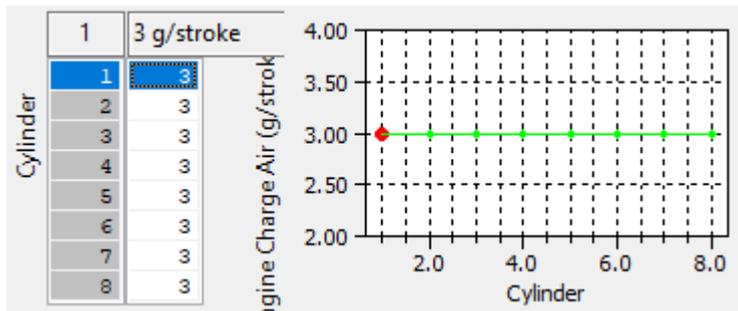
- 1 - 6.1kHz
- 2 - 7.3kHz
- 3 - 8.5kHz
- 4 - 9.8kHz
- 5 - 11.0kHz
- 6 - 12.2kHz
- 7 - 13.4kHz
- 8 - 14.6kHz

Frequency Mask – Cylinder Charge Lower Limit



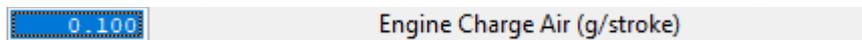
The load threshold that the engine load needs to be above for the masking maps to be used.

Frequency Mask – Cylinder Charge Upper Limit



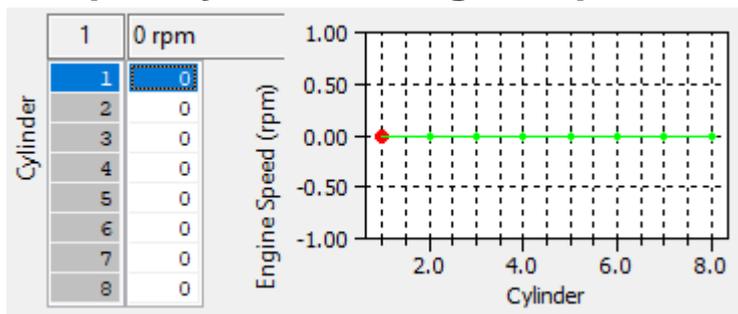
The load threshold that the engine load needs to be below for the masking maps to be used.

Frequency Mask - Cylinder Charge Hysteresis



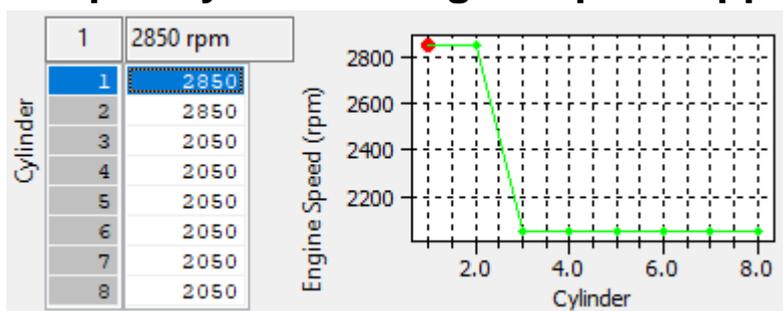
Hysteresis value for the engine load thresholds

Frequency Mask – Engine Speed Lower Limit



Engine speed threshold for enabling the knock masking maps.

Frequency Mask – Engine Speed Upper Limit



Engine speed threshold for disabling the knock masking maps.

Frequency Mask – Engine Speed hysteresis

Engine Speed (rpm)

Hysteresis value for engine speed thresholds.

Knock Sensor Gain

This is not currently defined however it does directly affect the knock sum per cylinder for the highest count frequency bands.

MAP Sensor Scaling – Pressure Offset

Offset (bar)

This is the sensor located in the Inlet manifold, which is used for airflow estimation and pressure control. The standard sensor is a 3.0bar Absolute sensor. There is shared scaling for the MAP and pre-throttle boost sensors so all three sensors must be changed to keep the measurements correct. This is the pressure offset value to adjust the conversion output of the sensor to hit the calibrated 0 (Zero) point.

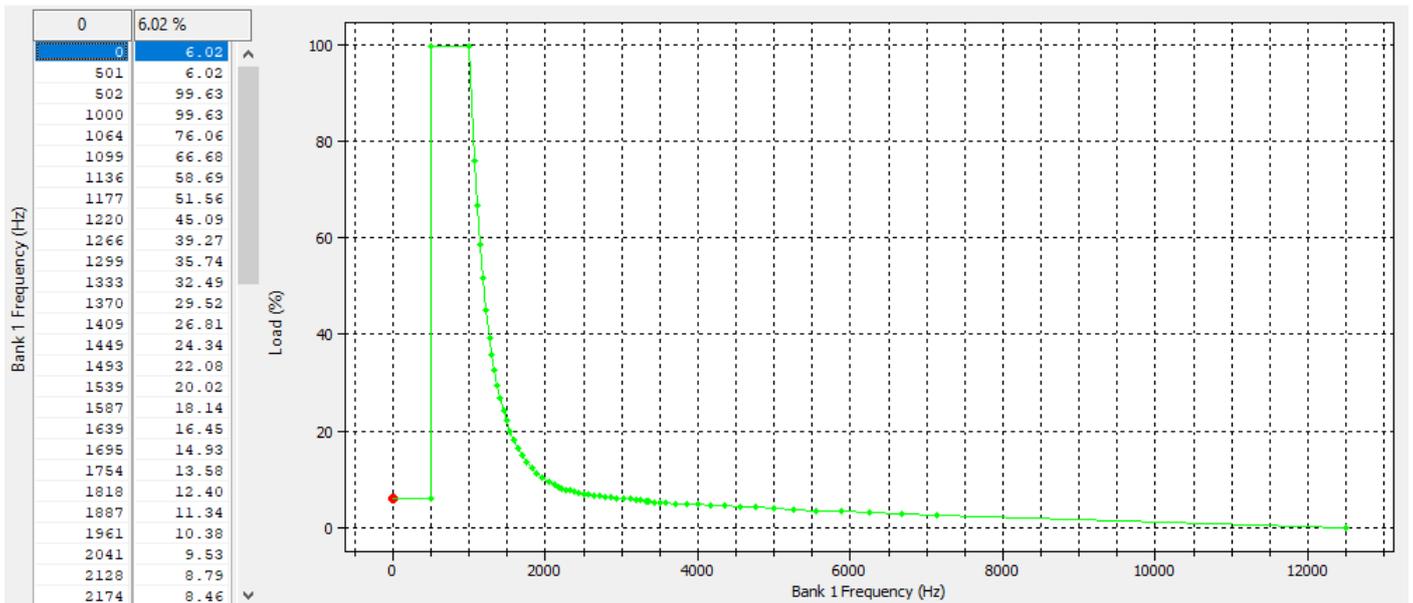
MAP Sensor Scaling – Voltage Multiplier

File Edit Help

Multiplier (bar/V)

This is the sensor located in the Inlet manifold, which is used for airflow estimation and pressure control. The standard sensor is a 3.0 bar Absolute sensor. There is shared scaling for the MAP and pre-throttle boost sensors so all three sensors must be changed to keep the measurements correct. This is the voltage multiplier value to set the slope of the boost sensor output.

MAF sensor Q-Hz Conversion Bank 1 & 2



Mass air flow sensor frequency to air flow conversion table. The mass air flow sensor is placed in the intake air stream measuring a part of the entire intake flow and outputting a frequency back to the ECU. It measures the frequency from both MAFs and uses the load output of each one to calculate a respective airflow. To tune the fuel trims you should adjust the load output of these maps for given frequencies.

BFS Multiplier (K-Factor)

0.0268 s/g

This is a conversion factor that is used to generate engine load and fuel volumes, it should not need to be adjusted.

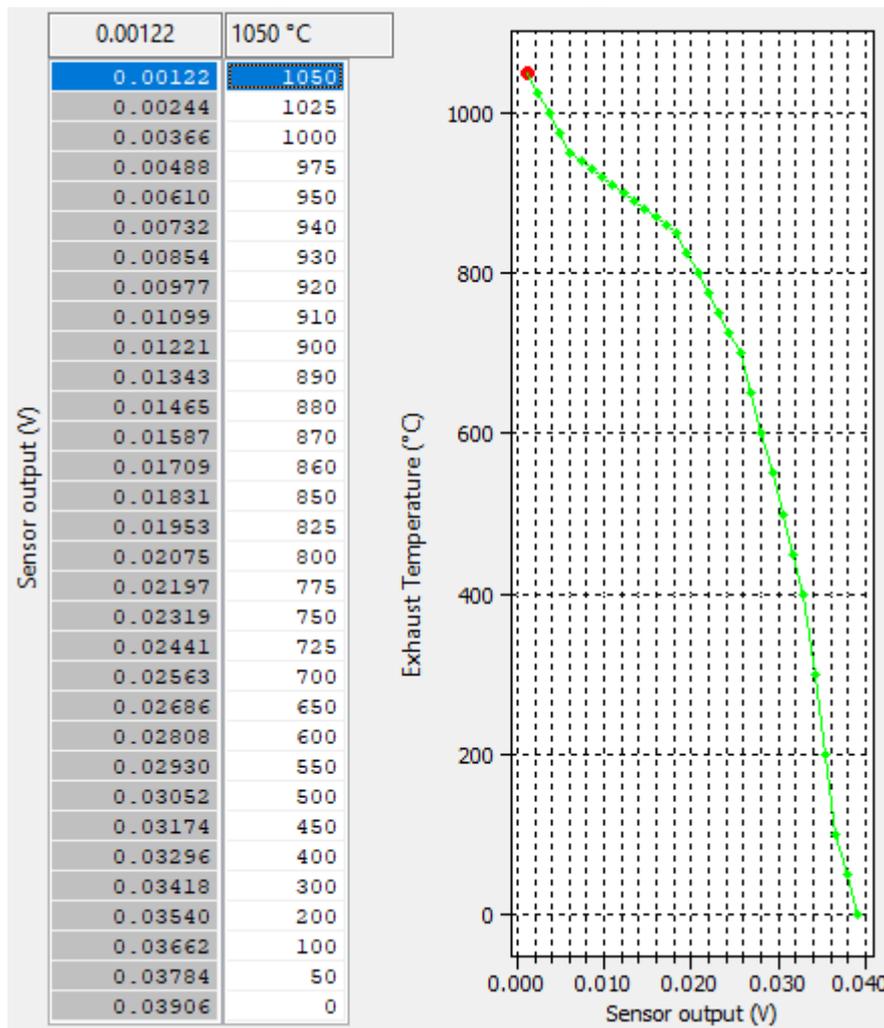
MAF Sensor Scale (% to g/sec) for Load

138 100% MAF

When fitting larger MAF housings (or Induction kits) then this value should be increased proportionally relative to the surface area increase of the larger MAF housing,

This is a coarse adjustment for MAF scaling, it converts the MAF sensor % value into grams of air per second

Exhaust Temperature Scaling



Sensor voltage output conversion to temperature, this will need to be changed if the sensors are changed or removed. There is common scaling for both banks.

Torque

Introduction

The VR30DDTT uses torque targets to control requested throttle airflows and power demand, torque reduction requests are also released through these strategies. Similar to other Nissan platforms there are powertrain torque demand maps, torque output maps, limits and torque corrections.

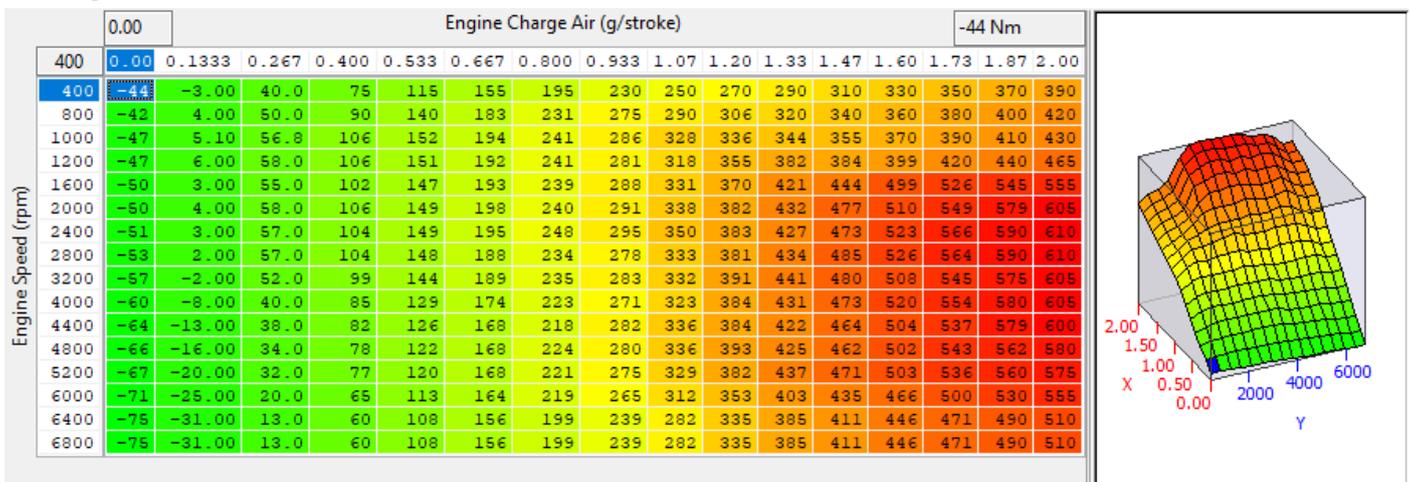
Map List

Torque	
<input type="checkbox"/>	Torque Actual
<input type="checkbox"/>	Torque Desired - 1
<input type="checkbox"/>	Torque Desired - 1 trustful
<input type="checkbox"/>	Torque Desired - 2
<input type="checkbox"/>	Torque Desired - 2 trustful
<input type="checkbox"/>	Torque - PTD Correction
<input type="checkbox"/>	Torque Limit correction
<input type="checkbox"/>	Torque Limit failsafe
<input type="checkbox"/>	Torque Limit for Drive Mode
<input type="checkbox"/>	Torque Limit knock prevention
<input type="checkbox"/>	Torque Overboost Limit

Live Data Parameters

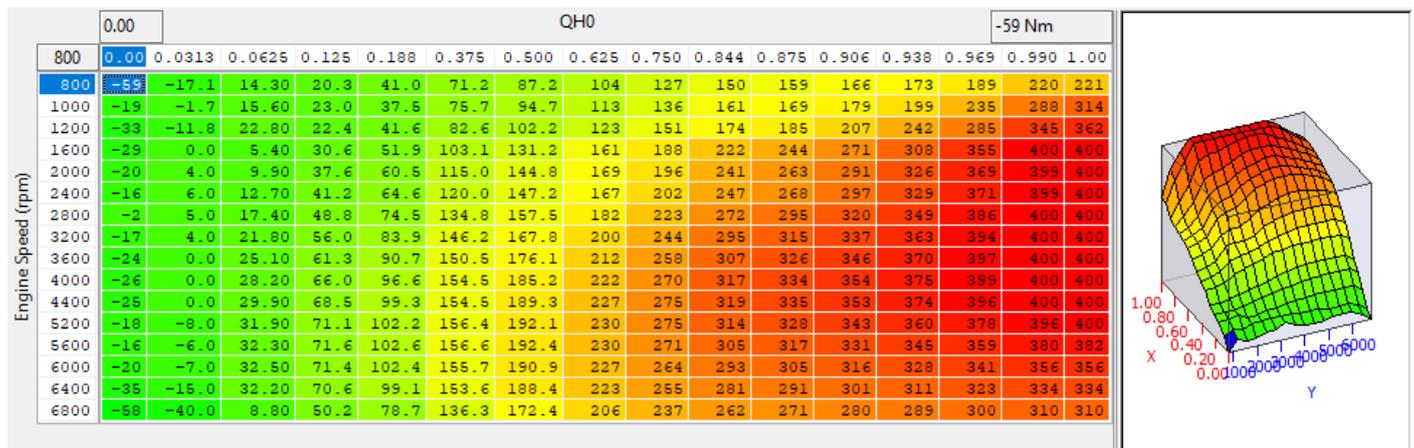
- *Torque Actual (Nm)* – Estimates Actual Engine Torque Produced.
- *Torque Demand 1 (Nm)* – Demanded torque for powertrain
- *Torque Demand 3 (Nm)* – Demanded torque for other units
- *Torque Limit (Nm)* – Current safety limit for torque
- *Torque Red Req – Time Since Gear (s)* – Gear sift timer from torque reduction request release
- *Torque Red Req 1 (Nm)* – Torque reduction request from transmission
- *Torque Red Req 2 (Nm)* – Torque reduction request from other modules

Torque Actual



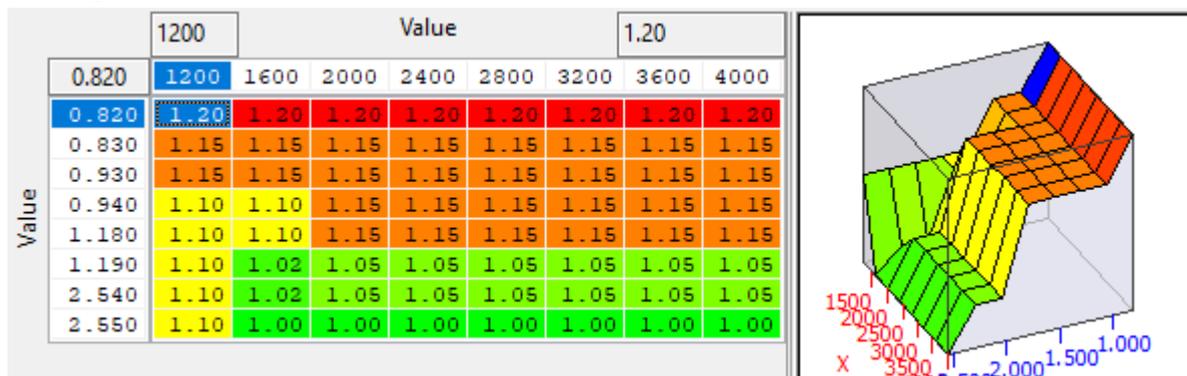
Estimates Actual Engine Torque and is used by the TCM and other modules to decide on the amount and level of torque reduction.

Torque Desired – 1 & 2 (& trustful)



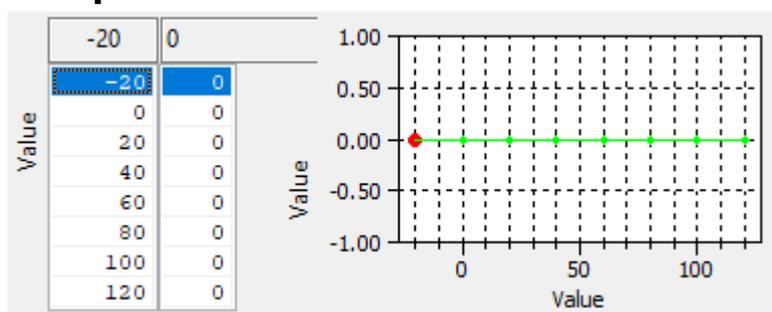
The demanded torque from the power train, there are two modes and the #1 maps appear to be used most of the time, the trustful equivalent must match exactly or P0605 DTC's will occur. The silver sport cars have a lower torque target from the factory and these may need to be raised to get the boost to increase.

Torque – PTD correction



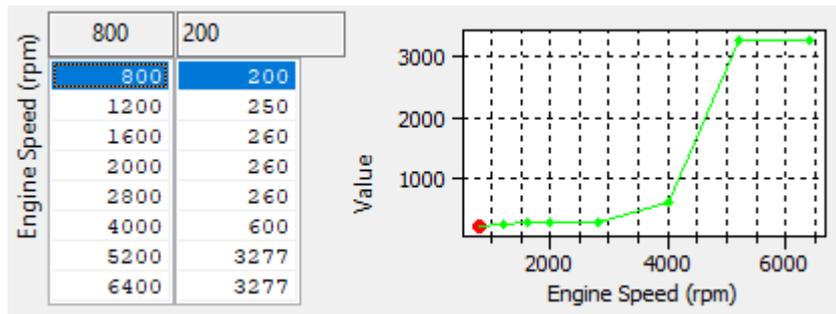
The Powertrain Torque Desired correction based on current gear ratio, the adjust the torque demanded in different gears.

Torque limit correction



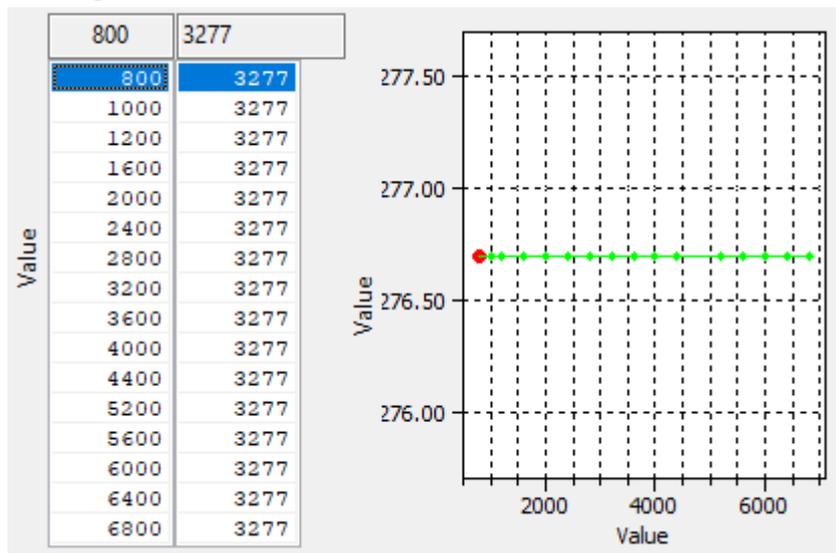
This is an adjustment to the torque limit based on temperature

Torque Limit Failsafe



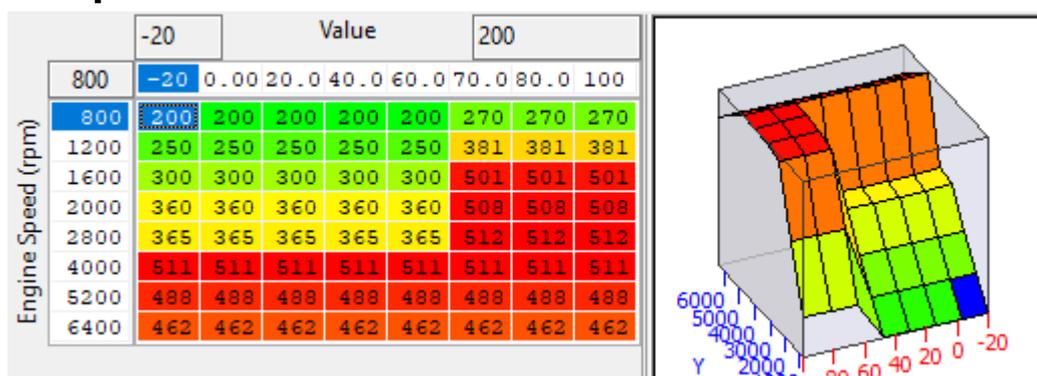
This is the maximum allowed torque in failsafe mode.

Torque limit Drive Mode



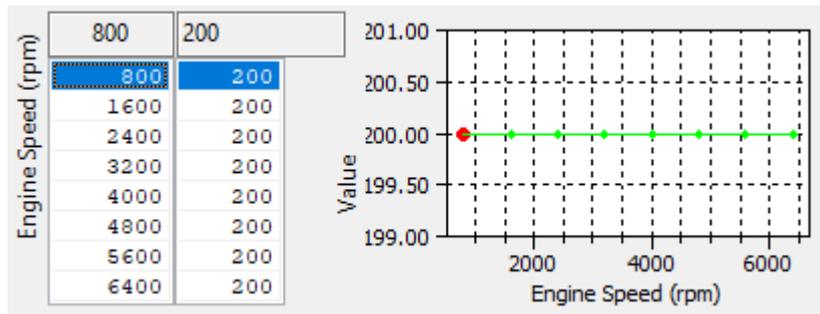
This is the maximum allowed torque when in drive, it is currently set to maximum.

Torque Limit Knock Prevention



This is the maximum allowed torque for coolant temperature to prevent knock.

Torque Overboost Limit



This is the maximum allowed torque when over boost is detected.

Idle Control

Introduction

Idle control is done using the electronic throttle, the function uses a similar method to other Nissan products.

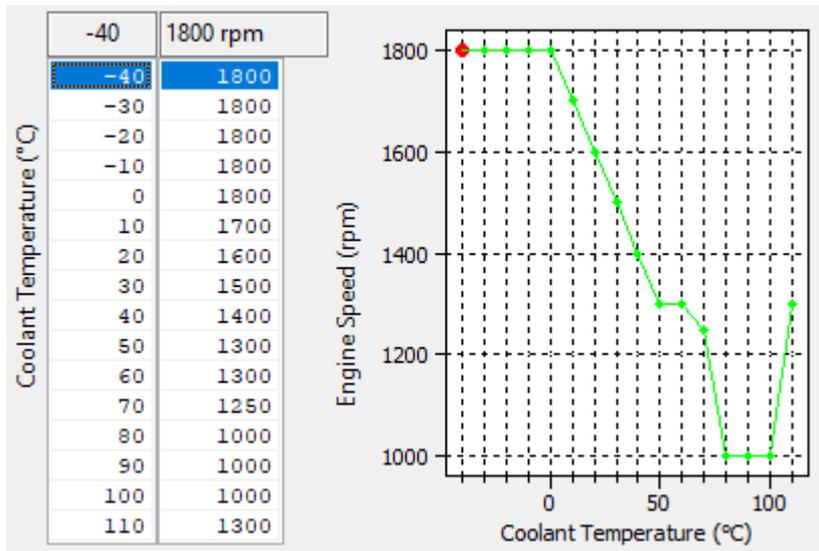
Map List

Idle Control	
<input type="checkbox"/>	Idle Target
<input type="checkbox"/>	Idle IPW Lower Limit
<input type="checkbox"/>	Idle IPW Upper Limit
<input type="checkbox"/>	Idle MAF Frequency Lower Limit
<input type="checkbox"/>	Idle MAF Frequency Upper Limit
<input type="checkbox"/>	Idle Throttle Lower Limit - Related
<input type="checkbox"/>	Idle Throttle Upper Limit - Related
<input type="checkbox"/>	ISC Airflow Comp - Atmospheric Pressure
<input type="checkbox"/>	ISC Airflow Comp - Coolant Temp
<input type="checkbox"/>	ISC Airflow Comp - IAT
<input type="checkbox"/>	ISC Open Area Max
<input type="checkbox"/>	ISC Open Area Max - trustful
<input type="checkbox"/>	ISC Open Area Max offset
<input type="checkbox"/>	ISC Open Area Max Offset
<input type="checkbox"/>	ISC Open Area Max Offset - Trustful
<input type="checkbox"/>	ISC Open Area Max offset trustful

Live Data related parameters

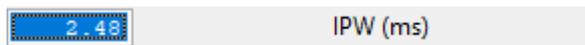
- *Engine Speed (RPM)* – Current engine speed
- *Coolant Temperature (°C)* – Current engine coolant temperature
- *Mass Airflow Sensor Freq B1* – Bank 1 MAF sensor output frequency
- *Mass Airflow Sensor Freq B2* – Bank 2 MAF sensor output frequency
- *Intake Air Temperature (°C)* – Current intake air temperature
- *Atmospheric Pressure (Bar)* – Current Barometric Pressure

Idle Target



There are many idle target maps identified, we currently do not know in which situation all of them are used however the all have coolant temperature as the axis and it's likely that there is one map used primarily and the other used in modes such as immediate after start, limp modes and target limits.

Idle IPW Upper / Lower Limit



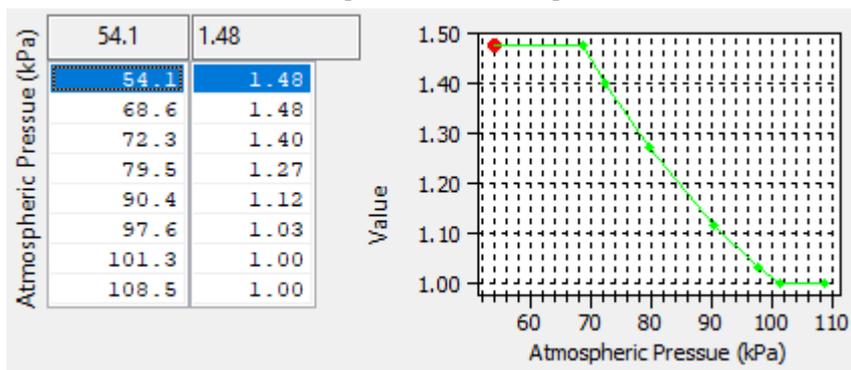
Upper and Lower limit of injector pulse width to allow idle flag to be set.

Idle MAF Frequency Upper / Lower limit



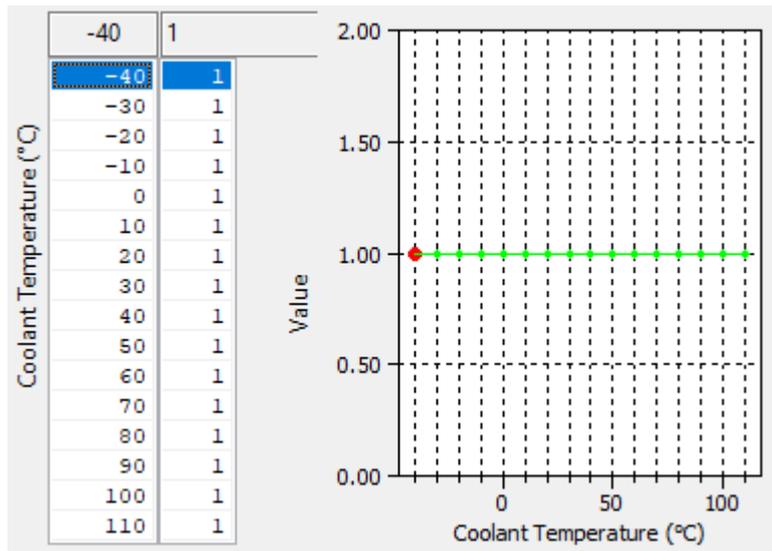
These maps set the idle MAF frequency bounds for the idle flag, there are also thresholds based on RPM and time

ISC Airflow Comp – Atmospheric Pressure



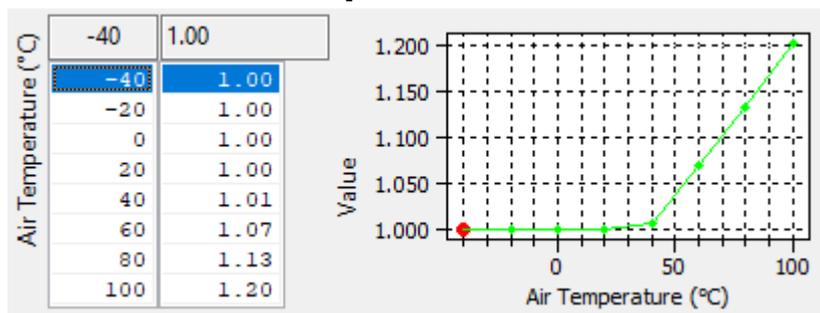
This is a compensation to Idle Speed Control (ISC) airflow target based on the atmospheric pressure. It should not need to be adjusted unless idle airflow requirements have changed significantly with different throttles or intake systems.

ISC Airflow Comp - Coolant Temp



This is a compensation to idle airflow target based on the engine coolant temperature. It should not need to be adjusted unless idle airflow requirements have changed significantly with different throttles or intake systems.

ISC Airflow Comp - IAT

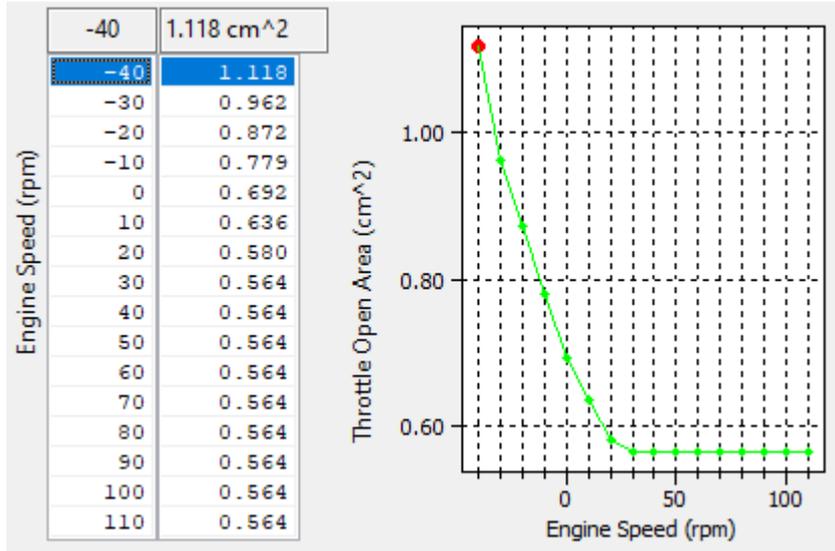


This is a compensation to idle airflow target based on the Intake Air Temperature. It should not need to be adjusted unless idle airflow requirements have changed significantly with different throttles or intake systems.

ISC Open Area Max

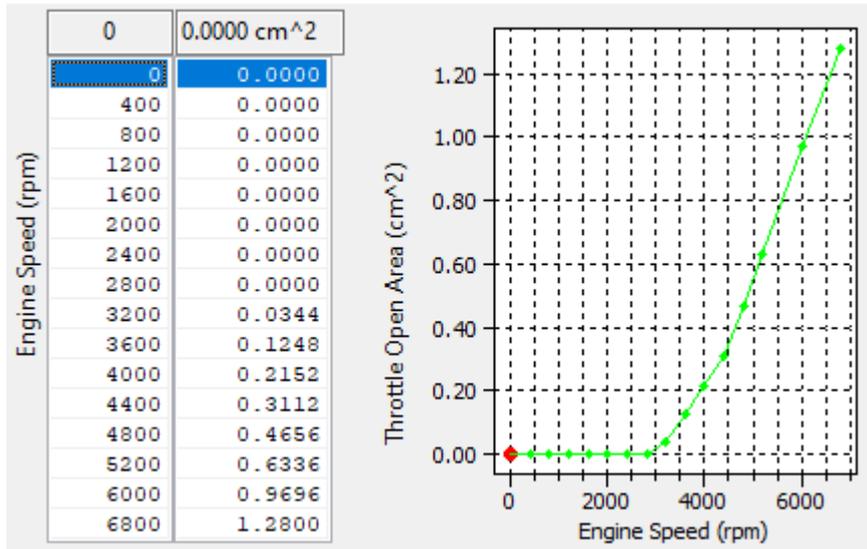
The Idle Speed Control (ISC) function constantly calculates an open area and hence throttle angle based on the idle airflow requirements, this value has a setting for maximum open area allowed for idle control to stop the calculations running away, this value has various offsets calculated and applied, these can be limited by the following maps

ISC Open Area Max & Trustful



This is the base value for Maximum idle open area referencing coolant temperature the other offsets are added to the output of this map. The final value is used to cap the allow idle open area.

2D RPM based Offset limiter & Trustful



This will limit the open area adjustment based on engine speed, it will cap the adjustment to maximum allowed open area. The trustful map of the same name must match this map exactly otherwise DTC's will occur. The intent of this map is to allow the base idle throttle open area to be increased with RPM.

3D Torque based offset limiter & trustful



This will limit the open area adjustment based on available torque and engine speed, it will cap the adjustment to allowed open area. The trustful map of the same name must match this map exactly otherwise DTC's will occur. It is believed currently that these maps are used only in hybrid vehicles not the current VR30DDTT line up.

Idle Throttle Upper / Lower Limit (misfire diagnosis at idle)

Upper Limit

Time (s)

BETA MAP USE WITH CAUTION. This is the maximum theoretical injector open time for the misfire diagnosis system to be active when the idle flag is set.

Lower Limit

Engine Speed (rpm)

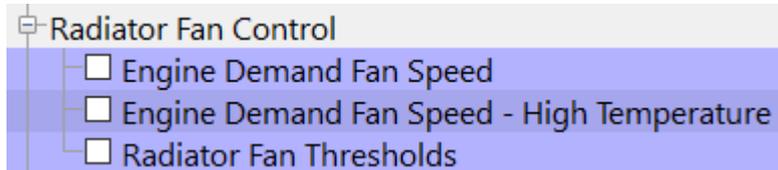
BETA MAP USE WITH CAUTION. The Maximum allowed engine speed for misfire diagnosis when idle flag is active.

Radiator Fan Control

Introduction

Radiator fan speed for coolant temperature control is performed by the ECM. The fan speed and activation points can be adjusted in the calibration to cope with increased cooling demand and changed radiator airflow characteristics.

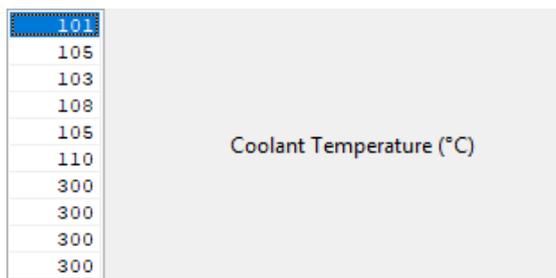
Map List



Live Data related parameters

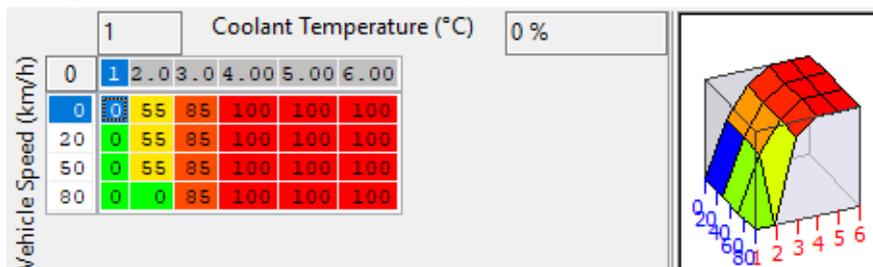
- Radiator Coolant Temp (°C) – Current radiator temperature.
- Fan Duty (%) – Current requested duty for the radiator fan

Radiator Fan Threshold



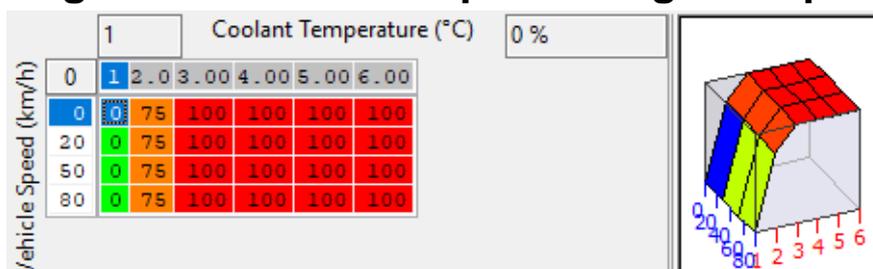
These values for the coolant temp axis of the Radiator Fan Speed control maps. The values are interleaved, so the first 2 values are the first thresholds for each map.

Engine Demand Fan Speed



The engine demand for radiator fan speed. X axis is coolant temp with values of 0, 101, 103, 105, 300, 300.

Engine Demand Fan Speed – High Temperature



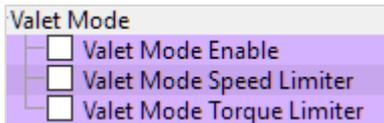
The engine demand for radiator fan speed. X axis is coolant temp with values of 0, 105, 108, 110, 300, 300.

Valet Mode

Introduction

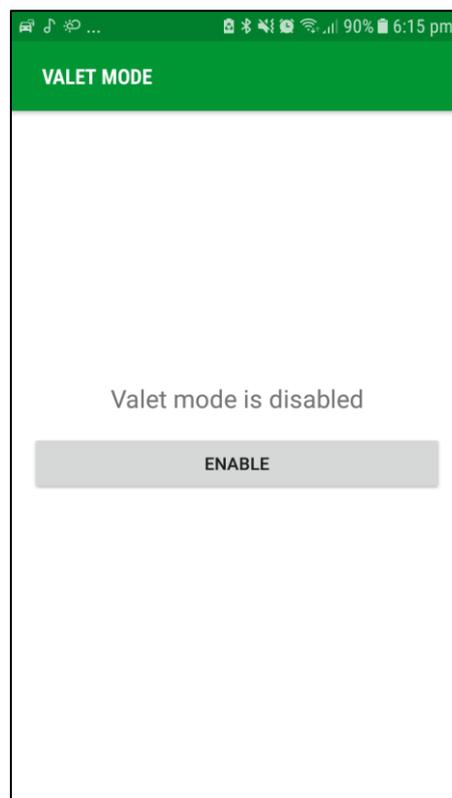
Valet Mode allows the driver to lock the car into a lower performance mode when lending it to a less experienced driver, or as a theft deterrent that kicks in when the car is at a safe distance. Valet mode has been simplified in line with the strategy used on the 370z, as the previous version was frequently commented on as being too complicated to activate and deactivate.

Map List



Method of Operation

Valet mode is currently only operated by using Ecu Connect, the ability to switch with the Cruise control buttons will hopefully be implemented in the next releases of RaceROM feature files.



To turn on Valet mode

- Enter the valet mode option and press enable

To turn off the Valet mode

- Enter the valet mode option and press Disable

Method of Operation (Cruise Control Buttons Not currently active)

Valet mode is operated using the cruise control switches in the same way as map switching. Instead of selecting map switch mode 1, 2, 3 or 4, select mode 8. The map switch mode does not change.

To turn on the Valet mode

- Ensure that the cruise control is OFF.
- Hold the CANCEL button for 1 second.
- The rev counter will move to indicate the current mode.
- Use the cruise up until the tachometer shows 8000rpm (mode 8).
- Press CANCEL or wait 1 second to enable the valet mode, the rev counter will show current RPM

To turn off the Valet mode

- Ensure that the cruise control is OFF.
- Hold the CANCEL button for 1 second.
- The rev counter will move to indicate the current mode.
- Use the cruise up until the tachometer shows 8000rpm (mode 8).
- Press CANCEL or wait 1 second to enable the valet mode, the rev counter will show current RPM

Cautionary Note for Tuners

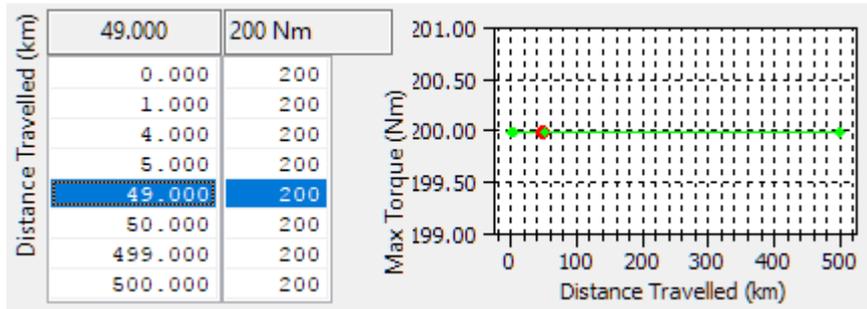
Please take note that Valet Mode activation is now a toggle and it's relatively easy to activate. Car owners can in some cases activate it accidentally and it's not been unknown for car owners to end up at a main dealer to have their "problem" fixed!

Valet Mode Enable

 Enable Valet Mode

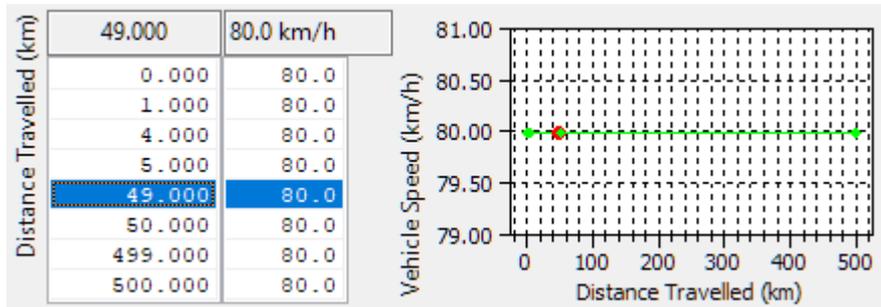
The "Enable Valet Mode" checkbox enables operation of the Valet Mode feature.

Valet Mode Torque Limiter



When Valet Mode is active the torque output can be limited to prevent a car being driven hard or recklessly. For use as an anti-theft measure it would be reasonable to reduce these values from the default 200Nm after a short distance.

Valet Mode Speed Limiter



When Valet Mode is active the maximum speed can be limited to prevent the car from being driven at anything beyond a sedate pace. For use as an anti-theft measure it would be normal to significantly reduce these default values to as low as zero after a shorter distance.

4. Glossary

AFM

Air Flow Meter

AFR

Air Fuel Ratio

Calculated Air Flow

The air flow sensor voltage is not linearly related to the amount of air flow. The ECU uses a scaling map to translate the air flow sensor voltage into an air flow rate value i.e. calculated air flow.

ECM

Engine Control Module

Engine Load

The ECU calculates engine load based on calculated air flow divided by engine RPM. It is effectively how much air enters the engine on each revolution.

FTST

Fuel Trim Short Term

FTLT

Fuel Trim Long Term

FMIC

Front Mounted Intercooler

MAF

Mass Air Flow (sensor)

MAP

Manifold Absolute Pressure (sensor)

MRP

Manifold Relative Pressure or boost pressure

MBT

Maximum Best Torque or Minimum Best Timing

O2 Sensor

Lambda Sensor (oxygen sensor)

RRLC

RaceROM Launch Control

RRBC

RaceROM Boost Control

RRFF

RaceROM Feature File (patch)

SD – Speed Density

The Mass Airflow in grams is calculated from MAP sensor not MAF sensors.

TCM

Transmission Control Unit or Gearbox ECU